



Update on ObsBox and Loss maps studies

Speaker: Loïc COYLE

Acknowledgements:

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D. Mirarchi, T. Persson

ObsBox

Quick recap

The ObsBox:

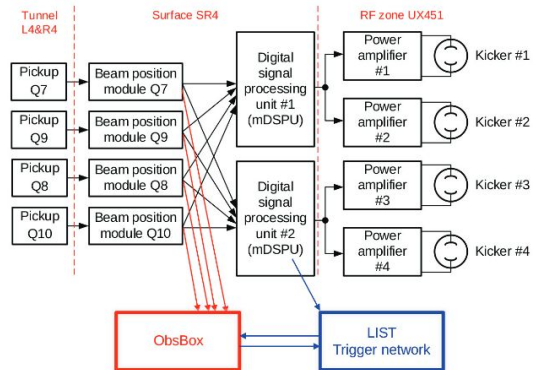


Figure 1: An overview of the LHC transverse feedback system (ADT).

- rolling buffer & saves on trigger
- 65536 turns
- bunch by bunch
- transverse position data

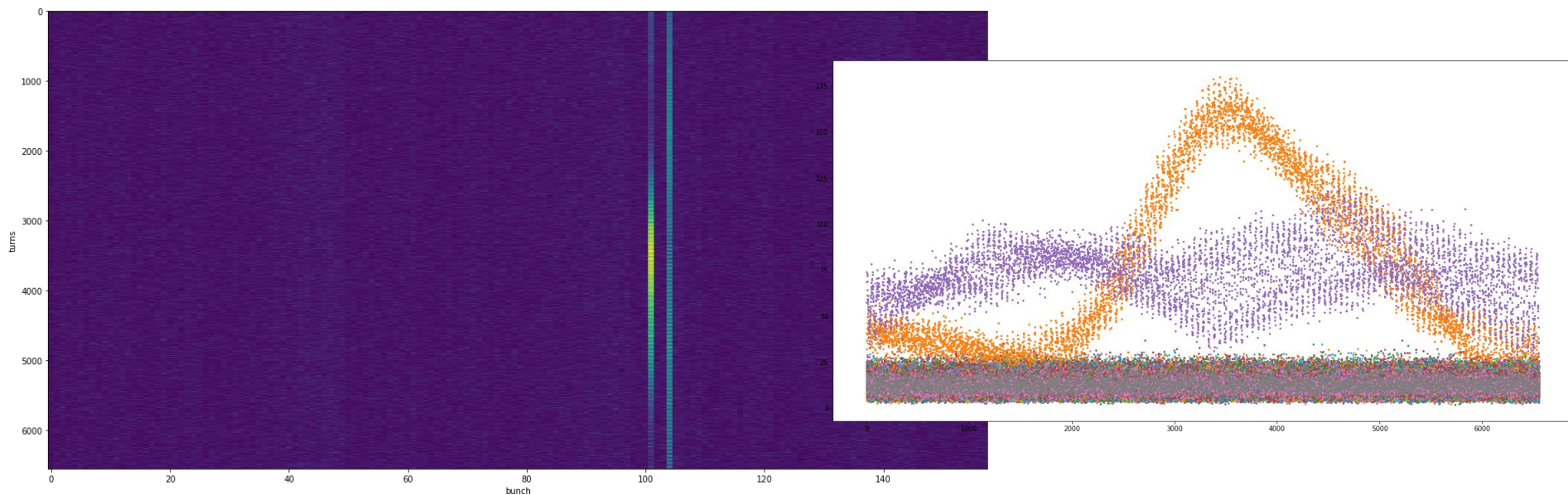
The problem:

- The trigger is not very accurate : Most of the data does not contain any instabilities.
→ instabilities make up less than 1% !
- Large amount of data ~4 TB
- Very little labeled data collected manually

ADTObsBox

Raw beam amplitude data at a turn by turn and bunch by bunch resolution. → multivariate time series

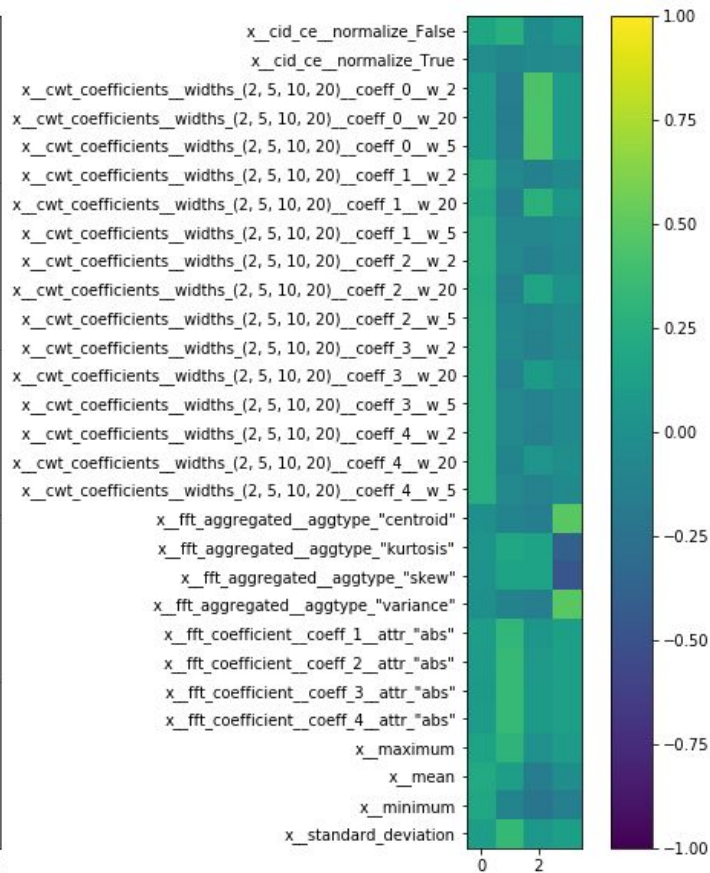
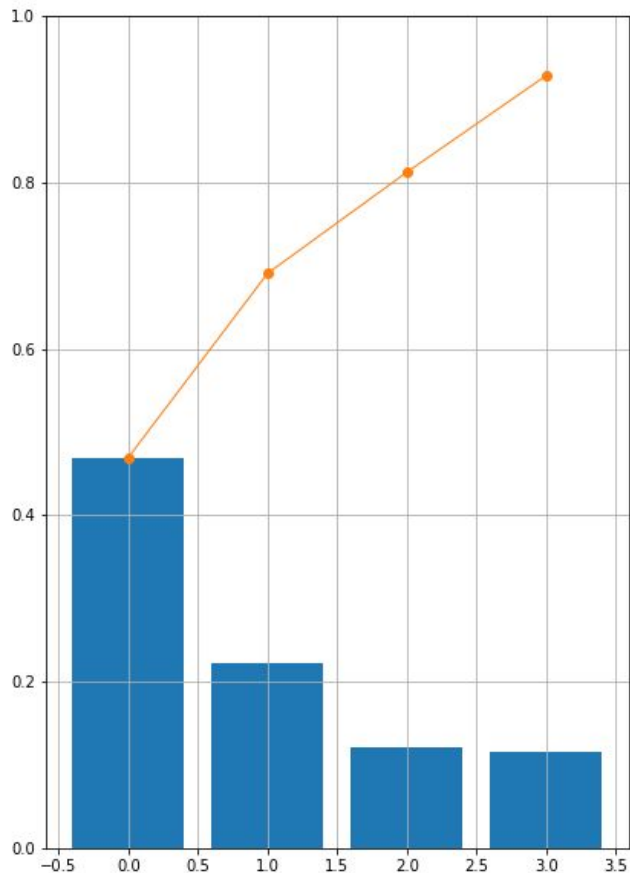
Example: 07169_Inst_B1V_Q7_20180914_08h53m08s → 2 unstable bunches



Principal Component Analysis

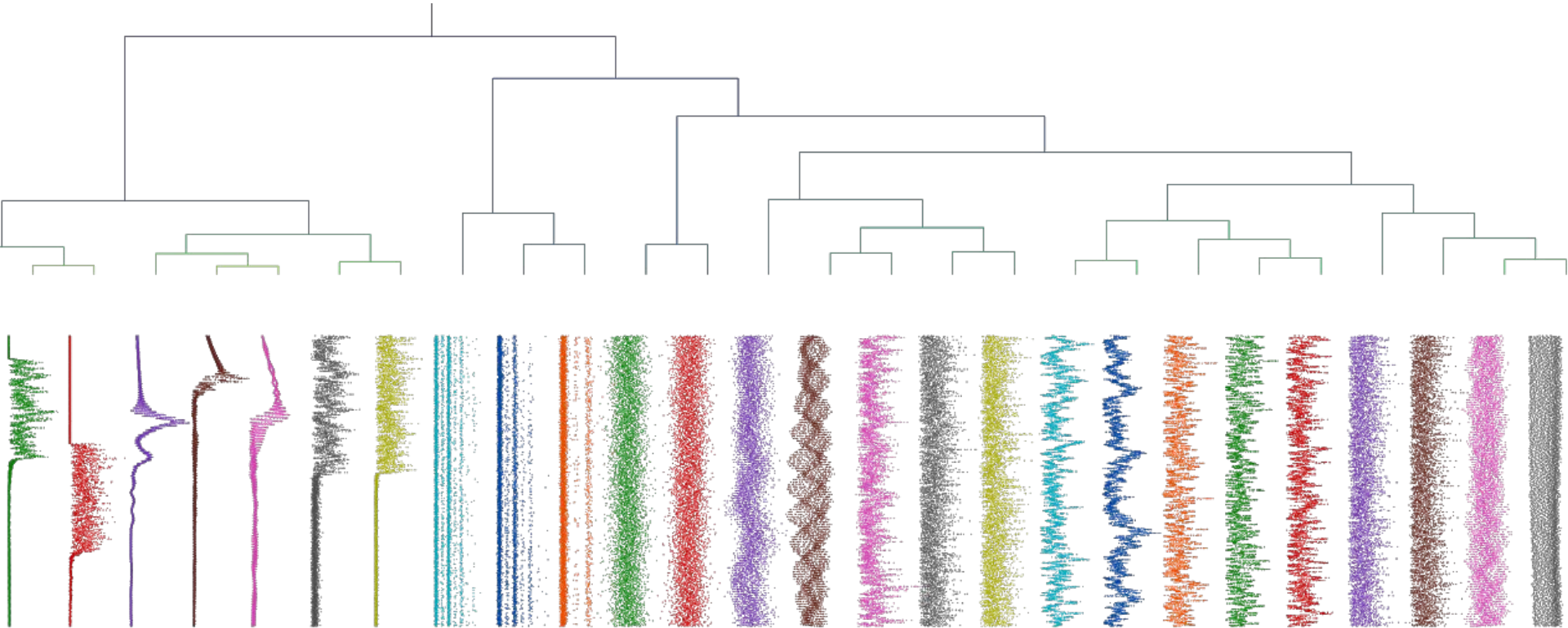
Quick recap

PCA vectors truncated to 4 components \rightarrow ~93% variance explained



Linkage Tree

Quick recap



Full plot: <https://cernbox.cern.ch/index.php/s/F6m2LQIVVBvCK79> or <https://imgur.com/a/jeDk8ts>

Conclusion

OBsBox:

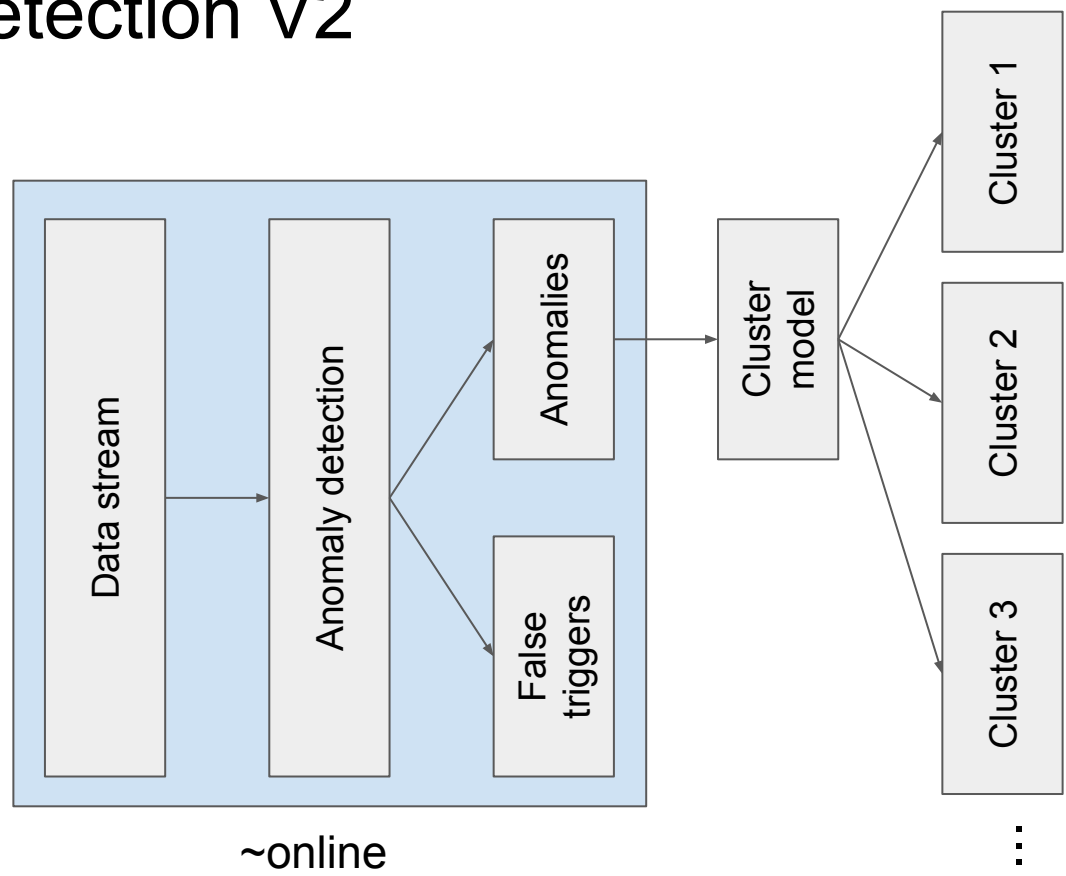
- Anomaly detection for instability detection ~working
 - Refine the extracted features
 - Isolation forest hyper parameters
- Some preliminary (univariate) time series clustering ~working
- Proof of concept seems to produce coherent results
- Improvement:
 - More features → extend to run on cluster ~nearly working
 - Look into multivariate (multi-bunch) time series clustering
- Look into online use

Conclusion

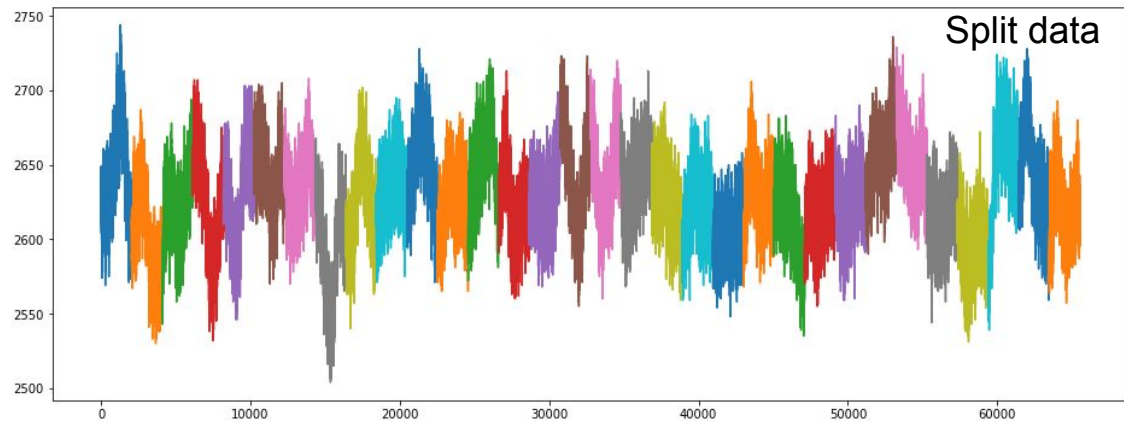
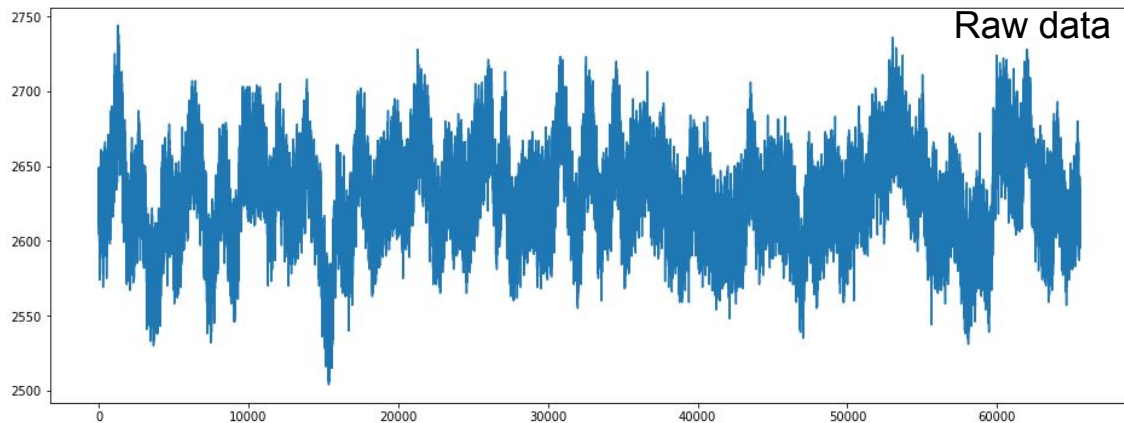
OBsBox:

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- Improvement:
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- **Look into online use**

Anomaly detection V2



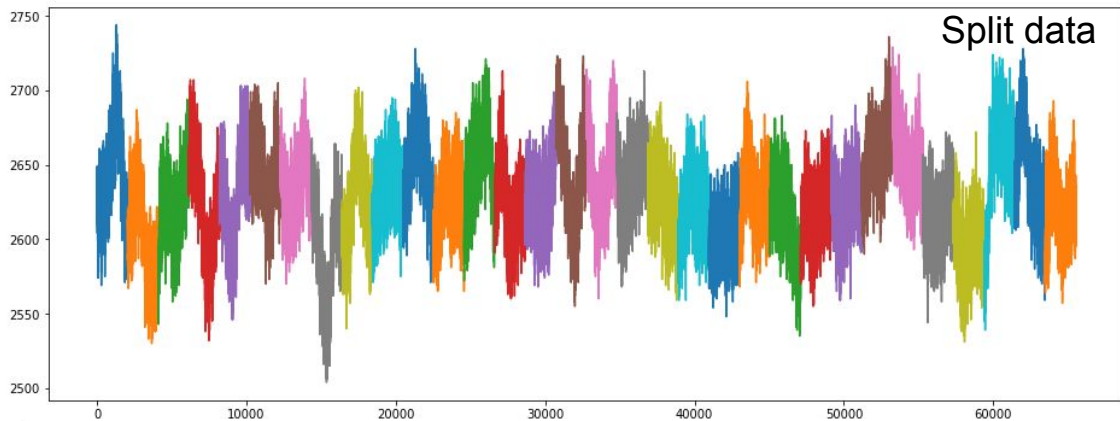
Anomaly detection V2 - Preprocessing



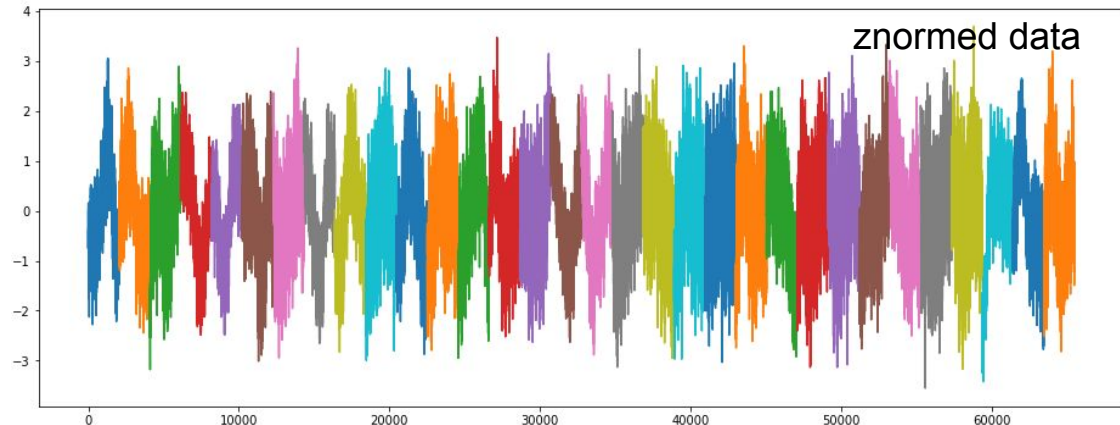
The 65536 turn buffer is split into 2048 smaller chunks.

Turn number

Anomaly detection V2 - Normalization



Each chunk is normalized

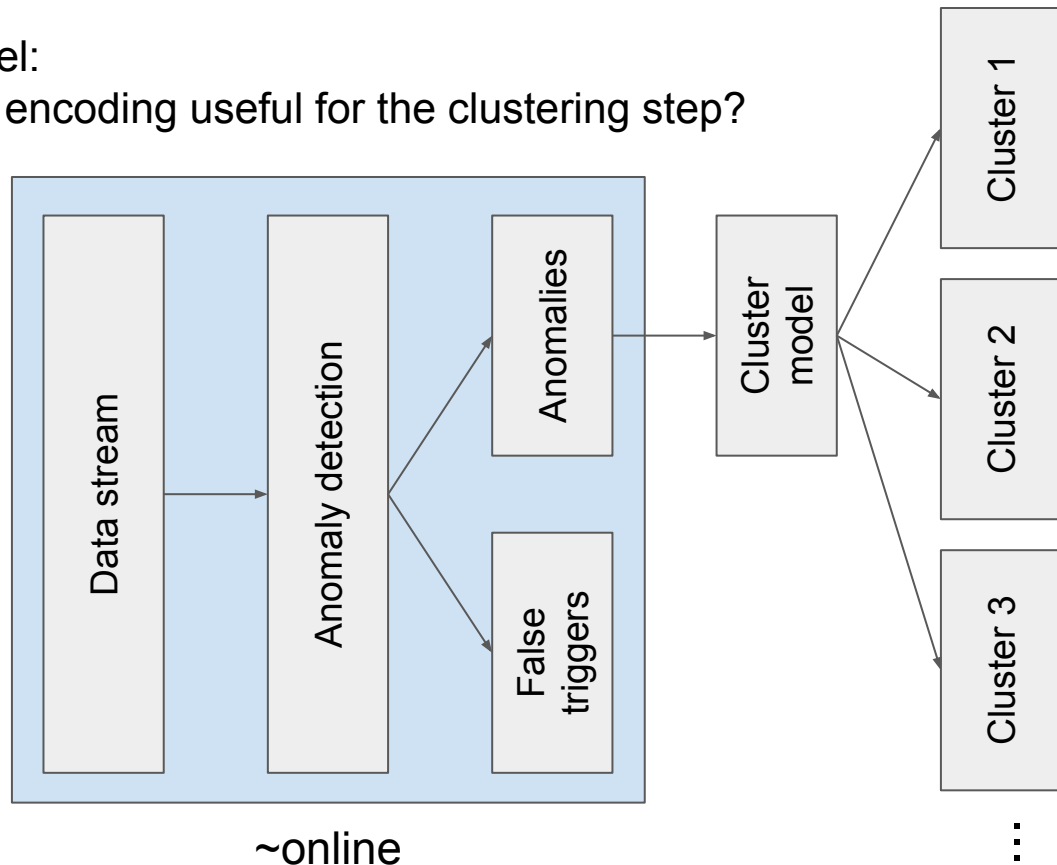


Turn number

Anomaly detection V2 - Model

Autoencoder based model:

→ Learns a latent space encoding useful for the clustering step?

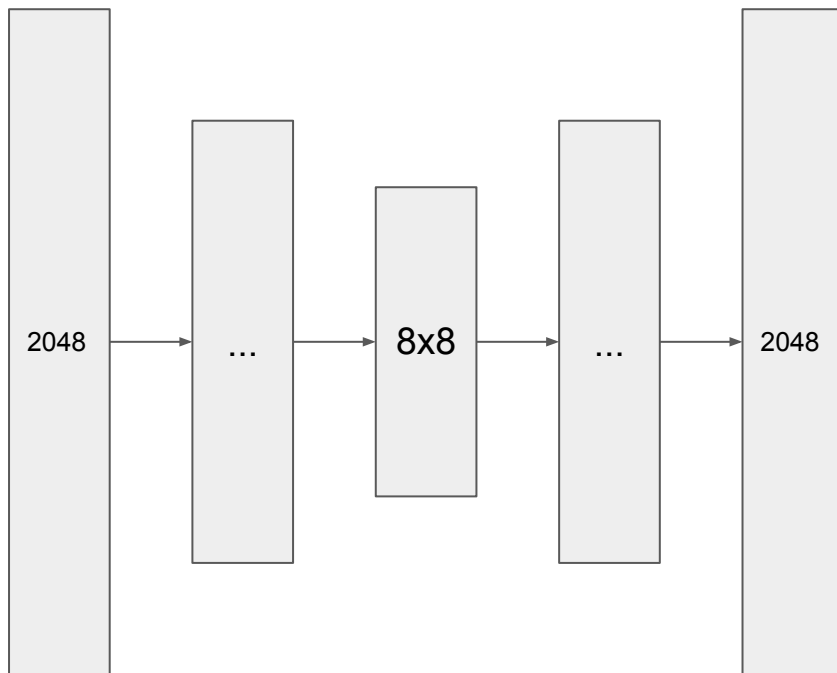


Anomaly detection V2 - Model

Autoencoder based model:

→ Convolutional autoencoder → image like representation in latent space

Reconstruct the input despite a bottle neck.

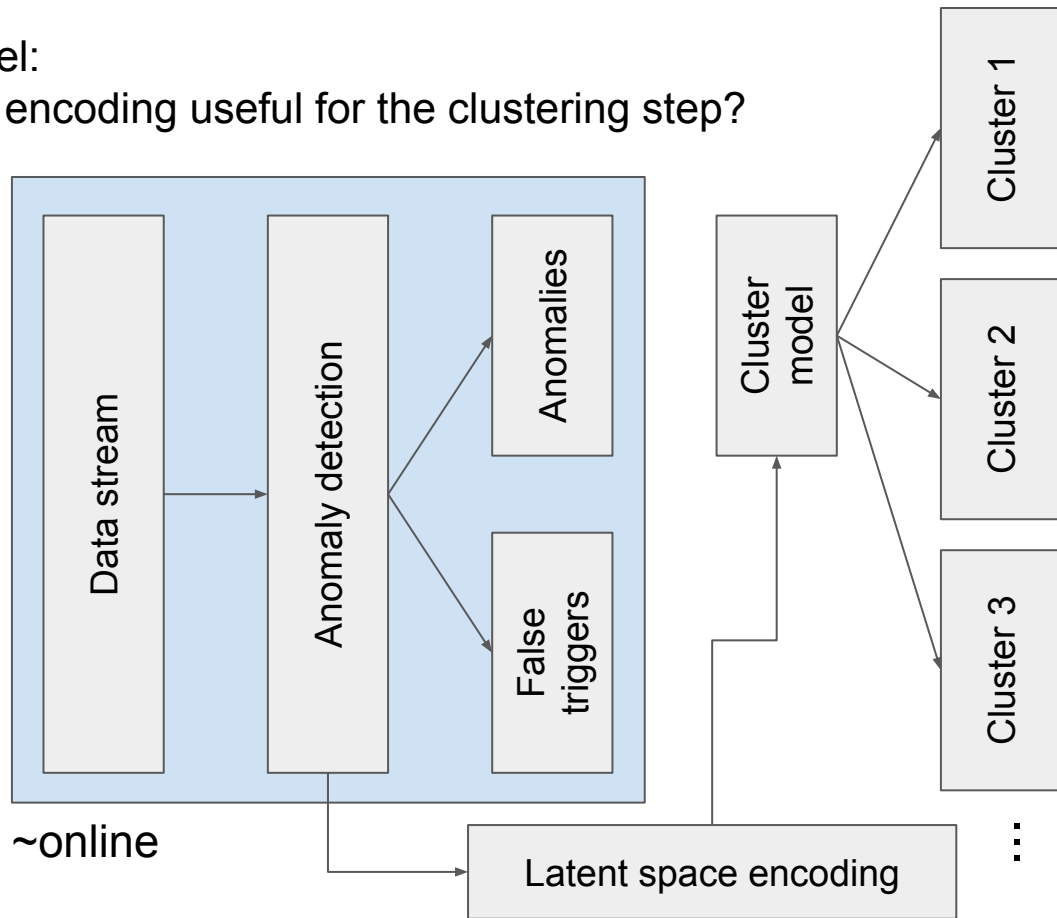


Layer (type)	Output Shape	Param #
conv1d (Conv1D)	(None, 512, 64)	512
dropout (Dropout)	(None, 512, 64)	0
conv1d_1 (Conv1D)	(None, 128, 32)	14368
dropout_1 (Dropout)	(None, 128, 32)	0
conv1d_2 (Conv1D)	(None, 32, 16)	3600
dropout_2 (Dropout)	(None, 32, 16)	0
conv1d_3 (Conv1D)	(None, 8, 8)	904
conv1d_transpose (Conv1DTran	(None, 32, 8)	456
dropout_3 (Dropout)	(None, 32, 8)	0
conv1d_transpose_1 (Conv1DTr	(None, 128, 16)	912
dropout_4 (Dropout)	(None, 128, 16)	0
conv1d_transpose_2 (Conv1DTr	(None, 512, 32)	3616
dropout_5 (Dropout)	(None, 512, 32)	0
conv1d_transpose_3 (Conv1DTr	(None, 2048, 64)	14400
conv1d_transpose_4 (Conv1DTr	(None, 2048, 1)	449
Total params: 39,217		
Trainable params: 39,217		
Non-trainable params: 0		

Anomaly detection V2 - Model

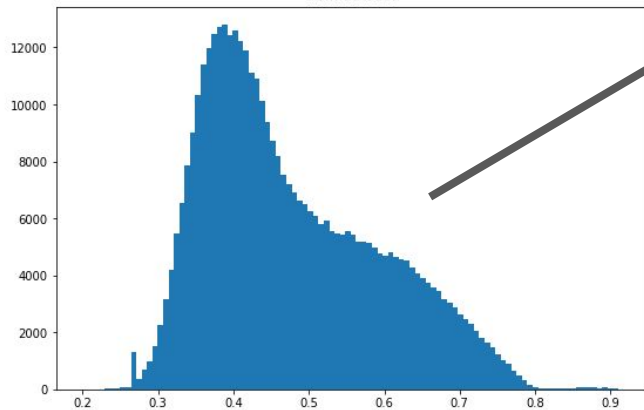
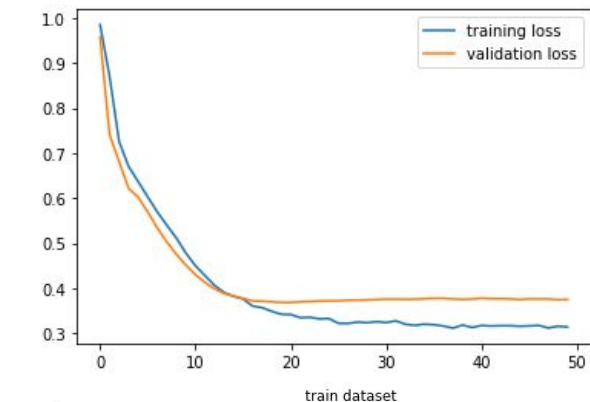
Autoencoder based model:

→ Learns a latent space encoding useful for the clustering step?



Anomaly detection V2 - Results

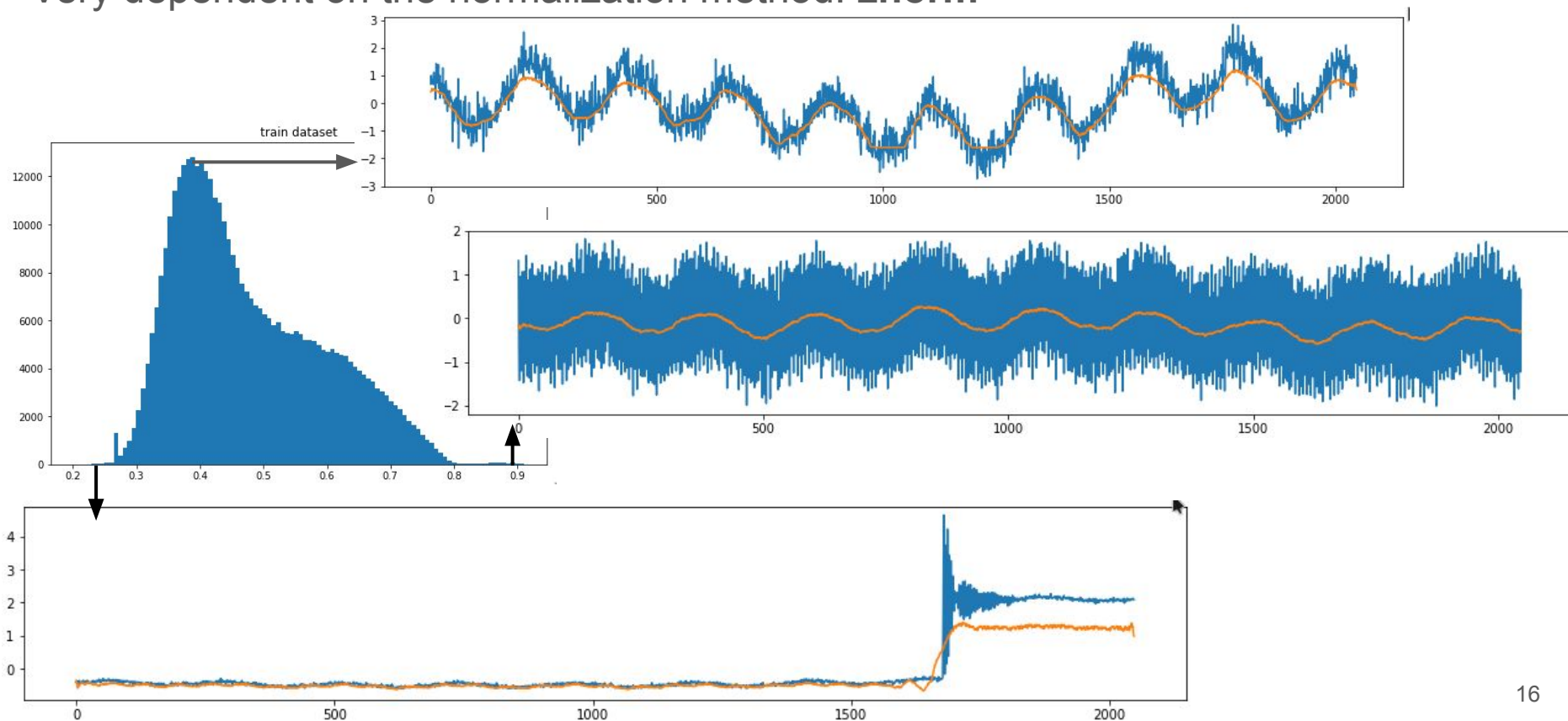
Very dependent on the normalization method: **znorm**



Distribution surprising, was expecting the most frequently occurring signals to have the lowest error.

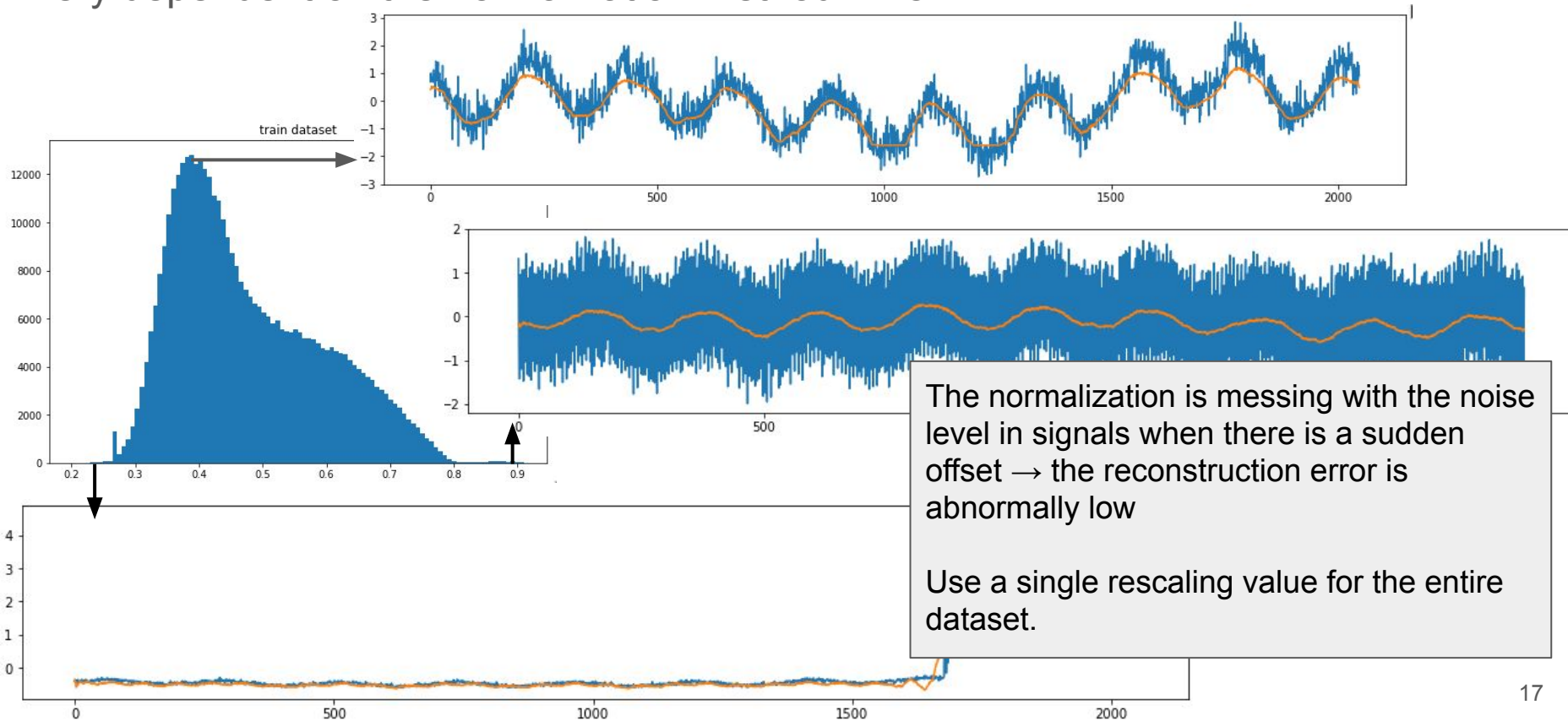
Anomaly detection V2 - Results

Very dependent on the normalization method: **znorm**



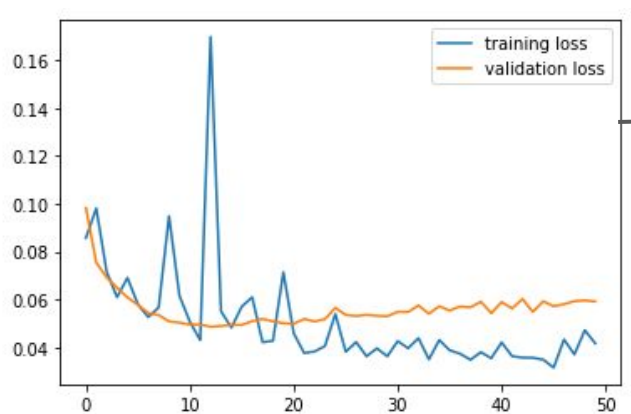
Anomaly detection V2 - Results

Very dependent on the normalization method: **znorm**

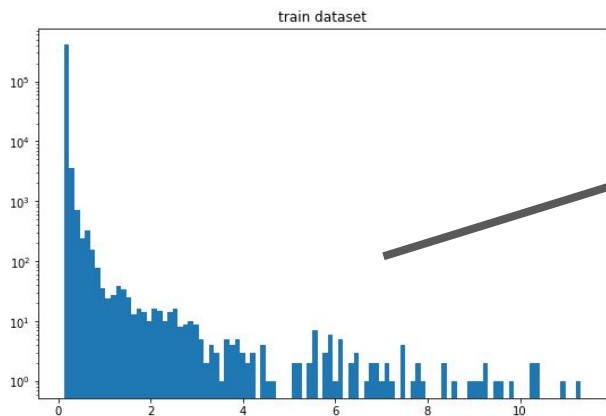


Anomaly detection V2 - Results

Alternative normalization: mean 0 constant normalization factor (**center scale**)



Losses is much more erratic, to be expected.

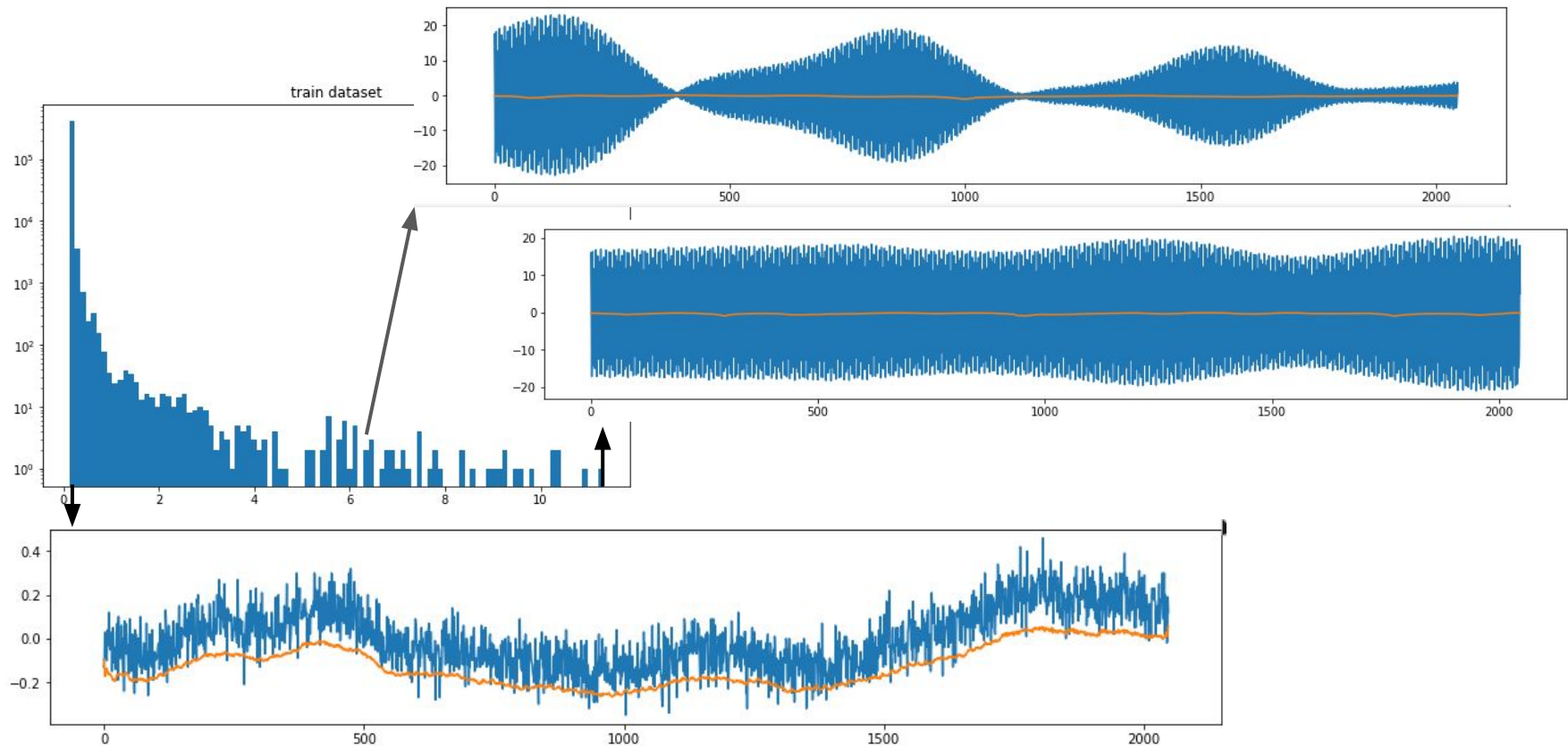


More like what I was expecting, lower errors occur more frequently.

Note the log scale.

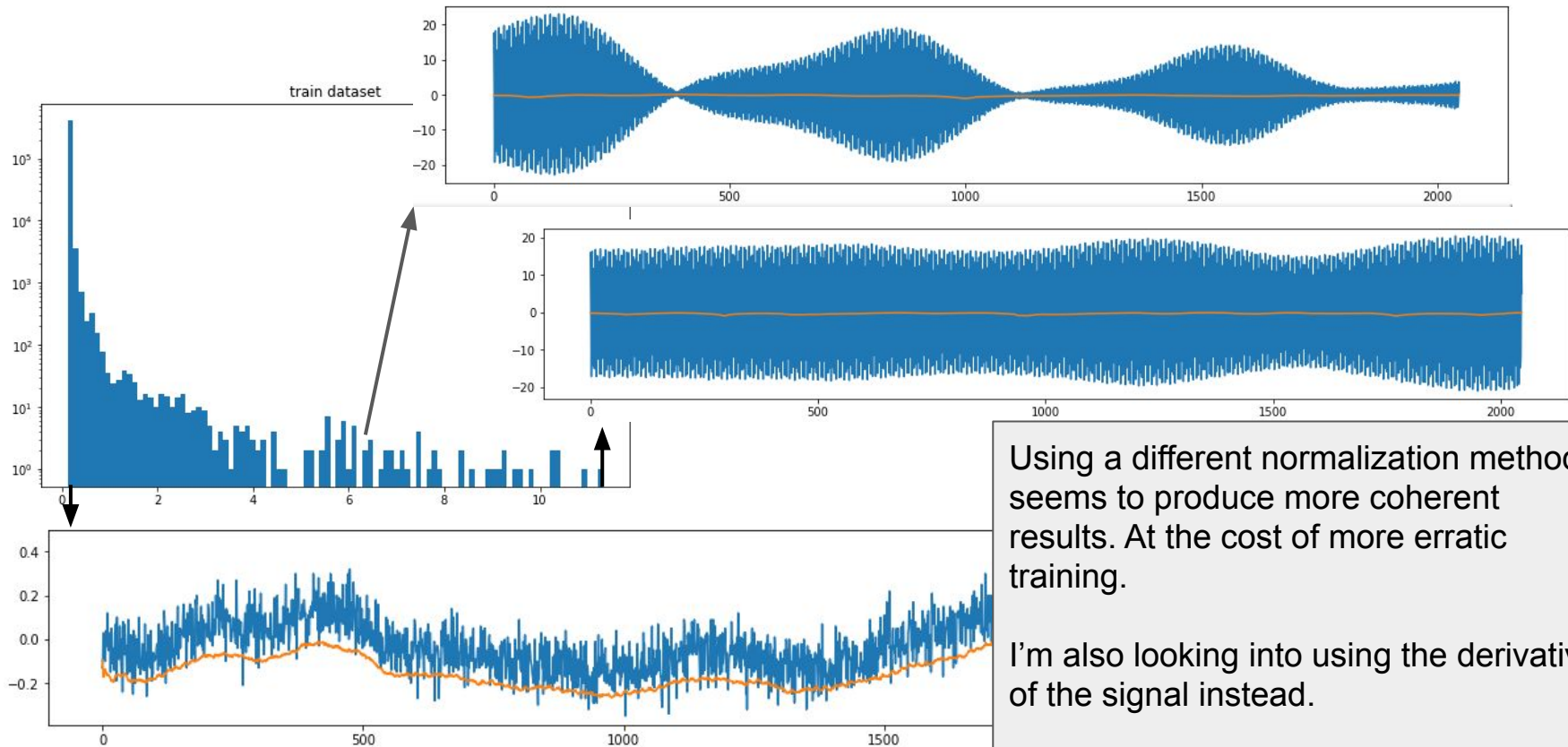
Anomaly detection V2 - Results

Very dependent on the normalization method: **center scale**



Anomaly detection V2 - Results

Very dependent on the normalization method: **center scale**



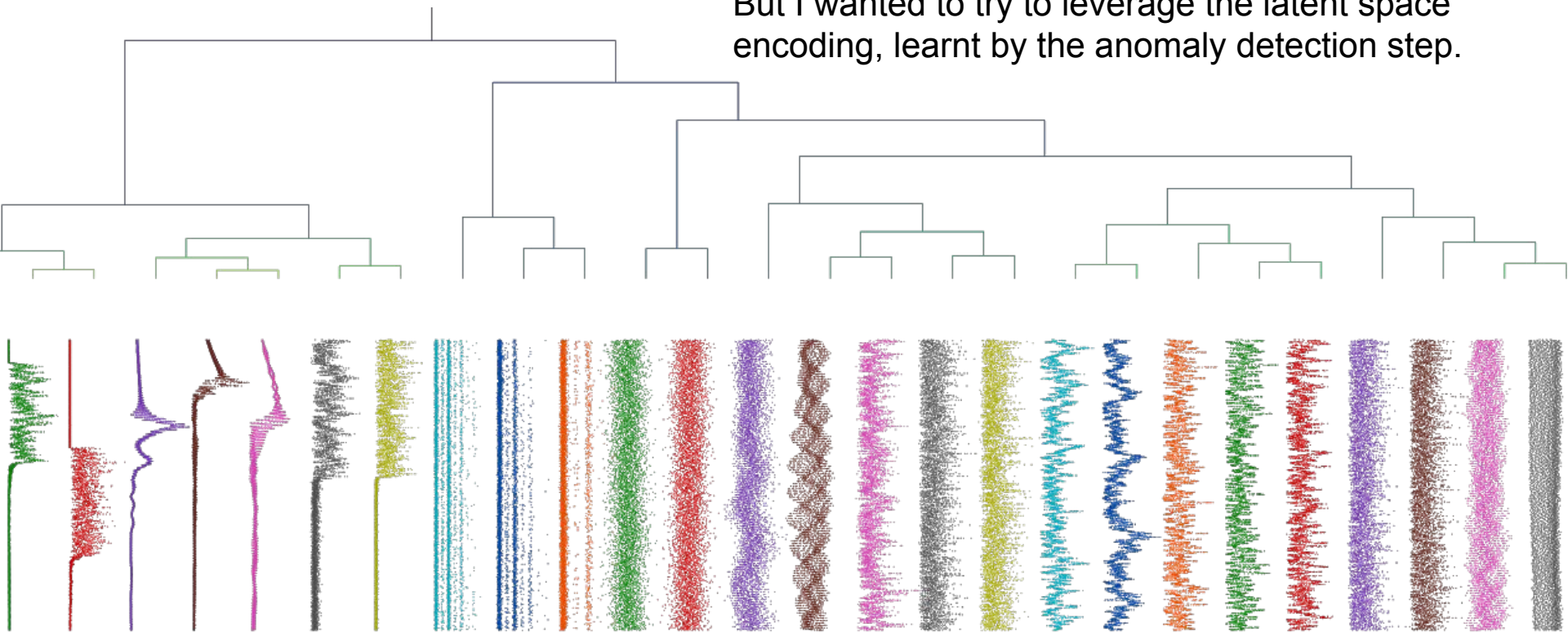
Using a different normalization method, seems to produce more coherent results. At the cost of more erratic training.

I'm also looking into using the derivative of the signal instead.

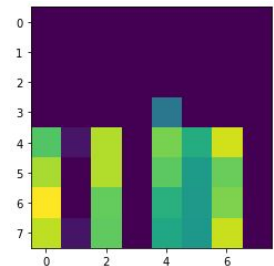
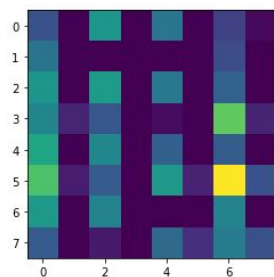
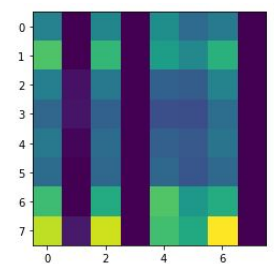
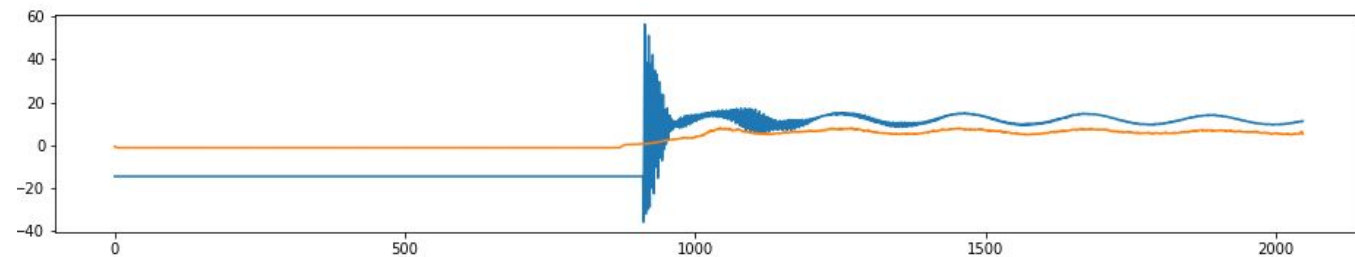
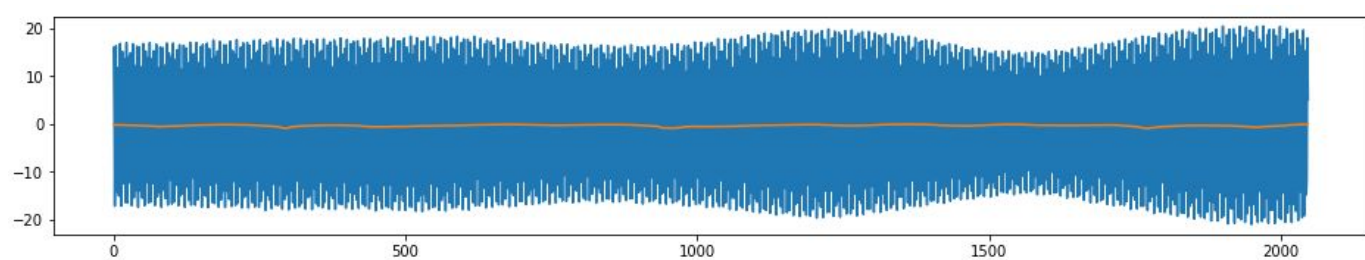
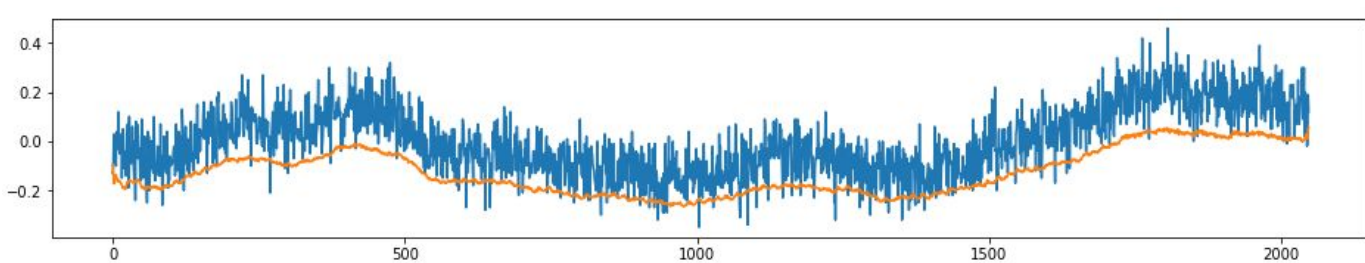
Clustering

We could use the same Hierarchical clustering (using DTW) method as previously.

But I wanted to try to leverage the latent space encoding, learnt by the anomaly detection step.



Clustering - Latent space



Clustering - Latent space

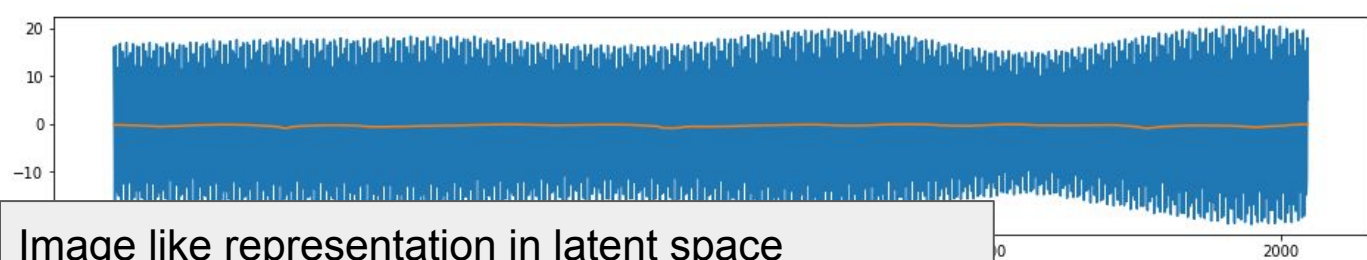
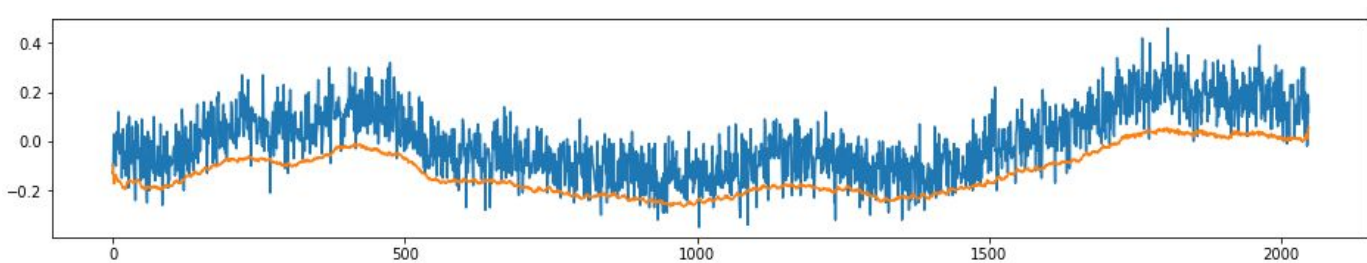
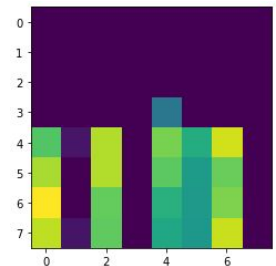
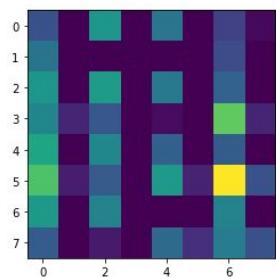
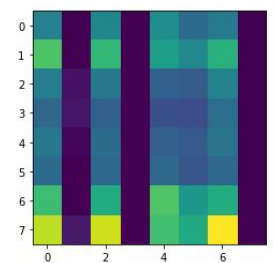
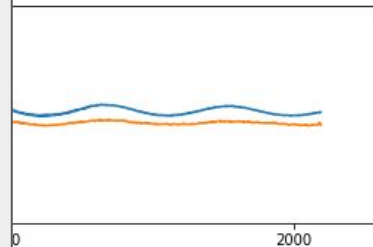


Image like representation in latent space
→ image clustering methods

Could also be very useful for multibunch
instabilities, stacking of the images

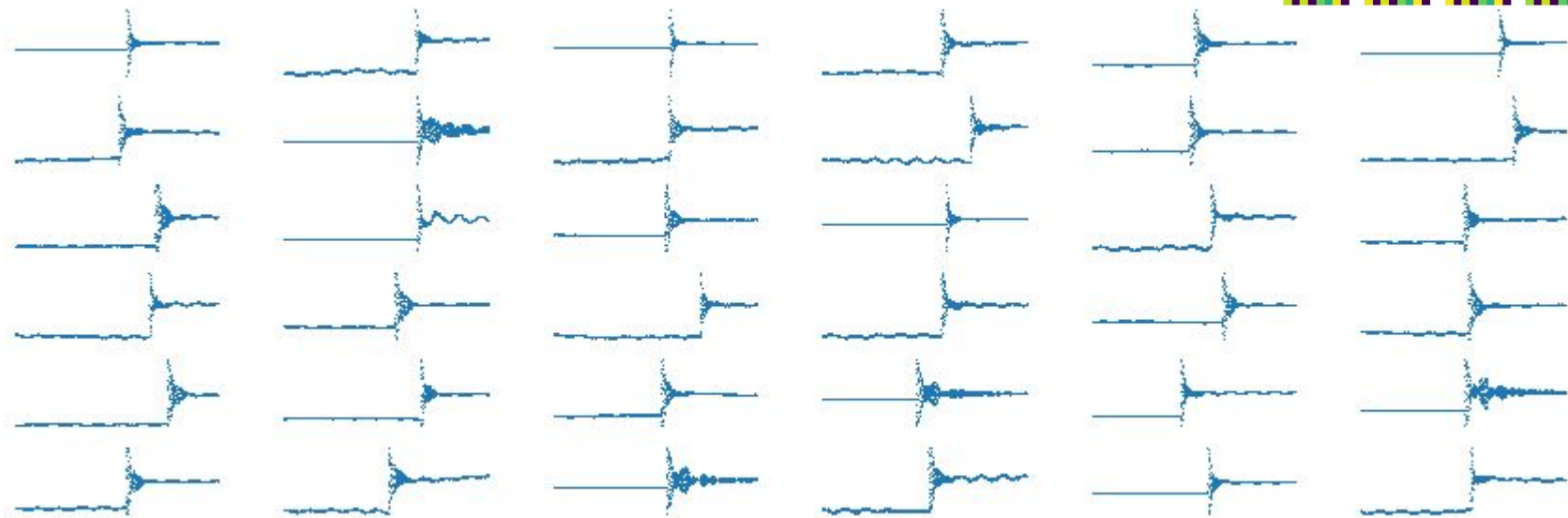
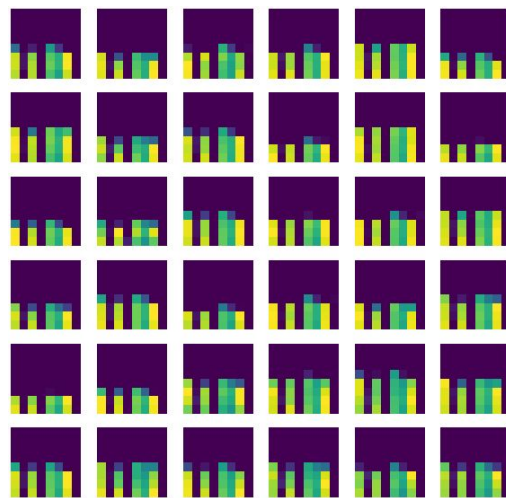
For now, standard K-Means to illustrate



Clustering - Latent space

KMeans on the top anomalous signals:

Probably injections, or orbit feedback turn on.



Clustering - Latent space



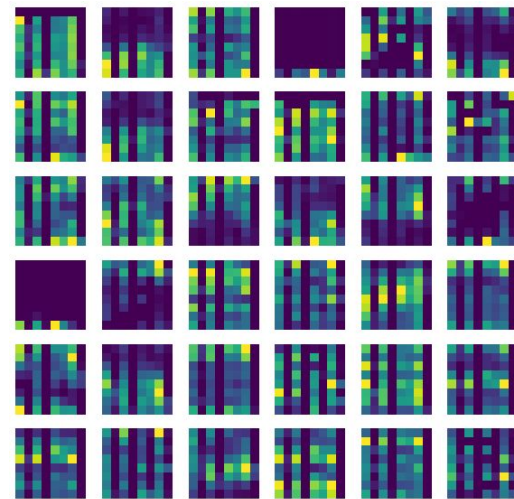
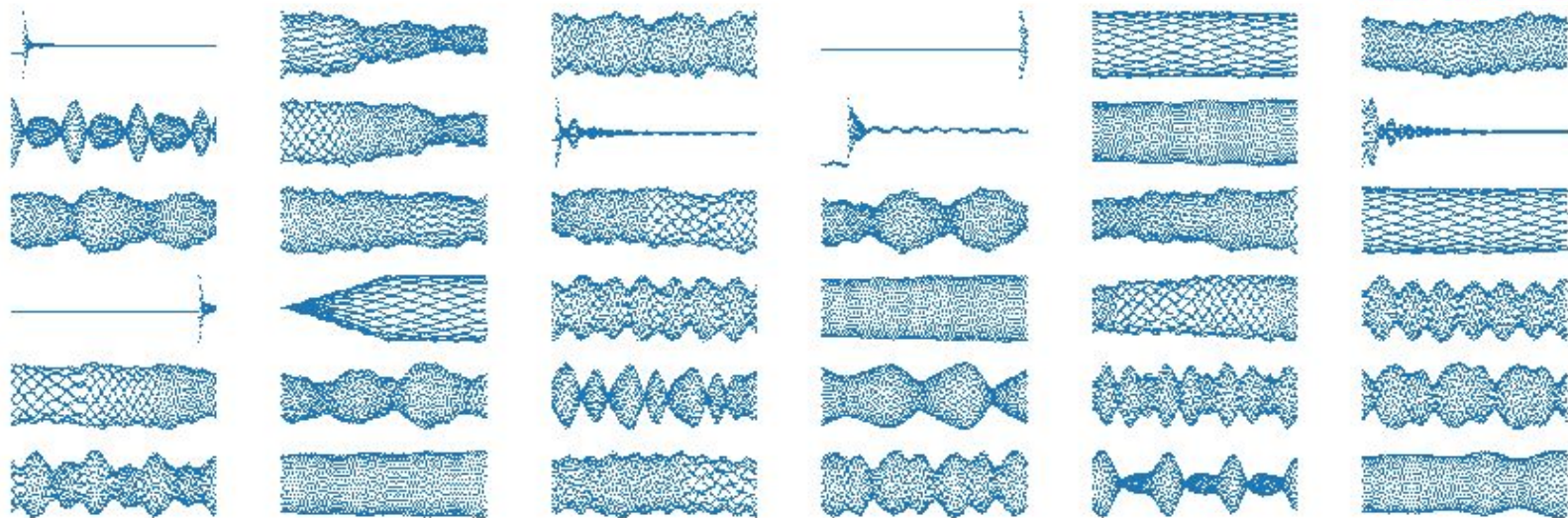
Probably beam dumps ?



Clustering - Latent space

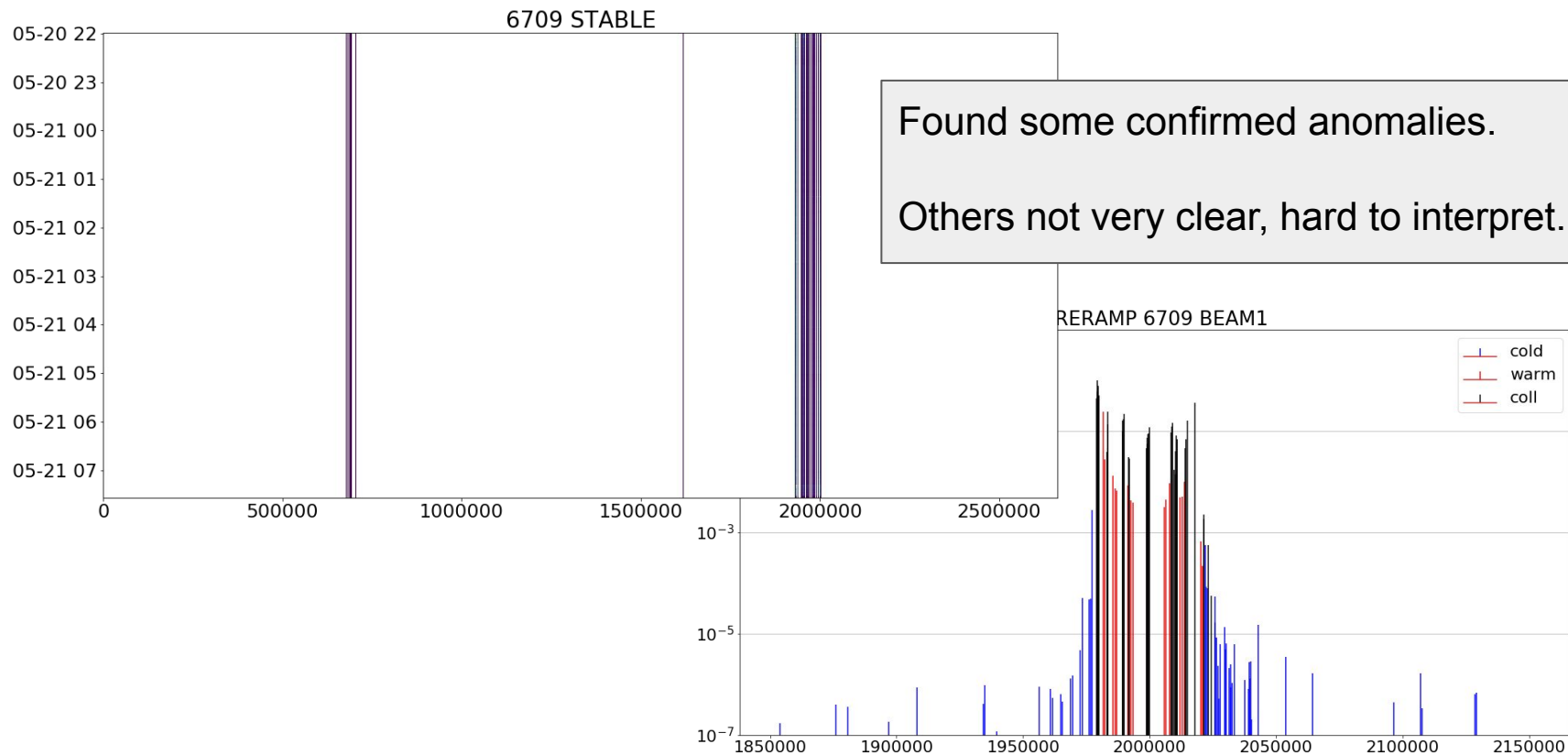
The interesting stuff, unfortunately, the different looking signals don't get clustered together.

But it is at least illustrative.



Loss maps

Loss map



Loss map

Tried many variations, no eureka moment.

Add cold region BLMs and cross check with known UFO events.

Ran into some technical problems (data storage issues), so it took a back seat to the ObsBox study.

Will pick it back up soon.

Conclusion

ObsBox:

- Online anomaly model
- Clustering with latent space encoding promising
- Figure out proper clustering model (instead of KMeans)
 - Hierarchical Clustering in latent space ?
 - Image based clustering methods ?
- Multibunch instabilities feasible