

Automation, performance optimisation & ML @ Elettra G. Gaio

www.elettra.eu



Outline

✓ Reinforcement Learning in a Free Electron Laser

✓ Toward an accelerator autopilot





Reinforcement Learning in FERMI FEL optimization

✓ Study goal:

Apply Reinforcement Learning to automatically overlap the seed laser with the electron beam optimizing the radiation intensity

✓ Seed Laser alignment system:

- 2 planar Tip-Tilt mirrors (TTs) paired with 2 piezo-motors (hor - ver)
- 2 screens based on Charged-Coupled Devices (CCDs)

✓ Final output:

Intensity acquired by I_0 monitor

laser source TT1 Screen/CCD1 Screen/CCD2 I_0 monitor modulator light e^- beam e^- beam e

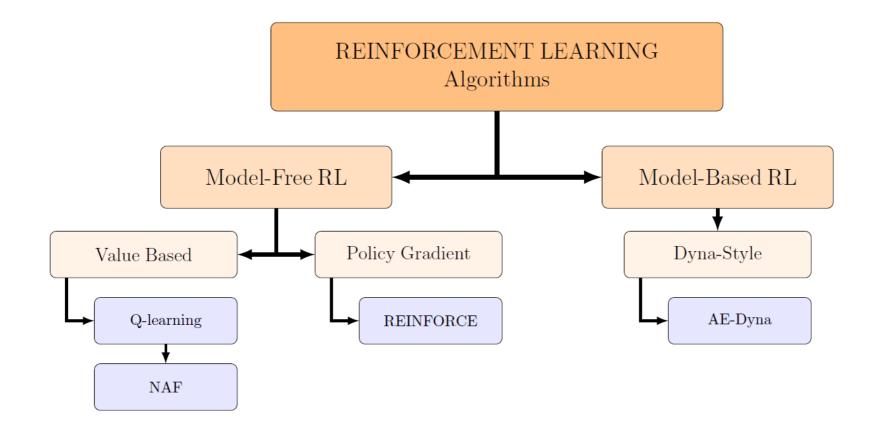
Optimization of 4 variables

Niky Bruchon, PhD of University of Trieste https://arts.units.it/retrieve/handle/11368/2982117/362563/PhD_Thesis_Final_NikyBruchon.pdf





Reinforcement Learning algorithms applied on FERMI



collaboration with CERN

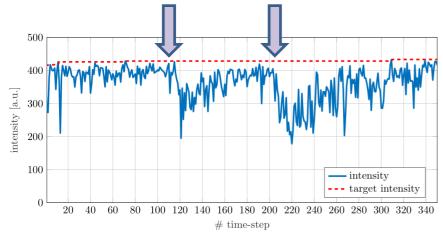
(V. Kain, S. Hirlander)





Reinforcement Learning results

Recover from manually imposed perturbation (NPG Reinforce)



Policy gradient methods for free-electron laser and terahertz source optimization and stabilization at the FERMI free-electron laser at Elettra F. H. O'Shea, N. Bruchon, G. Gaio – PRAB 2020

Attainment of the optimal working point starting from random initial conditions

	Algorithm	Training data points	Mean num. of steps	Normalized final intensity
	Q-learning	3128	11.28	-
	NAF	1074	2.56	1.0019
	NAF2	824	2.64	0.9995
	AE-Dyna (TRPO)	450	4.46	1.0150
_	AE-Dyna (SAC)	500	3.28	1.0427
Not RL –	GradAscent	1024	3.82	0.9911
	iLQR	1024	2.54	1.0019





- Decrease "virtually" to 0 the number of clicks on graphical panels in the control room
- ✓ Move human knowledge and logics inside GUIs to server side (TANGO devices)
- ✓ Develop an infrastructure that can scale easily with the complexity of the logics and allows a fast deployment of automatic optimization / feedback systems
- Machine physicists and operators should become the developers / mantainers of the logic of the infrastructure





Behavior Trees (BT)

- ✓ BT are used for in-game AI player opponents, UAV and robotics
- ✓ They are able to create very complex tasks composed by simple decoupled selfcontained tasks, regardless how they are implemented
- ✓ The tree-structure is composed by:
 - o a root node
 - o intermediate nodes (composite, selector, decorator) that control the flow
 - \circ leaf nodes
- ✓ In the control system:
 - Each leaf/node is a TANGO device that executes a specific task (leaf) or launch in series or parallel other tasks (intermediate/root node)
 - In-house basic scripting language to execute simple reading/setting of variables after receiving a Start command; it supports if/else statement;
 - Can execute Python, Matlab, bash scripts...
 - Native support of **retry** and **fallback** actions
 - It controls a programmable TANGO device server which implements feedback / numerical optimization schemes
 - At Elettra BT are known a SEQUENCERS

A framework for high level machine automation based on behavior tree - in submission to ICALEPCS2021

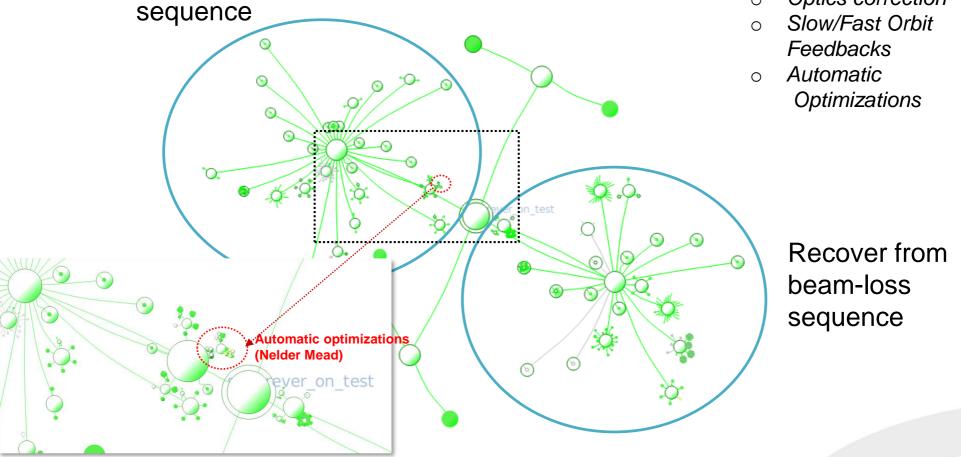




Elettra full automation



- Injection, beam to users \checkmark
- It manages: \checkmark
 - HW devices 0
 - **Optics correction** 0
 - Slow/Fast Orbit Feedbacks





Injection- beam to user



Sequencers monitoring

Qt-based dynamic panel explores and monitors the execution of sequences (web interface available)

r List seq/o	n/sr_forever_on_test							 Start Stop Clear 		L
View No	de View seq/on/sr_forever_on_test									seq/on/sr_forever_or
ce		State	Enable	Block	Executed	Last Exec	Elapsed	Description		
ea/on/sr fo	rever on test	OFF				unavailable	1053	TEST PURPOSE ONLY infinite loop recover		
 seg/on/la 	unch automatic sr recover test	ÎOFF	-i			unavailable	0	FULL automatic SR Recover after DB		
	nonitor/sleep until bd test	OFF	V	YES	E YES E	-	102	TEST PURPOSE ONLY Wait Beam Dump		
seq/recover/beamdump s		OFF	v	YES	E NO E	3d 22h 29m	ÎO	Recover SR after BD		
seq/on/gun injection test		OFF	V	YES	E YES E	4d 3h 39m	1	TEST PURPOSE ONLY Switch ON GUN, set Vgrid	d, Enable KISR&SISR and inject in SR	
▼ (seq/or	n/injection 2.4gev	IOFF	\checkmark	YES		2d 2h 40m	[511	Injection @2.4Gev operations		
	q/check/gof status not on	OFF	\checkmark	YES		2d 2h 49m	<u>lo</u>	Check if GOF status is not ON		
	q/on/gof_buffers	OFF	✓	YES		2d 2h 49m	3	Switch GOF buffers ON		
	q/on/fillpat	OFF	✓	YES		2d 2h 49m	0	Put ON and unpause Fillpat if needed		
	q/on/Imbf s	OFF	✓	NO		2d 2h 49m	lo	Put ON LMBF		
	q/check/tmbf h	OFF	_ v	YES		2d 2h 42m	10	Check Transverse multibunch feedback		
	q/check/tmbf v	OFF	Y	YES		2d 2h 42m	10	Check Transverse multibunch feedback		
	q/on/fast tunefb s	OFF	¥	NO		2d 2h 49m	1	Switch ON Fast Tune Feedback		
	q/check/3hc freq 2.4gev	OFF		YES	YES	-	0	Check if 3HC freqencies are ok for 2.4Gev	h	
	q/opt/launch opt booster injection	OFF OFF	V V	YES	E NO E	unavailable	298	Optimize BOOSTER current and SR injection rat		
	seq/on/current optimizer b minimal operations	OFF				2d 2h 58m 2d 2h 58m	1298	Optimize BOOSTER current during manual injection	cuon (no Topue)	
	(seq/check/opt thresold injection 1 s (seq/opt/launch ch cv bts	OFF	- ·	YES	E YES	20 211 3811	110	BTS CH CV injection efficiency optimization (rol	llback avaliable)	
	(seq/check/opt thresold injection 2 s	OFF	- `	YES	E NO	- unavailable	10	Check current thresold during injection	.iDduk availdDie)	
	(seq/opt/launch ki si sr	OFF		YES		4d 0h 58m		[KISR/SISR injection efficiency optimization (roll	(back avaliable)	
	g/check/120ma injection s	OFF	- ÷	YES		2d 2h 46m	172	Wait to reach 120mA SR. 15 minutes timeout a		& check 2HC VGan <200K
	g/on/fast meanfb s	OFF	Ĵ	NO		2d 2h 46m	2	Switch ON Fast Mean Feedback	a reset blodebi in hisk off 55 and 511 c	x check sine voap <200k
	g/check/158ma injection s	OFF	- ÷	YES		2d 2h 45m	159	Wait to reach 158mA SR. 15 minutes timeout	& reset DiodeBPM risk on S5 and S11 /	& check 3HC VGan <200K
	g/off/injection s	OFF	- ÷	YES	E YES E	-	10	Stop Injection (kisr, sisr, gun grid at 0V)		veneek one roup -zeek
	g/on/global orbit fb	OFF	- ÷	YES	E NO E	2d 2h 55m	159	Switch ON Slow Global Orbit Feedback		
	g/restore/scw id5 diodebpm risk	IOFF	V	YES		2d 2h 42m	10	Reset DiodeBPM risk on S5 and S11		
	g/on/local orbit fb	OFF	V	YES		2d 2h 42m	146	Switch ON Local Orbit Feedback		
Ise	g/restore/scw_id5_diodebpm_risk	ÎOFF	$\overline{\mathbf{v}}$	YES	E YES E	2d 2h 42m	0	Reset DiodeBPM risk on S5 and S11		
Ise	g/check/orbit guality s	OFF	v	YES	E YES E	2d 2h 42m	1	Check Orbit Quality		
Ise	g/on/gof	OFF	\checkmark	YES	E YES E	2d 2h 42m	4	Switch ON GOF		
In the set of the	q/close/launch id s	OFF	\checkmark	YES	E YES E	2d 2h 41m	51	Close ID launcher with retry		
	q/init/topup 2.4gev	OFF	✓	YES		2d 2h 41m	(8	Init TopUp with 2.4Gev Parameters		
	q/restore/gof discharge dacs	OFF	V	NO		2d 2h 41m	[6	Discharge GOF DACS & wait 10 sec		
	q/restore/topup_longtermrisk	OFF	\checkmark	YES		2d 2h 41m	0	Restore TopUp long term risk		
	q/on/topup	OFF	_ v	YES		J2d 2h 41m	1	Put ON TopUp		
	q/on/sdo_2.4gev	OFF	✓	NO		2d 2h 41m	0	Put ON SDO for 2.4 GeV		
	q/on/bd_monitor_s	OFF	V	NO		2d 2h 41m	0	ON Beam Dump Monitor		
k leo	alrectorolccu, quonch protoctor c	INCL		INCO	sivec s	-116 Jb 41m		Postoro SCW Quench Protector		
n/sr_fore	ver_on_test	Filter ou	ut events old	der than	36000000s	\$		Filter:	Clear Filter	Operation History
Time	Sequencer	Message								
	14:56:29 2021 seq/opt/launch_opt_booster_injectio									
	2:21:09 2021 seq/enable/id_s					//id/id_s7/enabled,1		(accept interference)		
	2:21:05 2021 seq/on/injection_2.4gev					e' command_ino	ut(seq/enable)	launch_ld_s/start)		
	2:21:03 2021 seq/on/sdo_2.4gev					edback/sdo/on) :e(sr/id/id_s3/enable	(0 be			
	2:20:32 2021 seq/move/id_s3 2:20:26 2021 seq/move/id_s8					e(sr/id/id_s3/enable e(sr/id/id_s8.2/enable				
	2:20:26 2021 seq/move/id_s8 2:19:49 2021 seq/move/id_s10.2					ute(sr/id/id_s8.2/enat ute(sr/id/id_s10.2/g				
	2:19:49 2021 seq/move/id_s10.2 2:19:49 2021 seq/move/id_s9.1					te(sr/id/id_s10.2/g				
	2:19:49 2021 seq/move/id_s9.1 2:19:48 2021 seq/move/id_s1.1					te(sr/id/id_s9.1/gap				
	2:19:48 2021 seq/move/id_s1.1 2:19:48 2021 seq/move/id_s3.3					te(sr/id/id_s3/gap3,				
	2:19:47 2021 seq/move/id_s5.5					te(sr/id/id_s6/gap3,				

- ✓ Next steps:
 - Integration of *scikit-learn* and *OpenAI Gym* (optimizers)
 - o Analyze drifts in the execution time to detect anomalies
 - Add BT learning capabilities to achieve more flexibility





Thank you!

N. Bruchon, P. Cinquegrana, G. Gaio, S. Krecic, G. Scalamera, G. Strangolino, F. Tripaldi, M. Trovo', L. Zambon



LEAPS Integrated Platform Workshop

Giulio Gaio, 11/05/2021

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