

# Accurate & Confident Prediction of Electron Beam Longitudinal Properties using Spectral Virtual Diagnostics

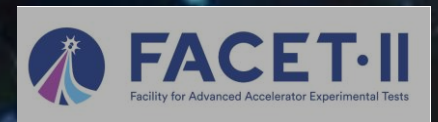
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May 12<sup>th</sup> 2021

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 [@AccAdkoo](https://twitter.com/AccAdkoo)

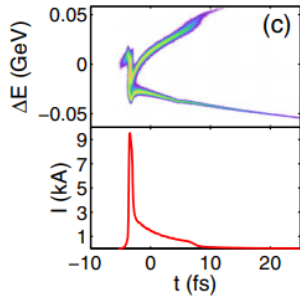


# Outline

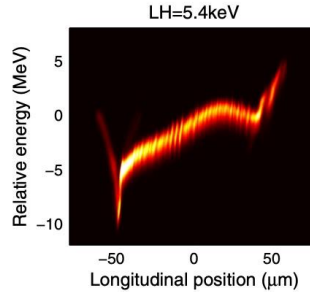
1. ML-based virtual diagnostics (VD) – Motivation & Background.
2. Spectral virtual diagnostic – 3 case studies:
  - a. Improved accuracy over scalar VD (*LCLS*)
  - b. Shot-to-shot prediction of fine features (*LCLS-II*)
  - c. Going beyond current diagnostic resolution (*FACET-II*)
3. Incorporating uncertainties - know what we don't know.
4. Summary

# Motivation

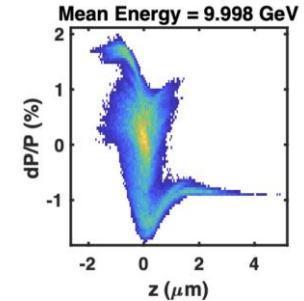
Accurate characterization of beams is required to successfully meet experimental goals.



Huang et al, PRL 119, 154801 2017

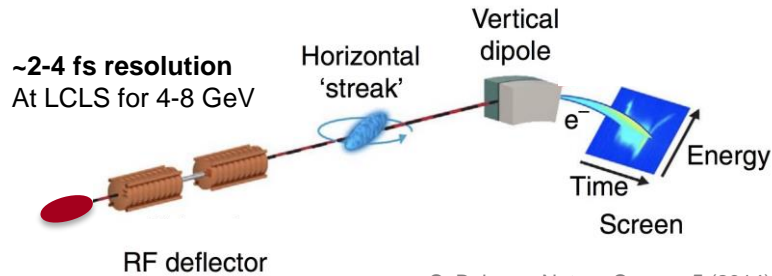


Ratner et al., PRSTAB 18, 030704 (2015)

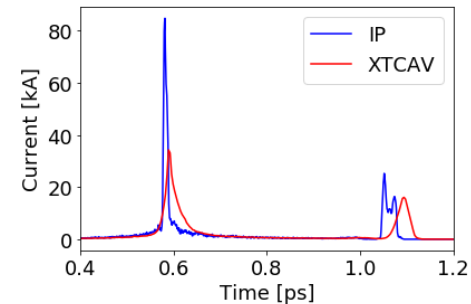


G. White, HEP ABP Workshop #1 2019

Current diagnostic methods for measuring LPS are **destructive** or have **insufficient** resolution.



C. Behrens Nature Comms 5 (2014)

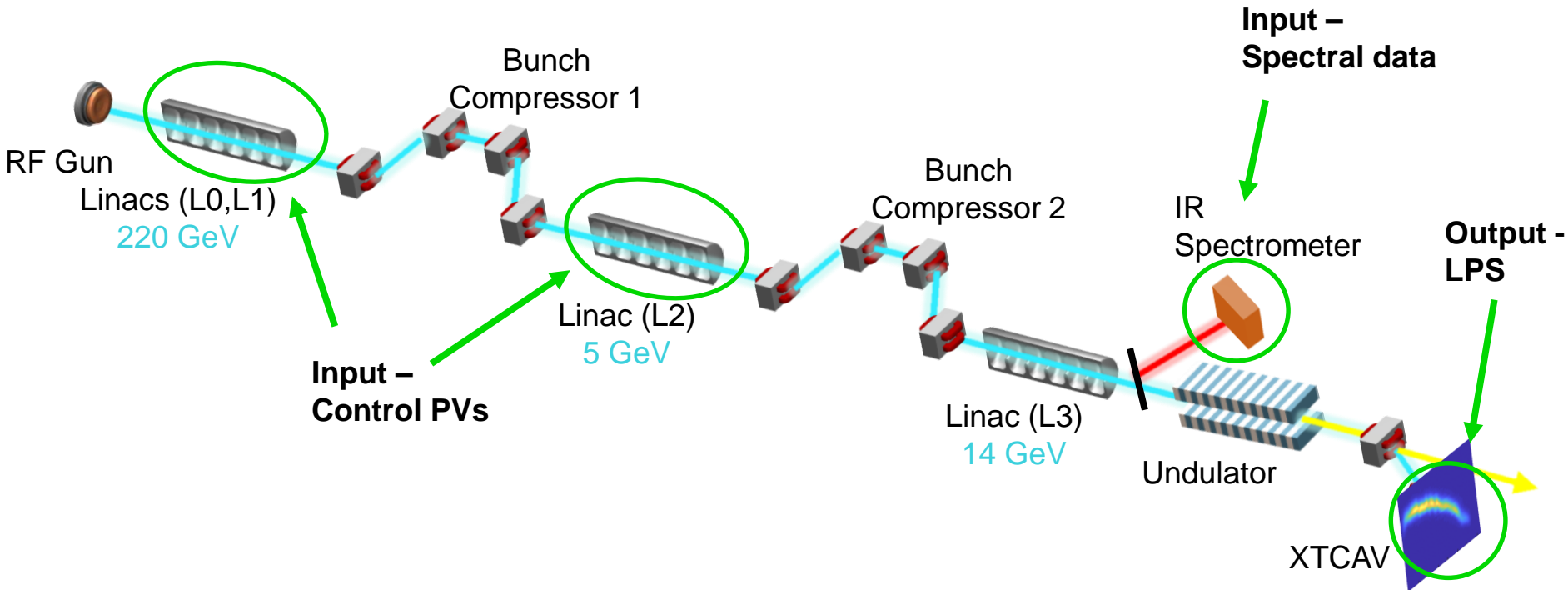


G. White, HEP ABP Workshop #1 2019

Machine learning based diagnostics can predict the beam properties on **shot-to-shot** basis **non-destructively** during transport and delivery to experiments.

# ML-based Virtual Diagnostics

Goal: Get otherwise unavailable (single-shot) information about the beam non-destructively to improve machine characterization, optimization, and data analysis.



- Once trained, fast to execute!
- Train on measured data and/or (slow) high fidelity simulations.

# Background: Scalars Virtual Diagnostics (VD)

Measured machine inputs (non-destructive)

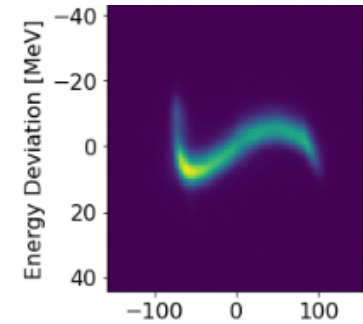
Control PVs (scalars)

Linac phase / amp

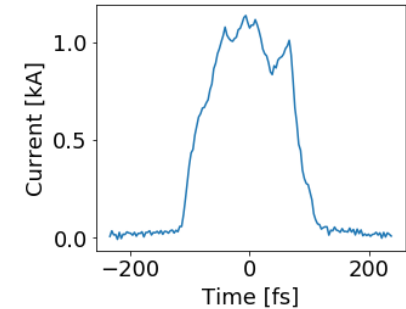


Scalars  
Virtual  
Diagnostic

LPS 2D images

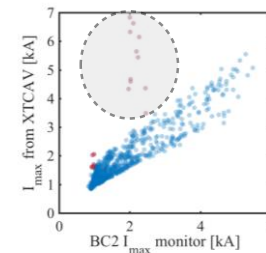


1D Current profile



## Limitations of Scalar VD:

1. Readback scalars are wrong → **GIGO!**
2. Readback scalars are integrated signals → **cannot predict** shot-to-shot fluctuation effects like microbunching.
3. Bad predictions can result from large **discrepancy** between diagnostic input (e.g. BC2 current) and XTCAV current.



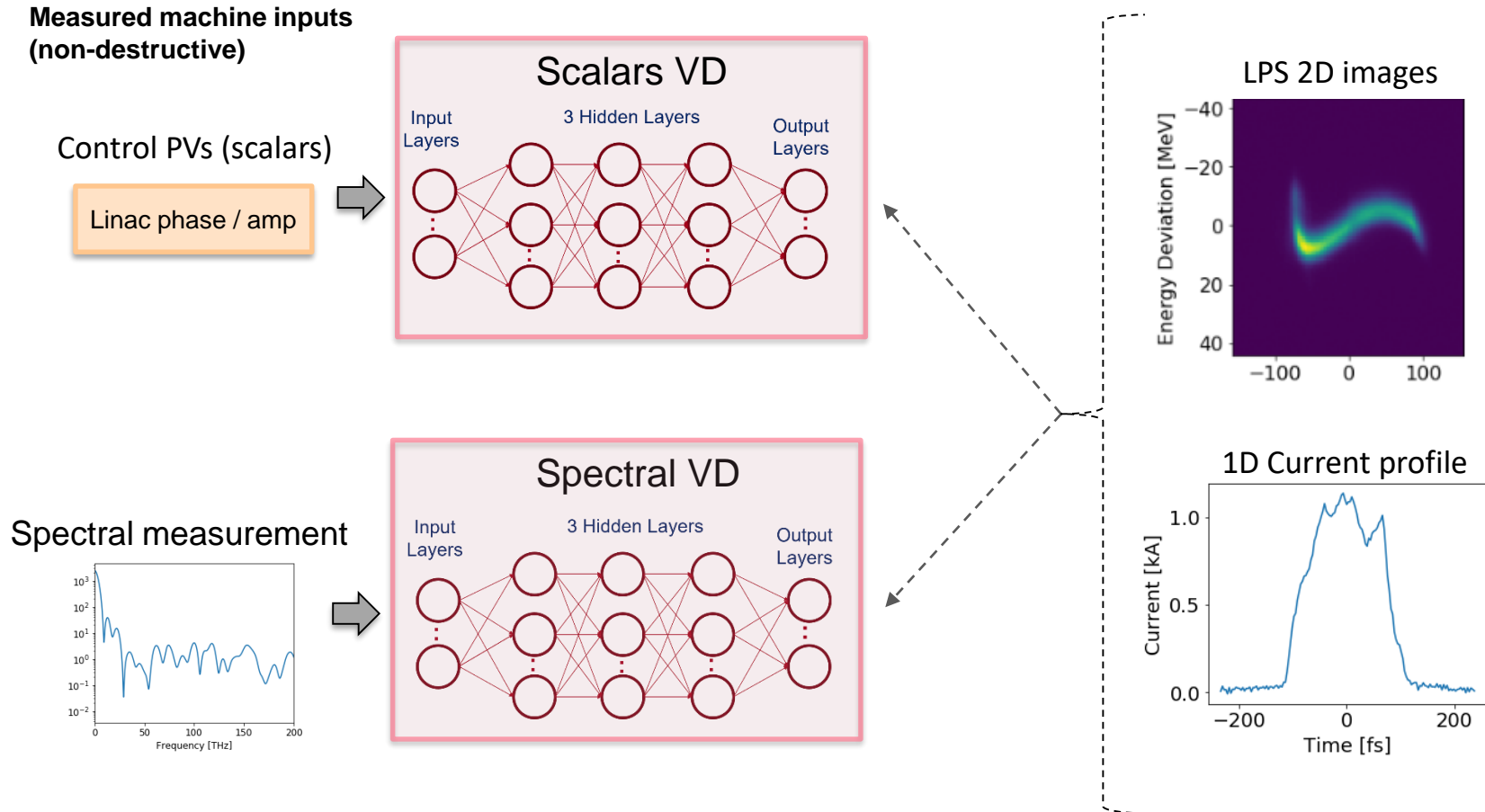
Shots with 'bad' prediction circled

C. Emma, et al., PRAB 21, 112802 (2018)

\*May be exacerbated in more complicated accelerator operation modes.

# Our Solution: Spectral Virtual Diagnostic (VD)

Neural Network— mapping millions of inputs to similarly numerous outputs.



**Only train **once!****  
**Fast prediction of beam**



# VD Class in Python is easy to use

```
from VD_class import VD
vd = VD(spectrum, Iz)
Iz_predict = vd.vd_trainer(batch_size=64, epochs=500, mc=False, mbi=False)
```

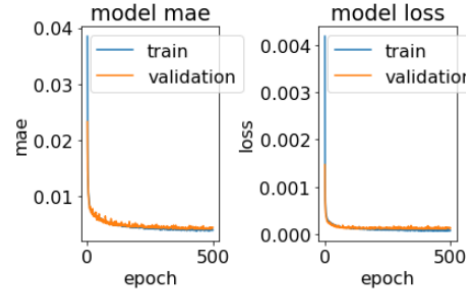
get\_model  
fit\_model  
predict\_model

Model: "model\_26"

Layer (type)	Output Shape	Param #
input_26 (InputLayer)	(None, 5)	0
dense_101 (Dense)	(None, 200)	1200
dense_102 (Dense)	(None, 100)	20100
dense_103 (Dense)	(None, 50)	5050
dense_104 (Dense)	(None, 150)	7650

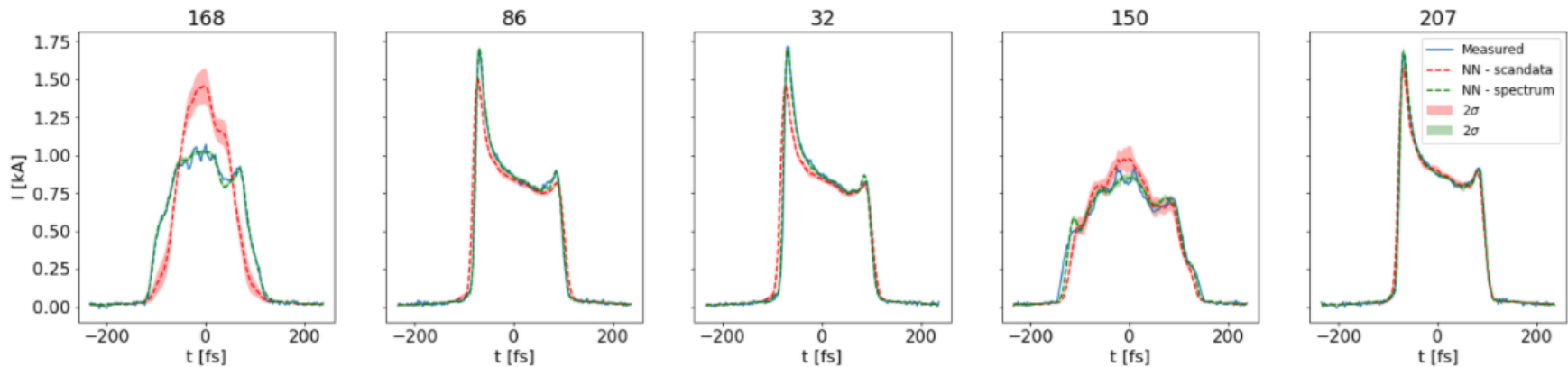
Total params: 34,000  
Trainable params: 34,000  
Non-trainable params: 0

None  
Time to perform fit [mins] = 1.140



loss: 7.725056511245074e-05  
Validation loss: 0.0001323133176889696  
Test loss: 9.489419417711619e-05  
Test accuracy: 0.004323772620409727

```
from spec_utils import *
plot_Iz_vs_VDscalar_vs_spec(y_test,y_pred_scalar,y_pred_spec,nrow=nrow,ncol=5, rnd=False, idx=[32,86,150,782,118])
```



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# Accurate & Confident Predictions - Case Studies

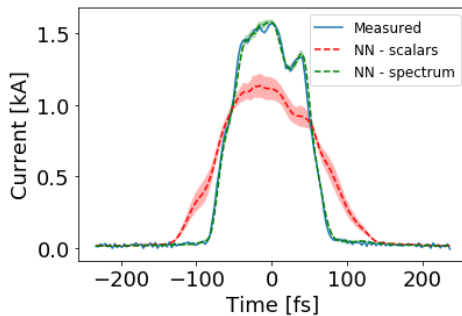
**Accuracy** would come from designing the neural network architecture & its training.

**Confidence** would come from various methods depending on the case.

## LCLS

- Experimental
- 1D/2D outputs

Accuracy

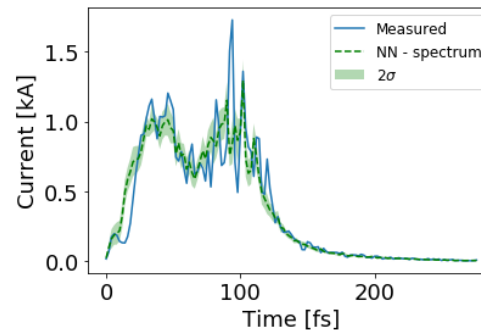


Confidence

Comparing Scalar VD  
vs Spectral VD

## LCLS-II

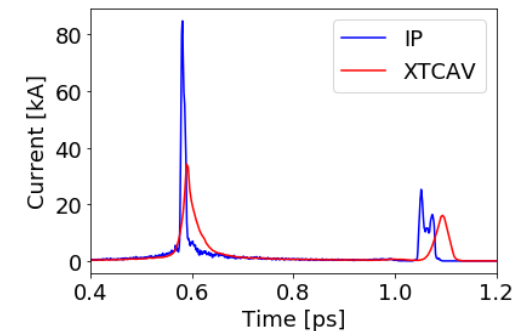
- Microbunching
- Elegant SC SXR simulation



Prediction uncertainty  
from ensemble

## FACET-II

- 2-bunch mode
- Lucretia simulation



Correlating prediction  
with spectral intensity

# Improved accuracy over scalar VD (LCLS)

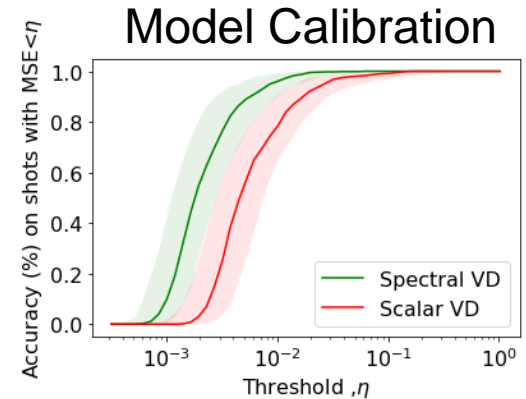
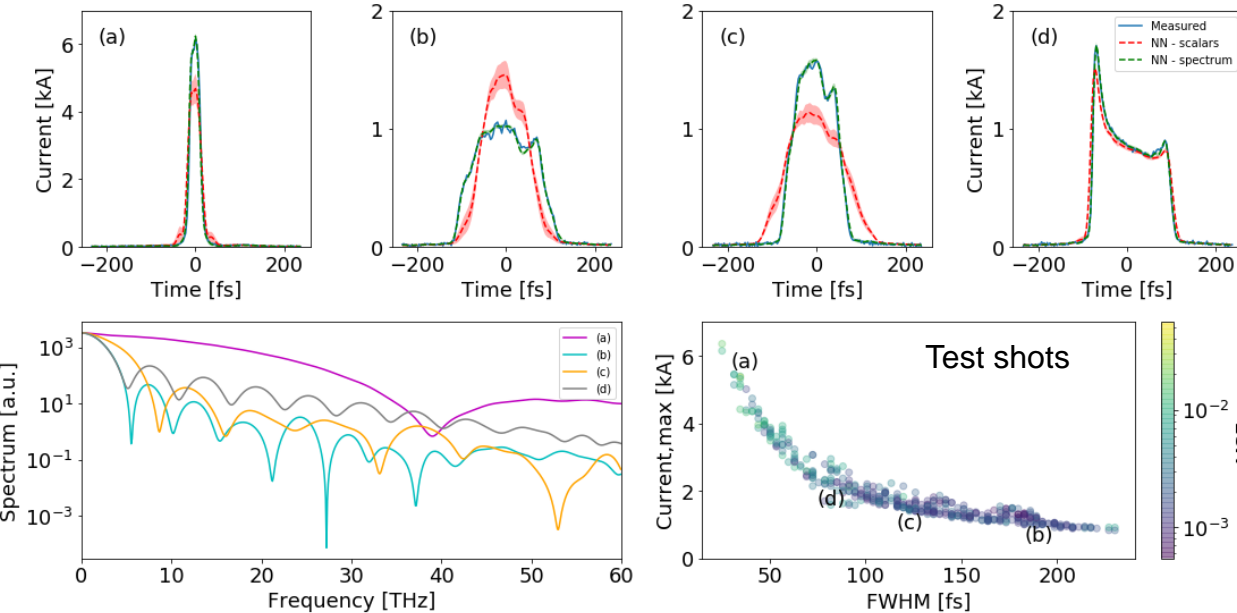
Train on ~4000 examples ; Test on ~600 examples.

Spectral VD has lower MSE than scalar VD.

## LCLS Experiment:

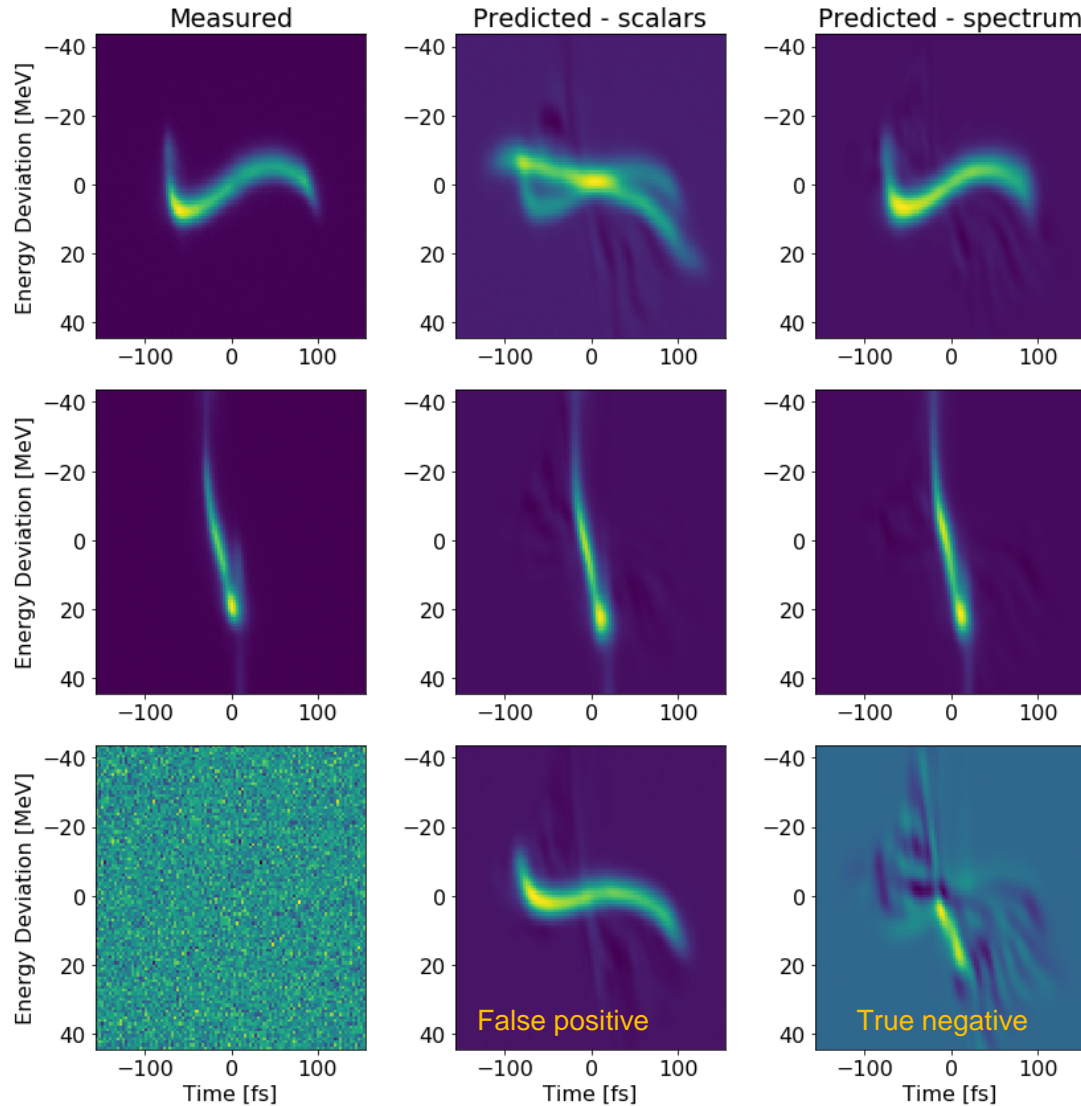
Machine parameters scanned:  
L1s phase from -21 to -27.8 deg  
BC2 peak current from 1 to 7 kA

Inputs to Scalar VD:  
L1s voltage & phase,  
L1x voltage, BC1 and BC2 current



- Scalar VD: Optimized NN architecture compared to prior work - consistently improved by 15%.
- Improved accuracy of the spectral VD.

# Spectral VD better predicts LPS images (LCLS)



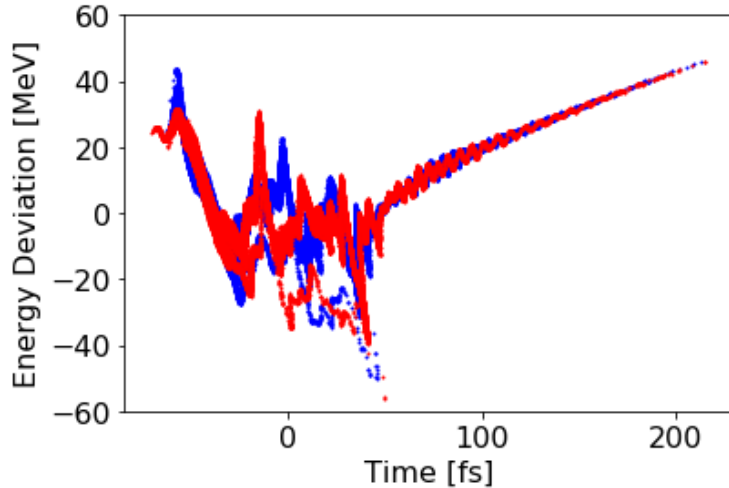
- Improved accuracy of the spectral VD\*.
- Increased confidence from multiple diagnostic predictions.

\* $MSE=0.054, 0.079$ ;  $SSIM=0.97, 0.96$  for *spectral*, *scalars*

SSIM=structural similarity index measure [0,1]

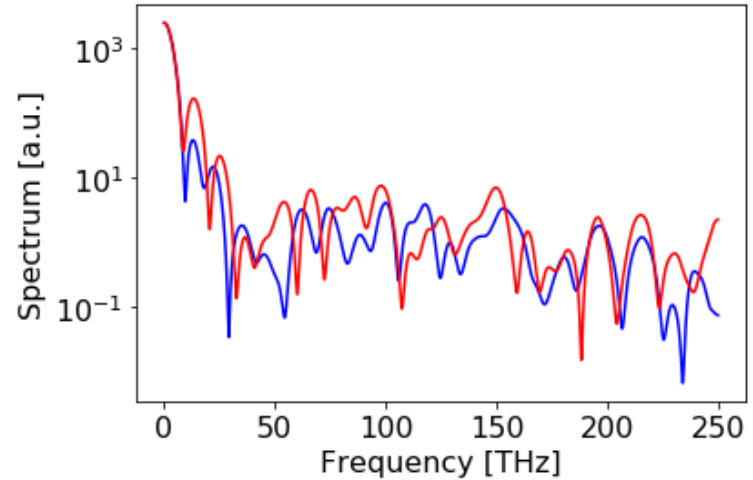
# Shot-to-shot prediction of fine features via ensembling (LCLS-II)

Two Simulations of LCLS-II SC SXR – same input, different output



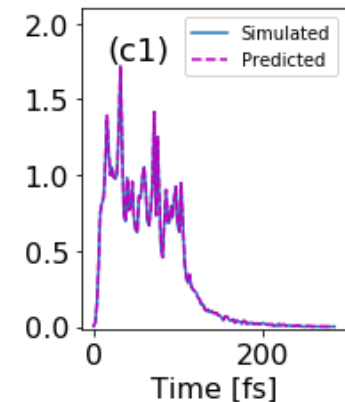
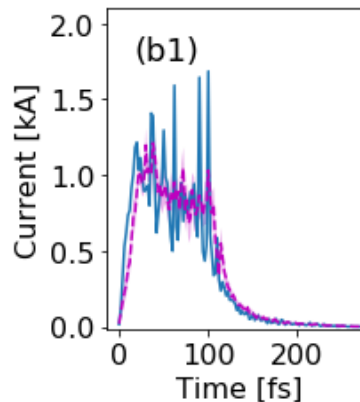
→

Only Spectral VD can be used!



- 4000 Elegant simulations
- Ensemble of networks to obtain std

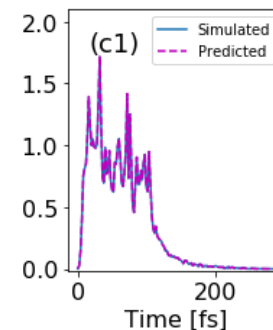
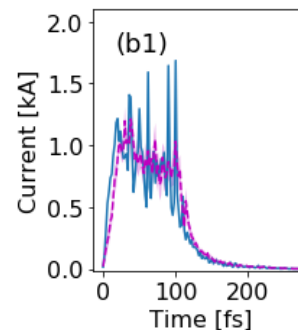
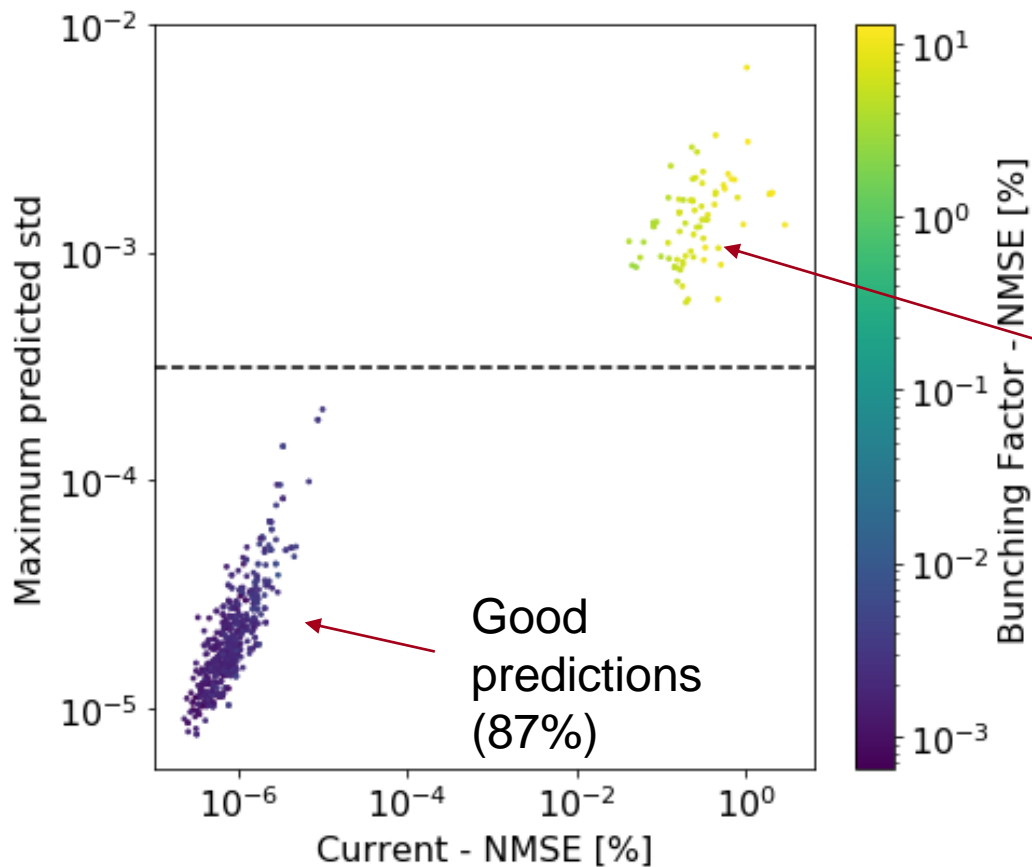
Predict current profile NMSE=1.1%



$$\text{NMSE}(y, \hat{y}) = \text{MSE} / \sum_{i=0}^{N-1} y_i^2$$

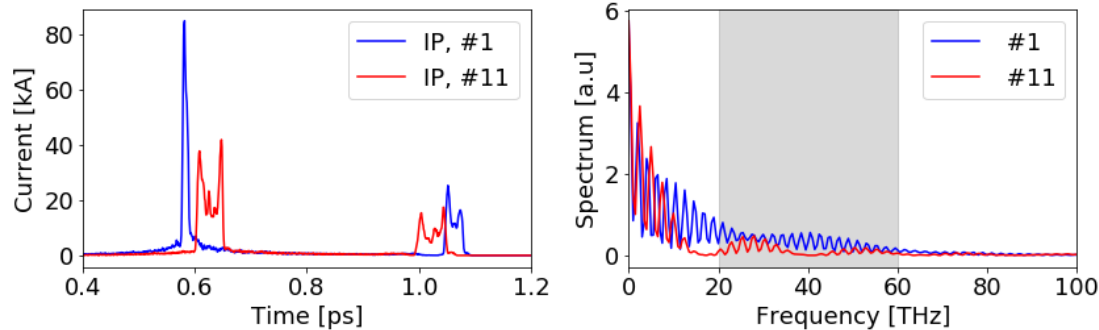
# Increasing prediction's confidence (LCLS-II)

Correlate max std and mean MSE from ensemble of random initializations.



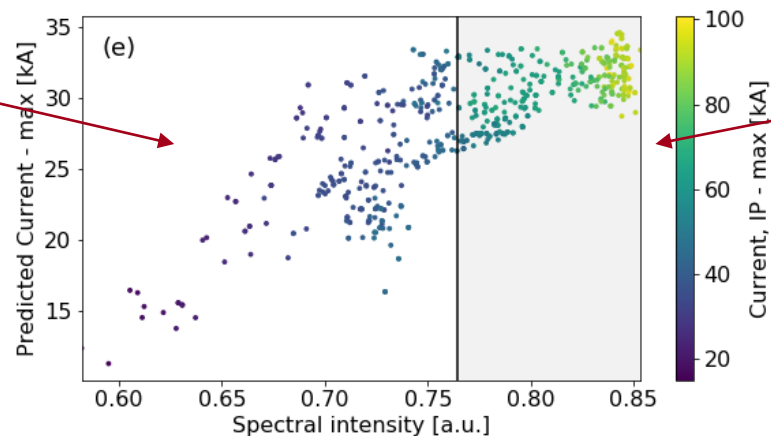
Bad predictions  
(13%)

# Going beyond current diagnostic resolution (*FACET-II*)



Optimize the frequency band to distinguish between high peak current (>35 kA) shots to lower ones.

High confidence region (46%)



Shots are beyond the TCAV resolution

Spectral VD resolves features that are beyond the TCAV limited resolution.

# Accurate & Confident Predictions - Summary

## LCLS

- Experimental
- 1D/2D outputs

## LCLS-II

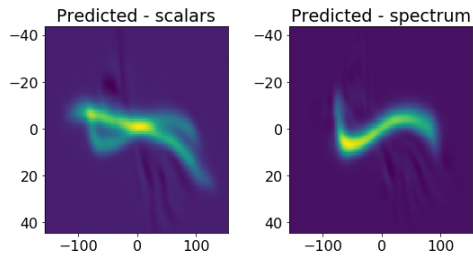
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## FACET-II

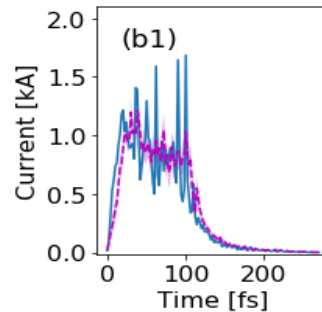
- 2-bunch mode
- Lucretia simulation

Customized the NN architecture.

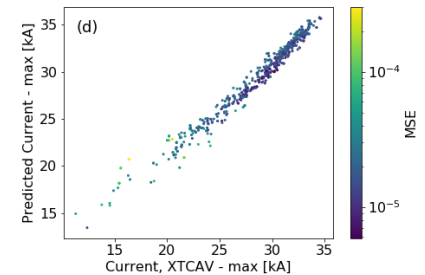
Accuracy



Wider NN trained longer

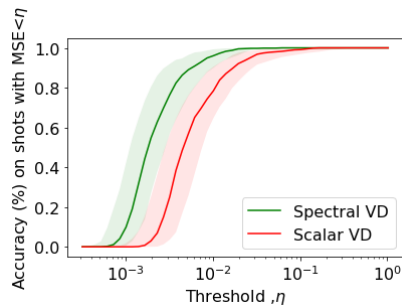


Customized the NN architecture.

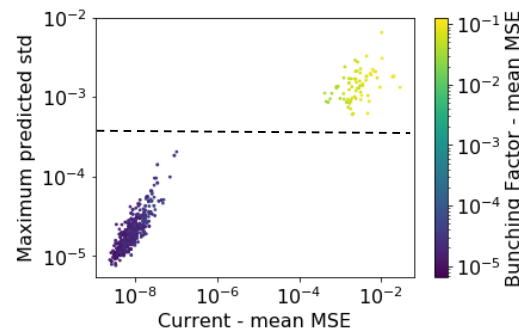


Comparing Scalar VD vs Spectral VD

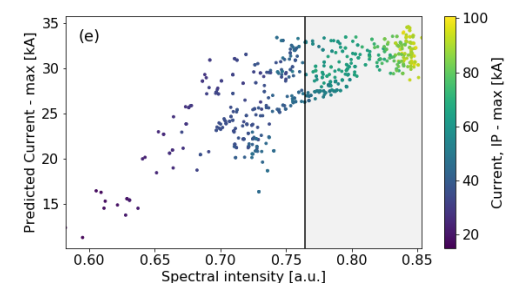
Confidence



Prediction std from ensemble



Correlating prediction with spectral intensity

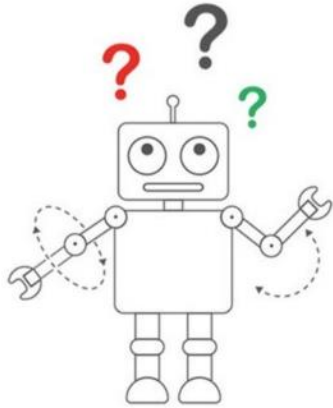




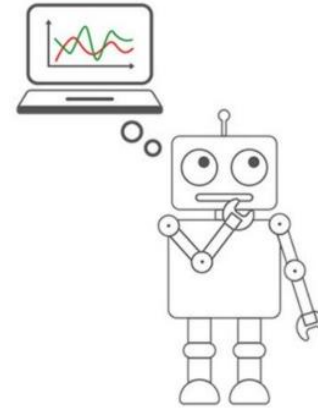
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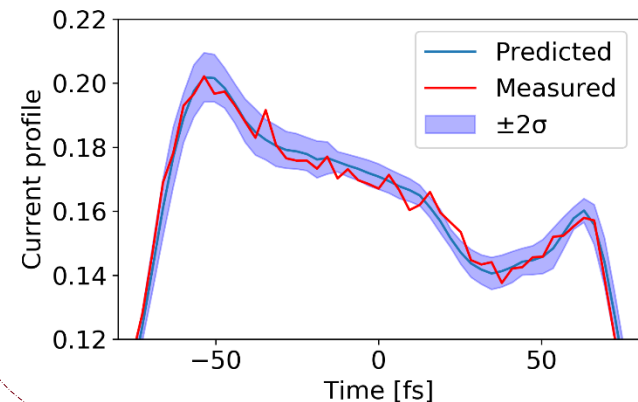
# Incorporating Uncertainties – know what we don't know



- Neural network is not aware of what it does not know!
- New shots might be out of trained distribution → prediction is unreliable.



Need estimates of std along with prediction mean.

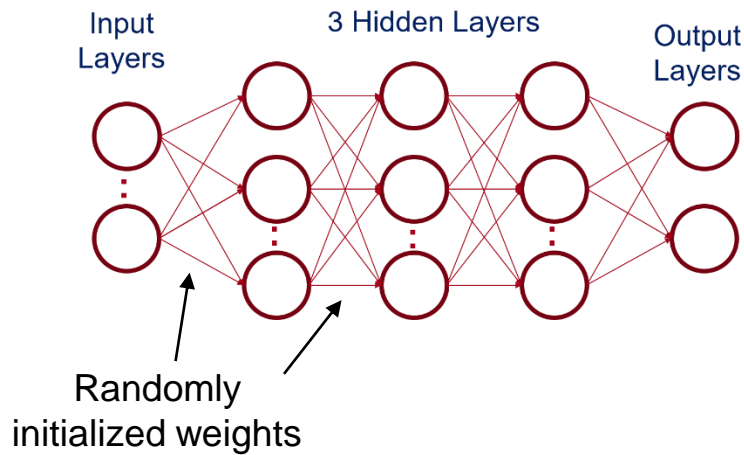


# Incorporating Uncertainties – Methods

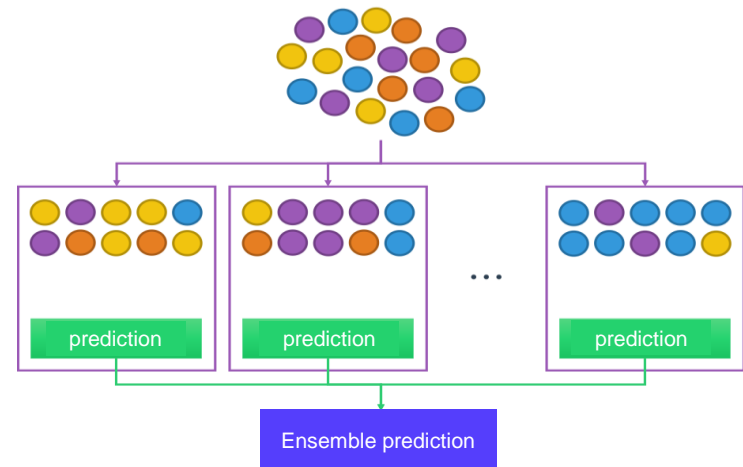
**Goal:** Prediction sensitivity - quantify how reliable the mean prediction is.

1. Ensemble methods = a collection of neural networks

## Random initializations



## Random data split

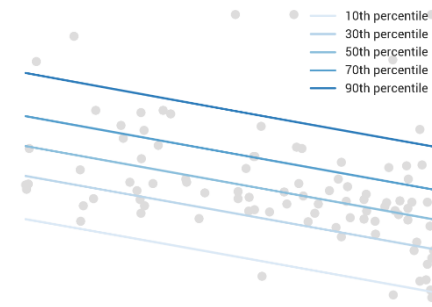


2. Quantile regression:

$$\xi_i = y_i - f(\mathbf{x}_i)$$

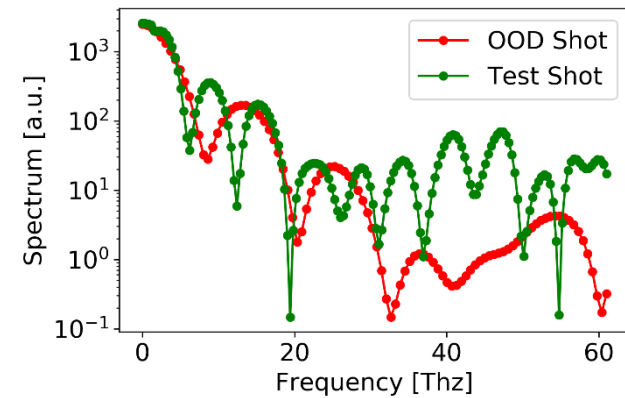
$$\mathcal{L}(\xi_i|\alpha) = \begin{cases} \alpha \xi_i & \text{if } \xi_i \geq 0, \\ (\alpha - 1)\xi_i & \text{if } \xi_i < 0. \end{cases}$$

$$\mathcal{L}(\mathbf{y}, \mathbf{f}|\alpha) = \frac{1}{N} \sum_{i=1}^N \mathcal{L}(y_i - f(\mathbf{x}_i)|\alpha)$$

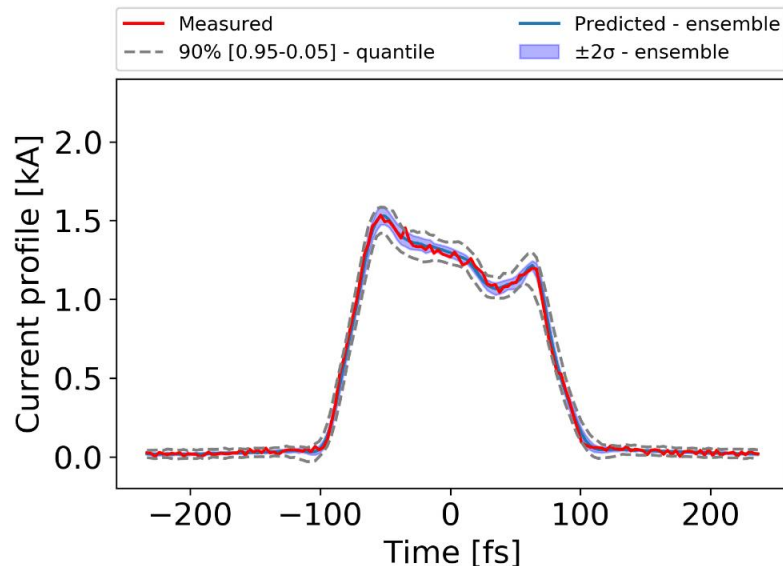


# OOD Robustness

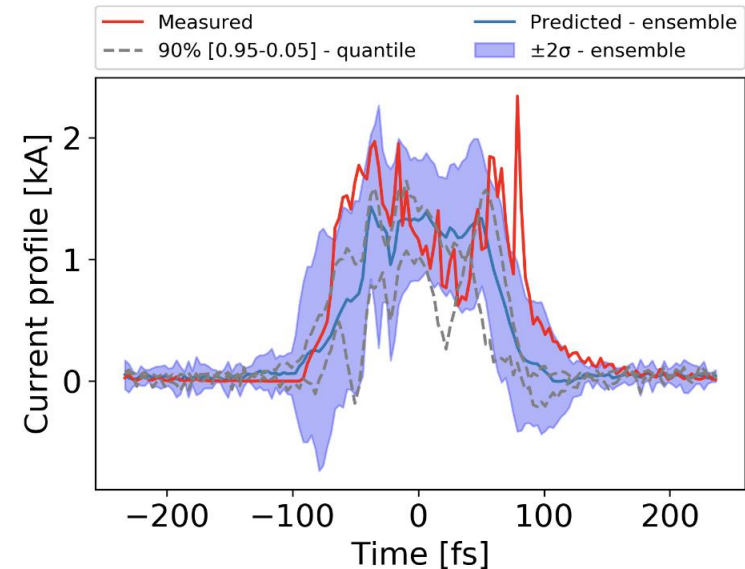
**Methods:** Ensembles (random initializations, random subset of the data, Bagging), Quantile regression.



Test shot within the trained distribution



Out-of-distribution



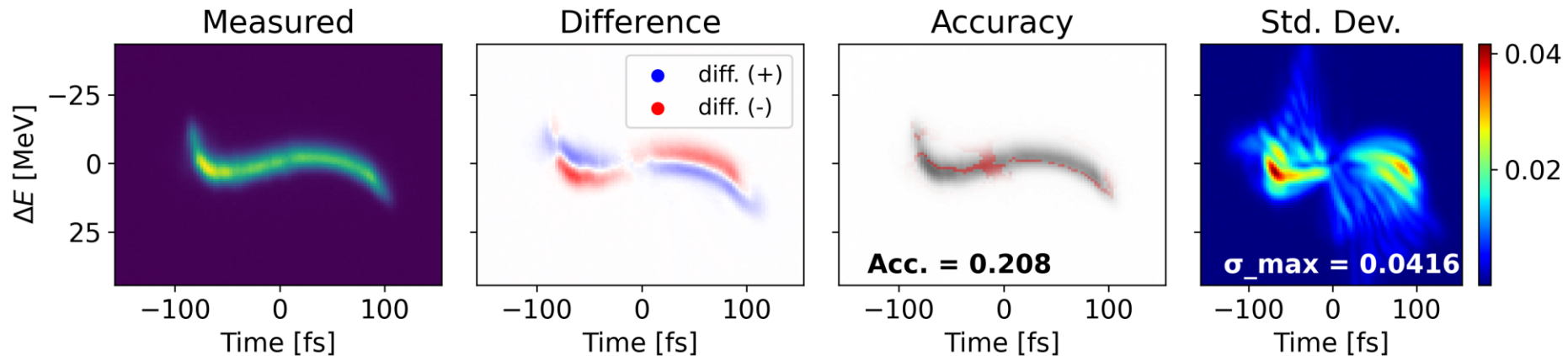
Out-of-Distribution  $\rightarrow$  Higher Uncertainty

# Common prediction errors with LPS images

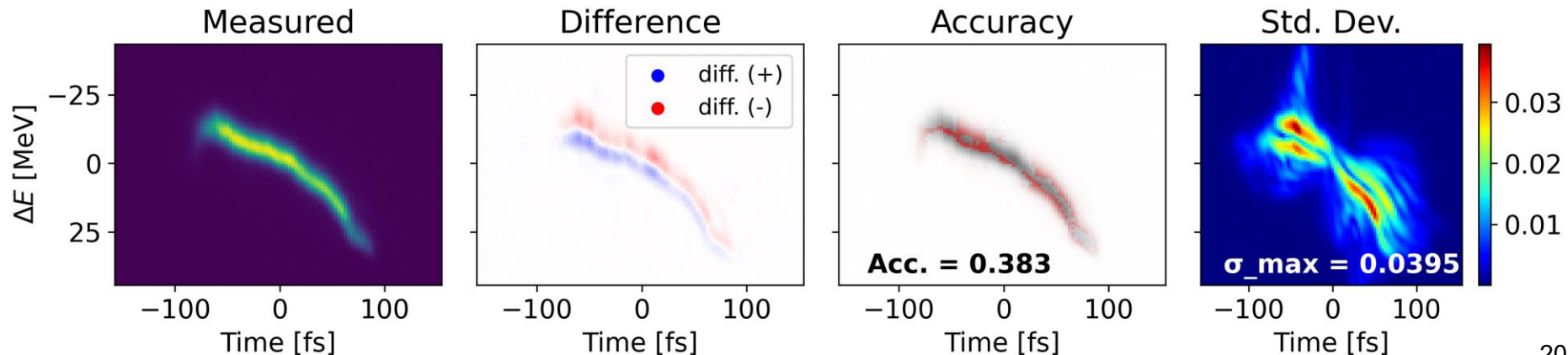
Shot #789 - Shape error: the prediction is of the wrong shape

$$\text{Accuracy} = \frac{\sum_{t=1}^T \alpha_t \cdot I_{\text{measured},t}^2}{\sum_{t=1}^T I_{\text{measured},t}^2}$$

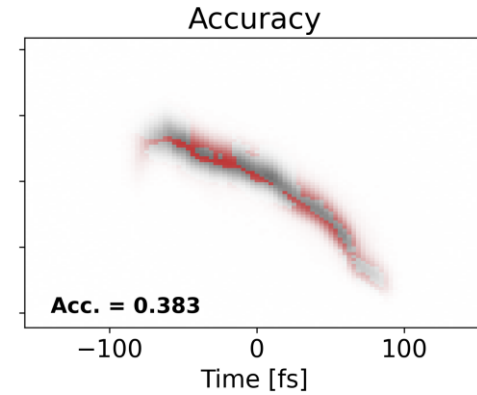
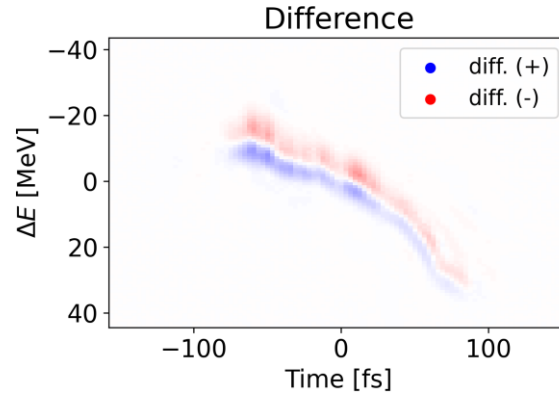
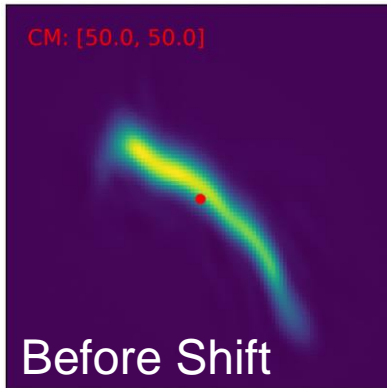
$$\alpha_t = 1 \text{ if } I_{\text{lower},t} < I_{\text{measured},t} < I_{\text{upper},t}$$



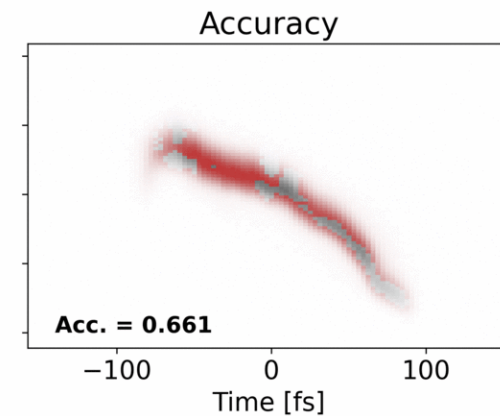
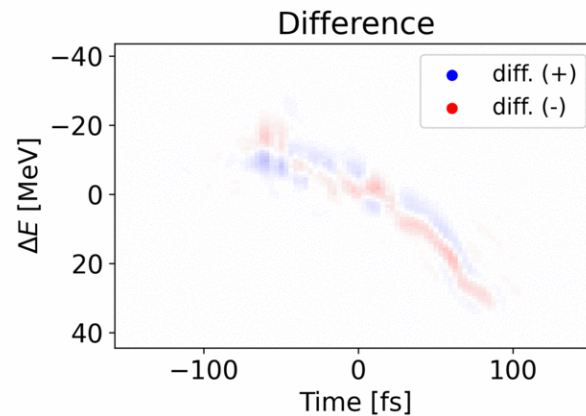
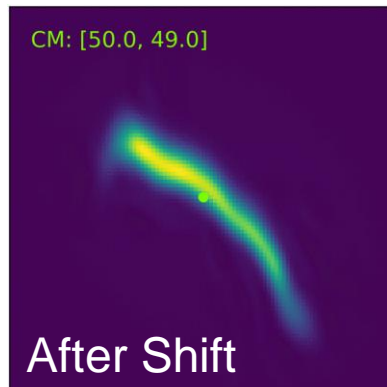
Shot #762 - Translational error: the prediction is in the wrong place



# Alleviating Translational Error



Center of Mass Correction (Pred.  $\rightarrow$  Truth)



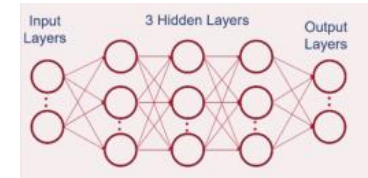
MSE  $\downarrow$   
-65.6%

Accuracy  $\uparrow$   
58.7%

# Summary of Virtual Diagnostics

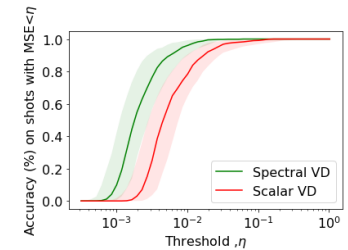
Non-destructive, shot-to-shot of bunch diagnostic during transport and delivery to experiments.

- **Fast & online** – doesn't require convoluted data processing.
- Fill in **missing** information – high peak current, repetition rate, etc.
- Understand **exotic** configs – by combining ML model with simulation.
- **Reverse** engineering of machine settings for a pre-defined current profile.



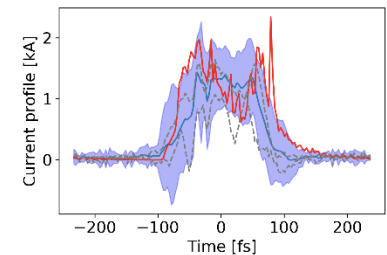
## Spectral VD:

- **Increase** confidence – flag bad shots by cross check with scalars VD.
- **Improved** accuracy over scalars VD.
- In some cases is the **only** option! (e.g. microbunching)



## Quantify prediction sensitivity:

- Flag **bad** predictions.
- Flag a **change** in the machine – out-of-distribution prediction.



ML-based virtual diagnostic for single shot prediction will provide additional information for users, and a signal for LPS feedback, tuning and control.



# Thanks to the wonderful team!



O. Convery



C. Emma



Z. Huang



M. Hogan



A. Fisher



T. Maxwell

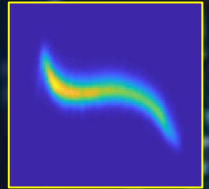


B. Jacobson



Y. Gal

# Thank You!



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