# IBA S2C2: coil forces and median plane errors due to coil displacements 

## Wiel Kleeven and Eric Forton

## INTRODUCTION

During the commissioning of the S2C2 it is intended to move the main coil assembly in the cryostat into an optimum position such that the overall effect of the median plane error during acceleration and extraction has the smallest impact on the extracted beam. The main coils are held in position by horizontal and vertical tie-rods. This allows placing these coils with five degrees of freedom (3 displacements and 2 rotations). During this operation care has to be taken, because the forces and torques acting on the coils can be large. Furthermore the system is unstable: the forces acting on a displaced coil are directed such that they intend to increase the displacement. Forces and torques acting on the main coils and median plane errors that due to coil displacement and rotations are calculated using different OPERA finite elements models in 2D as well as 3D. Forces and torques are therefore given as differential quantities. A large part of the median plane error in the S2C2 is created by the vertical asymmetry present in the design of the iron parts that are placed at the exterior of the cyclotron. These errors have been given in another communication. Median plane errors are compensated by main coils shifts. Median plane fields are computed for each of the five degrees of coil position.


3 horizontal tand $2 \times 3$ vertical tie-rods are used to position the coil-assembly in the cryostat and to hold the forces

## DIFFERENT OPERA MODELS

1. OPERA2D $=>$ rotational symmetry $=>$ used as benchmark for 3D models and for calculation of radial field error due to vertical coil-shift
2. OPERA3D-preprocessor => includes full updown cyclotron geometry with all yoke penetrations but without exterior elements => model is more difficult to make but uses hexahedral mesh which generally gives more precise magnetic field results
3. OPERA3D-modeller $\Rightarrow>$ same geometrical features as previous case => easier modeling => tetrahedal meshing => more noise fields => details can more easily be modeled
4. OPERA3D-modeller=>full up-down geometry, all yoke penetrations and all external systems such as yoke-lifting system, cyclotron feet, cryocooler and rotco shields and external beam line



## COIL ALIGNMENT ERRORS

- Five different alignment errors were introduced DDisplacements along $\mathrm{X}, \mathrm{Y}$ and Z -direction Retations around $X$ and $Y$-axis -The two coil are considered as one assembly DThree effects are calculated: i) Forces acting on the coils, ii) Torques acting on the coils, iii) Median plane magnetic field error


## FORCES AND TORQUES

- Forces and torques vary linearly with displacements up to at least 10 mm and rotations up to at least 1 degree
-Maximum force: about 2 tons per mm displacement -All displacements and rotations are unstable, i.e. forces and torques are directed such that they tend to increase their initial displacement or rotation
aTie-rods have to be designed in order to keep and position the coils in stable position


Total forces (left scale - solid line) and torques (right scale - dashed line) acting on the assembly of two main coils for a given displacement of this assembly in the X-direction or Z-direction and for a rotation of this assembly around the X -axis respectively (calculated with the pre-processor model)

| FORCES AND TORQUES ACTING ON THE MAIN COIL SYSTEM DUE TO COILDISPLACEMENTS AND ROTATIONS |  |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  | FORCES |  |  | TORQUES |  |  |
|  |  | $\begin{array}{\|c\|} \hline \mathrm{d} F \mathrm{x} \\ \text { ton } / \mathrm{mm} \\ \hline \end{array}$ | $\begin{array}{\|c\|} \hline \text { dFy } \\ \text { ton } / \mathrm{mm} \\ \hline \end{array}$ | $\begin{array}{\|c\|} \hline \mathrm{dFz} 2 \\ \operatorname{ton} / \mathrm{mm} \\ \hline \end{array}$ | $\begin{array}{\|c\|} \hline \mathrm{dTx} \\ \mathrm{Nm} / \mathrm{mm} \\ \hline \end{array}$ | dTy $\mathrm{Nm} / \mathrm{mm}$ | $\begin{array}{\|c\|} \hline \mathrm{dTz} \\ \mathrm{Nm} / \mathrm{mm} \\ \hline \end{array}$ |
| $\begin{aligned} & \frac{5}{2} \\ & \frac{5}{5} \\ & \frac{0}{6} \\ & \hline \end{aligned}$ | x-direction | 1.99 | -0.05 | 0.00 | 0 | -9 | 8 |
|  | v -direction | -0.05 | 2.00 | 0.00 | 10 | 2 | 41 |
|  | z -direction | 0.00 | 0.00 | 0.56 | -80 | 201 | 0 |
|  |  | $\begin{array}{\|c\|} \hline \hline \mathrm{dfx} \\ \text { ton/deg } \\ \hline \end{array}$ | dFy ton/deg | $\begin{gathered} \mathrm{dFz} \\ \text { ton/deg } \end{gathered}$ | $\begin{gathered} \hline \mathrm{dTx} \\ \mathrm{Nm} / \mathrm{deg} \\ \hline \end{gathered}$ | $\begin{array}{\|c\|} \hline \hline \mathrm{dTy} \\ \mathrm{Nm} / \mathrm{deg} \\ \hline \end{array}$ | dTz $\mathrm{Nm} / \mathrm{deg}$ |
|  | around x -axis | -0.02 | 0.00 | 0.12 | 91559 | -4609 | -80 |
|  | around y -axis | -0.05 | 0.01 | -0.30 | 4484 | 91305 | 79 |


| Forces and Torques <br> for well-centered <br> coils (Full geometry) |  | When the coils are well <br> centered geometrically, |
| :---: | :--- | :--- | :--- |
| there are still substantial |  |  |
| forces acting on it due to |  |  |

## MODEL COMPARISON

There is good agreement between models created by the modeller and models created with the preprocessor
-There is some difference Opera2d and both 3D models for $z$-shifted coils. This is partly due to the absence of yoke penetrations in the 2D model. The vertical force in the absence of yoke-penetrations reduces from 0.56 to $0.49 \mathrm{Ton} / \mathrm{mm}$ (pre-processorcase)

| Comparisson between modeller, pre-processor and Opera2D |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: |
|  |  |  | $\begin{array}{\|c\|} \hline \text { pre- } \\ \text { proccosor } \\ \hline \end{array}$ | modeller | Opera2D |
| x-shift | dF/dx | ton/mm | 1.99 | 1.6231 | NA |
| z-shift | dF/dz | ton/mm | 0.5 | 0.6046 | 0.3773 |
| xis | dT $\mathrm{f} / \mathrm{d} \alpha$. | Nm/deg | 91559 | 91276.1 | NA |
| rotation | dTy/d $\alpha$. | Nm/deg | -4609 | -4150.2 | NA |

## MEDIAN PLANE ERRORS



Average value and first harmonic amplitude and phase of the radial magnetic field in the median plane due to a 10 mm vertical shift of the coils and due to a rotation of the coils with 1 degree along the X-axis. For the upper case a perfect match is obtained between the 2D and 3D model. A vertical shift of about 0.2 mm will be needed in order to compensate the median plane errors due to intrinsic asymmetry in the magnetic circuit

