

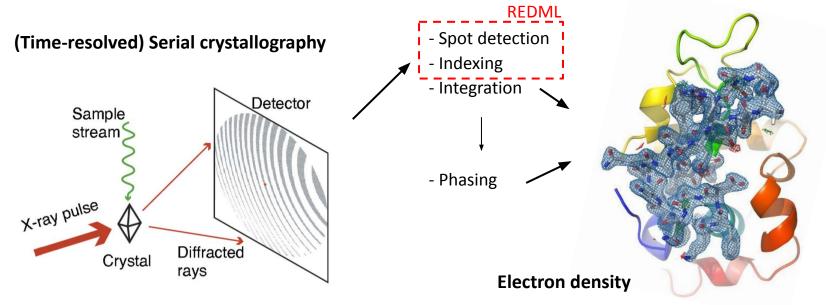


**Piero Gasparotto :: DevCon** 

## The REDML project

AWI Bi-Monthly Meeting – 17th Aug 2022

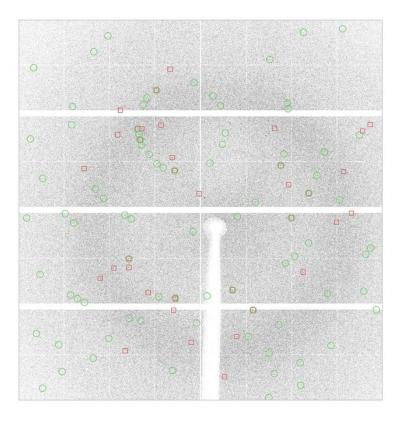




It is important to arrange for **data processing capabilities that produce real time feedback**, in order to understand the characteristics of the experimental results. Full data analysis, on a time scale significantly shorter than the data collection, permits key indicators to be monitored so that experimental parameters can be adjusted before the available sample and allotted beam time are exhausted.



## What and why?



- 1. Real-time steering of experiment
- 2. Data reduction

Predicted latticeStrong reflections

Less than 3% of the image ↓

Compression is tricky...

Garbage to gold: getting good results from bad data

By Tom Fleischman

July 26, 2018

A team led by physics professors <u>Sol Gruner</u> and <u>Veit Elser</u> began their recent research by seeking data other researchers had discarded as unusable.

Crazy, you say? To prove their idea was valid, the Cornell scientists needed data that was deemed too unclear – or "noisy" – to be used. The scientists who originally acquired the data were only able to use the best images – about 5 percent of the hundreds of thousands they collected – and threw the rest away. The Cornell group proved that these "garbage" images actually were golden. Lossy/lossless compression scheme

https://news.cornell.edu/stories/2 018/07/garbage-gold-getting-go od-results-bad-data



## Automated spot-finding

#### - Tedious search of the best parameters

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- Mostly offline processing, but faster online processing is required (JUNGFRAU 4 Mpixel at the full 2 kHz frame rate continuously produce 16.8 GB/s)
- Non trivial to detect spots in large/interesting proteins SNR ~1.2/1.4 3% hits
- Masking problems: mask is defined manually



## Automated spot-finding

Different approaches:

- Local spot-finding

The model works only in the surrounding of a pixel



- Pro: simple models, fast to train, fast to execute, good in detecting strong signals
- Cons: cannot capture long-range correlation within the full image, difficult to distinguish a Bragg reflection from any other strong pixel

### - Global spot-finding

The model works on the full image.



x

Pro: can capture long-range correlations, indexing can be implicitly taught to the model

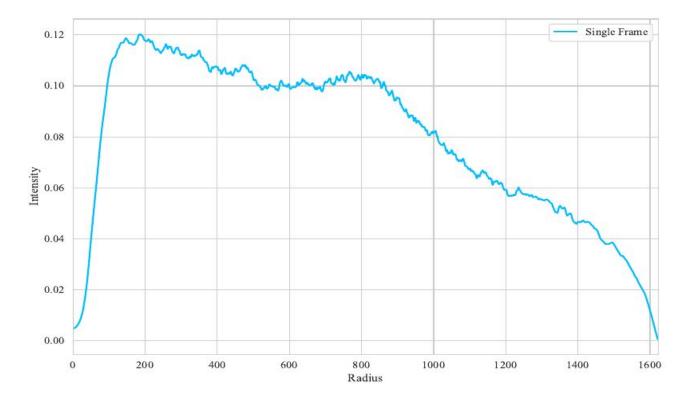
Cons: slower execution, possible problems with input sizes, slow training

1. Background removal -> 2. Local spotfinding -> 3. Global spotfinding -> 4. Fast indexing



## Automated spot-finding: background removal

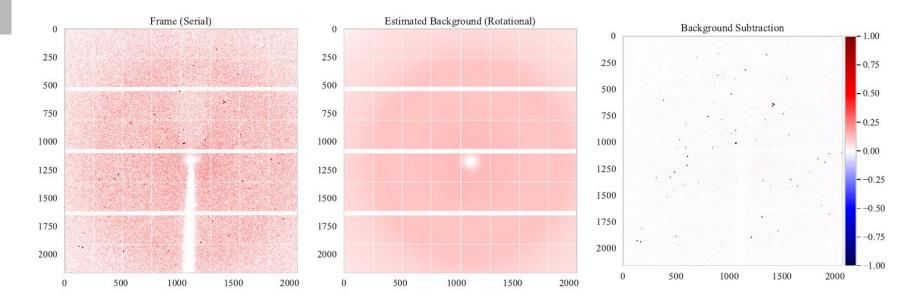
### 1. Radial background Estimation





## Automated spot-finding: background removal

#### 2. Background subtraction





## Automated spot-finding: local spotfinding

## Methods:

Supervised: LinearSVM, KernelSVM, FFNN, CNN

Unsupervised: Dictionary learning

Uncertainty estimation: Ensemble modeling

# Inputs:

- Raw counts, Square root, Log counts, Gaussian Filter Ratio
- Different sizes (9x9, 21x21), Centered

# Training:

Balanced/Unbalanced sets, Cross entropy, Focal loss, Dice loss, Weighted cross entropy



## Automated spot-finding

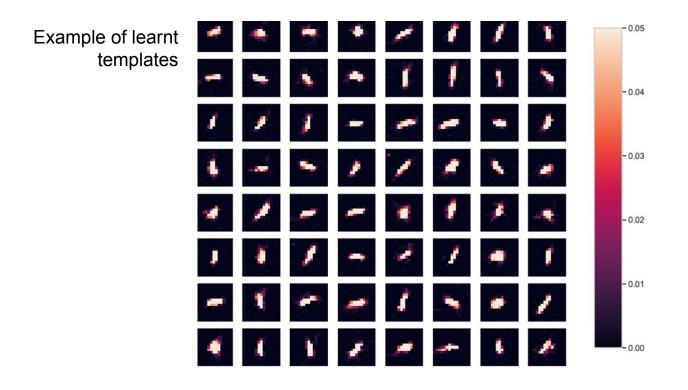
- General vs Specialized models: one can try to have a single model to work well in all cases, or for each system we can retrain a new specialized model





## Automated spot-finding: supervision?

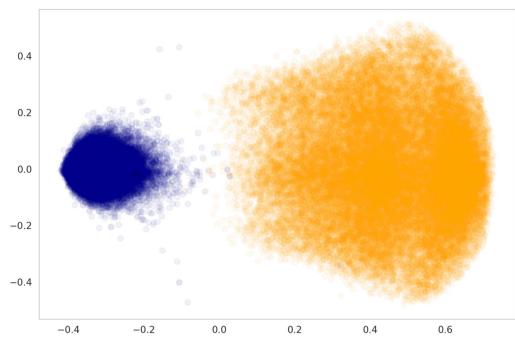
- 1. Initial labels provided by XDS, Crystfel or DIALS
- 2. Semi-supervised: label are learnt in unsupervised fashion using dictionary learning





## Automated spot-finding: binary or multiclass?

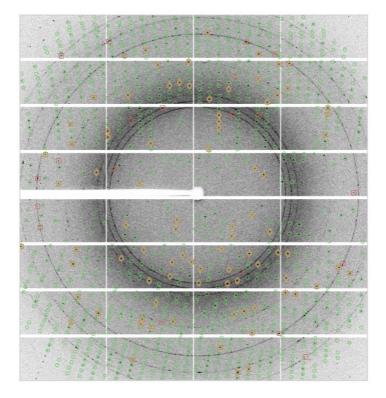
Finding strong reflections seems to be an easy task for ML. We can check this by using dimensionality reduction (KernelPCA) on the flattened image vector. Classes in the high-dimensional manifold are well-separated, meaning that also simple/fast linear models can capur strong signals

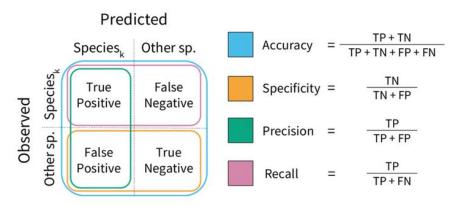




## Automated spot-finding: performance metrics

We need a way to compare different labels



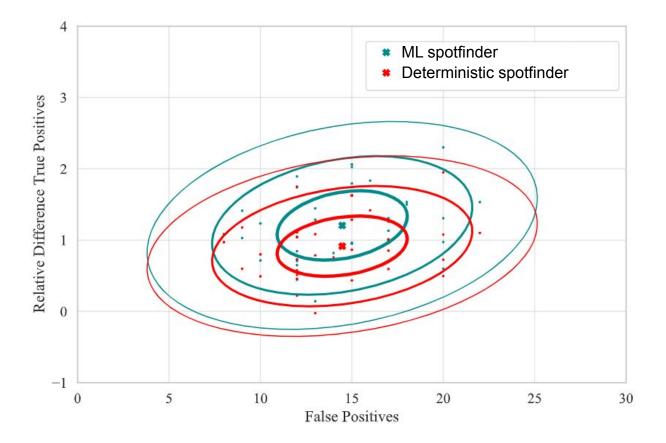


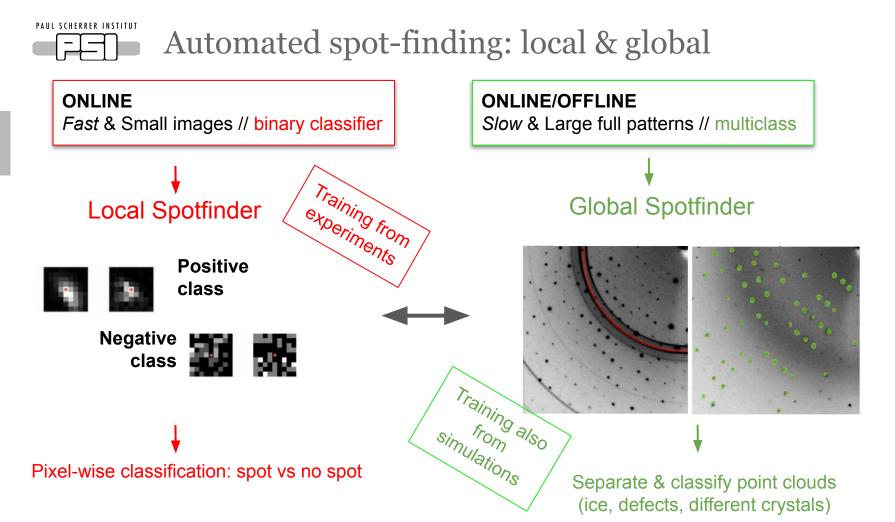
### **COLSPOT**:

F1: 0.153 | Precision: 0.802 | Recall: 0.085 | FP: 21.000



## Automated spot-finding: performance metrics



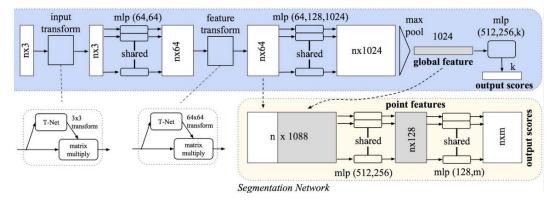




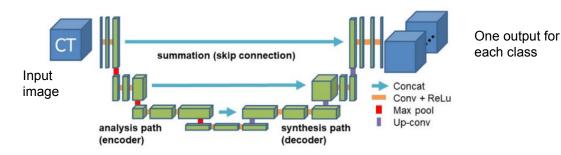
## Automated spot-finding: global spot finding

Segmentation problem: split patterns that are indexable from those that are not.

- Segmentation of 3D point clouds in the reciprocal space - PointNet (https://arxiv.org/abs/1612.00593)



- Segmentation of point of patterns in 2D images - UNet (https://arxiv.org/abs/1612.00593)





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