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Aligning Vision and Language in Embodied AI Tasks

Thursday 5 October 2023 10:15 (30 minutes)

A human moving around a busy urban environment is surrounded by signs, driving traffic, and other people. An artificial agent navigating a virtual environment of busy city streets using language instructions is also challenged with determining relevant information.

In this presentation, we introduce the research area of embodied AI, focusing on transformer-based agents in navigation tasks.

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