Update of the magnetic measurement benches of the ESRF

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ACKNOWLEDGMENTS

Special thanks



Joël Chavanne Head of the IDM group



Gaël Le Bec New IDM group leader



Damien Coulon Mechanical Engineer

Many thanks to all the Insertion Devices and Magnets team



OUTLINE

I. Introduction

Magnetic measurements at the ESRF

II. Stretched Wire Bench

- Bench design
- CE compliance

III. Hall Probe Bench

- Bench design
- 3 axis Hall probes

IV. Bench Software

- Current Igor software
- Python software development

V. Conclusion and prospects

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I. INTRODUCTION



ESRF Aerial view

ESRF – The European synchrotron

- Light source built in 1994 and upgraded in 2020 with EBS
- Located in the French Alps in Grenoble
- 6 GeV 200mA machine
- 844 m long storage ring with about 1000 accelerator magnets
- 32 straight sections with 72 undulators
- 44 beamlines welcoming 9000 scientists every year, researching material physics, chemistry, structural biology, nanotech...



Insertion Devices & Magnets team :

- 12 members, ID specialists, control specialists, magnetic measurement specialists and technicians :
- G. Le Bec, R. Versteegen, C. Benaberrahmane, L. Bortot, F. Revol, B. Cottin, G. Giroud, F. Bidault, F. Perratone, J. Caverot, M. Michel, L. Samaille
- Relocated in ESRF01 after EBS completion, about 1000m², LN2 network for CPMU measurements





I. INTRODUCTION



EBS SR Quadrupole, 20T/m

Accelerator magnets measurements

Use of a stretched wire bench for :

- Field & gradient measurements
- Multipole harmonic analysis
- Magnetic center measurement
- Roll, Pitch and Yaw angles measurement
- Magnetic length

Results with 20T/m 50cm long, 33mm radius quadrupole

	Typ. repeatability	
Magnetic center position	2	μm
Pitch and yaw angles	0.1	mrad
Roll angle	0.1	mrad
Integrated field	0.2	Gm



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I. INTRODUCTION



Long taper permanent magnet undulator

Undulators measurements

Use of a stretched wire bench for :

- Individual magnet field integral measurements for sorting assembly lists
- Magnets (and poles if hybrid) assembled on bench
- Field integral measurement of the undulator during the assembly and tuning process

Use of a Hall probe bench for :

- 3 axis field measurements along undulator
- Optimization of the electron trajectory, optical phase and magnetic angle



Bench upgrade motivations

Stretched wire bench :

- Improve measuring capability before EBS
- Improve wire position for fiducialization of EBS magnets
- CE certified for commercial purposes

Hall probe bench :

- Easier hybrid undulator assembly process with on bench touch probe and assembly tools
- Faster undulator measurement for shimming and optimization
- Update of our 20yo in house 3D Hall design
- CE certification



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II. STRETCHED WIRE BENCH - DESIGN



- Mostly 100µm Ti90 Al6 V4 wire, up to 2m
- Keithley 2182A nanovoltmeter

Integrated field repeatability 0.2 Gm

- Newport ILS-100CC horizontal stage
- Newport IMS-100V vertical stage
- XPS RLD4 motion controller

Repeatability 0.5 µm

- 80 x 60 x 300 cm granite table
- 4.4 Tons



ESRF stretched Wire bench CAD

II. STRETCHED WIRE BENCH - DESIGN



- Orthogonality plate, checked with interferometers, shimmed
- Tensioning system, wire frequency stretched to 50Hz multiple.

 V shaped wire support, measured with FARO arm,

 Alignment pins, checked with FARO arm, shimmed



II. STRETCHED WIRE BENCH – CE COMPLIANCE



Personne autorisée à compiler la documentation technique / Person authorised to compile the relevant technical documentation:

Bench now CE certified

- Complies to Machinery directive 2006/42/EC
- Mainly uses commercial components
- Complete user manual
- Emergency stop buttons
- Handling procedure
- Work area requirements



II. ESRF STRETCHED WIRE BENCHES LOCATIONS



- More than 10 benches installed across Europe
- Trusting partners such as Soleil, Tesla, Sigmaphi, SEF and more
- Bench being build for PAL in Korea



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Prototype under development at ESRF

- 4m granite for 3D Hall probe
- 2 satellite granite SW Bench

Needed to measure undulator field integrals and racetrack boundaries (see IMMW20 talk from G.Le Bec)

 Fit either a measuring table or an undulator





- Mostly 300µm Carbon wire, 3.3m
- Keithley 2182A nanovoltmeter

Integrated field repeatability 0.2 Gm

- Newport ILS-250CC horizontal stage
- Newport IMS-300V vertical stage
- XPS D8 motion controller

Repeatability 0.5 µm

• Z axis rotation plate needed





- Newport IMS-300CC horizontal stage
- Newport IMS-300V vertical stage

Repeatability 0.5 µm

 Tecnotion UL9 linear motor with Heidenhain LIDA 405 encoder

Accuracy 5 µm; Repeatability of 2 µm

- XPS EDBL driver
- 250W continuous, 1000W peak
- Acceleration up to 400mm/s²
- Linear motion up to 400mm/s



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- Quick mount for hall PCB, touch probe and assembly tools
- 3 axis hall sensor to determine
- Renishaw RMP 40 touch probe
- 1 µm repeatability for module positioning



ESRE



- Ergonomic mounting table
- 5 axis adjustments to align with bench
- Suited to all our types of undulators
- Use of the bench arm with assembly tools for positioning
- Position check and optimization with touch probe and hall probe
- Minimize the optimization process on undulator frame



- Similar to SW Bench
- Designed with CE compliant commercial parts
- New risk with moving parts

• Old design :

7A @ 44V – set to 5 cm/s => 15N to stop

• New design :

25A @ 96V – set to 40cm/s => 960N to stop

 \rightarrow Keyence laser scanner tests





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III. HALL PROBE BENCH – 3 AXIS HALL PROBES



Needs for a new 3D Hall sensor

- Less than 3mm thick with PCB
- Measure fields from 10mT to 2T
- Good orthogonality
- Analog outputs for XPS triggering
- \rightarrow In house design
- \rightarrow Commercial sensor



III. HALL PROBE BENCH – 3 AXIS HALL PROBES



3 axis ESRF Hall probe refresh

In house design with 3 analog hall sensors :

- Refresh of a design from the 2000s
- Cheap and easy to integrate
- 2.5mm thick for measurements at gap 4.5mm
- Orthogonality to characterize with undulator
- Calibration with NMR in a dipole.
- Tests with NI 6356 and NI 6421 DAQ



III. HALL PROBE BENCH – 3 AXIS HALL PROBES





Metrolab MV2

Commercial sensor :

- Either Senis SENM3Dx or Metrolab MV2
- Harder to integrate on custom PCB
- Orthogonality guaranteed by supplier
- Calibration with NMR probe in a dipole.
- \rightarrow Tests with Arduino and NI 6421 DAQ (Metrolab)
- \rightarrow Tests with Raspberry and NI 6421 DAQ (Senis)



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IV. BENCH SOFTWARE

💥 MagicFinger-ID14 - Igor Pro 8.04 32-bit

File Edit Data Analysis Statistics Macros Windows Misc Racetrack Undulators SWLab PM assy dev Tango Temperature Users Help



Current software

- Igor Pro interface
- C++/Igor XOP code to drive motors and Keithley
- Igor license and XOPtk license needed
- Non trivial to maintain and to further develop
- Steep learning curve



IV. BENCH SOFTWARE

🕒 Magbench GUI

File Settings Data Devices Measurements Console

OT XPS2D	QL Wire			Q1 Reference XPS2D	
Stop Reset Go Home	-Wire Configuration			X offset (mm): 0.00	÷ 0
	Sag (um):	30.6562500000	•		
State	Frequency (Hz):	100.000000000	•	Y offset (mm): -50.00	-50
State on	Tension (N):	1.3885839529	-		
	Tension Break (N):	7.0293135624	-	dX offset (mm): 0.00	0
Status READY	Frequency Break (Hz):	224.9937153471	•	dV offset (mm): 0.00	
	Resistance (Ohm):	213.9042435155	÷		. ·
HARDWARE STATUS XY.X: First driver powered on - 7M low level	Diameter (mm):	0.100000000	÷		
XY.Y: First driver powered on - ZM low level	Length (mm):	1000.000000000	÷		
YS.Pos: First driver powered on - ZM low level YS.Pos: First driver powered on - ZM low level	Material:	TiAI4V6	~		
POSITIONNER ERRORS		Restore Default			
XY.X:					
XS.Pos:					
YS.Pos:					
GROUP STATUS					
	TN (01:				
Motion					
X position (mm): 0.00 📮 0.0					
Y position (mm): 0.00 - 0.0					
Delta X position (mm): 0.00 💽 0					
Delta Y position (mm): 0.00 🔹 -0.0					
Velocity (mm/s): 20.00 20					
XPS frame of reference					
O Magnet frame of reference					

Python software in development

- Simple python GUI
- Python code to drive motors and Keithley
- Freeware and open source
- Object oriented software
- Easier to build upon for power users
- External libraries dependence
- Being finalized for SW Benches
- Work in progress for Hall bench



IV. BENCH SOFTWARE DEVELOPMENT STATUS

	Scan		Results
Stop Reset Start Set reference	e X start (mm):	-20.00 -20	☆ ← → ⊕ 🕒
State			10-
State on	X end (mm):	20.00 20	
Status Ready for measuring	Y start (mm):	0.00 🔹 0	0.8 -
MEASUREMENT:	Y end (mm):	0.00 🔹 0	a gu
idle SUBDEVICES:	Delta X position (mm):	0.00 0	0.0 -
DAQ state: on XPS2D state: on	Delta Y position (mm):	0.00 🗘 0	
	Velocity (mm/s):	20.00 🔦 20	ت د د د د
	Positioning velocity (m	m/s): 20.00 🔹 20	
	Acceleration (mm/s^2)	80.00 🔦 80	0.0 0.2 0.4 0.6 0.8 1.
	Averages:	1 1	Position (mm)
	Scan timeout (s):	30.00 30	
	Motion timeout (s):	30.00 🛉 30	Axis Horizontal V
	Sampling frequency (H	z): 1000000.00 🔹 1000000	
leasurement	Number of Points:	21 21	
100 100 Neasurement timestamp: 2024-10-03 09:46:04	0%		✓ Plot the measurement □ Plot the reference
eference timestamp:	Correct ambient field		

Measurements ready

- Field integral line
- Field integral Circle
- Field integral point
- Magnet Sequencer
- Wire tension

To do

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. . .

- Harmonic analysis
- Magnet center & angle
- Hall scan
- Touch probe measurements
- Various data processing tools to help with undulator tuning



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Conclusion

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- 3D Hall probe measurement bench update is in progress

3D hall sensor and safety laser scanner tests to be done before continuing the certification process

• Python based software is in progress and being finalized for SW applications

Prospects

- Future focus on magnet tomograph prototype (see IMMW21 presentation from G. Le Bec)
- Future upgrade on in vacuum measurement bench



THANK YOU FOR YOUR ATTENTION



<u>Grenoble and ESRF as seen from ISS – Thomas Pesquet 2021</u>



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