



# MuEDM superconducting solenoid: magnetic pre-design (Phase II)

F. Trillaud <[ftrillaudp@ii.unam.mx](mailto:ftrillaudp@ii.unam.mx)>

C. B. Crawford <[c.crawford@uky.edu](mailto:c.crawford@uky.edu)>

C. Calzolaio <[ciro.calzolaio@psi.ch](mailto:ciro.calzolaio@psi.ch)>

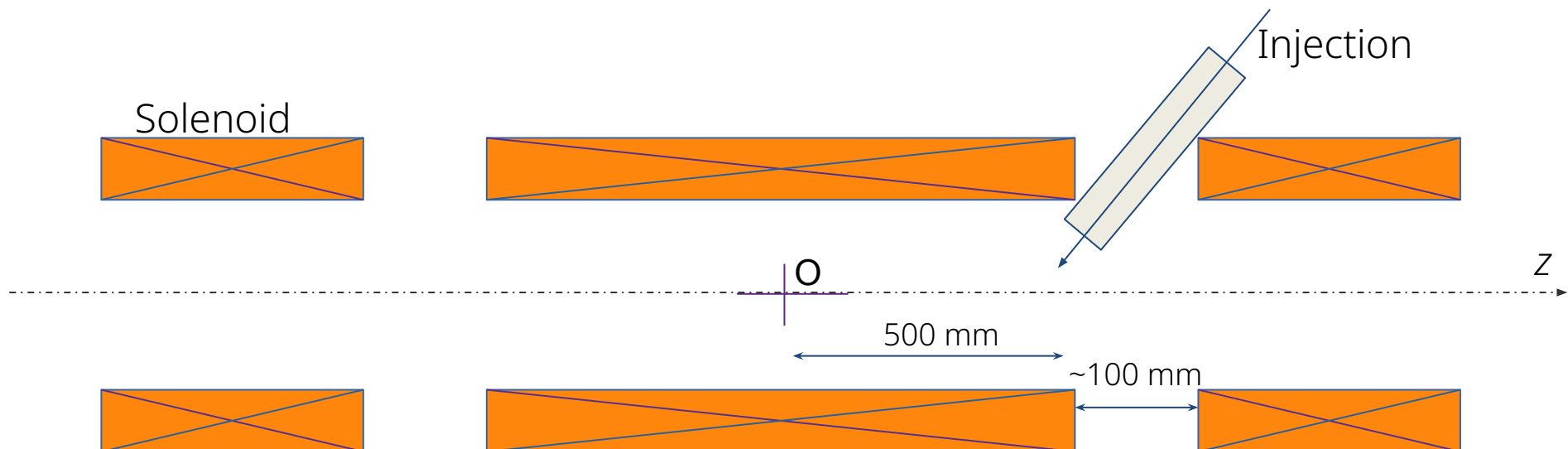


# Overview



Pre-design of a superconducting solenoid magnet

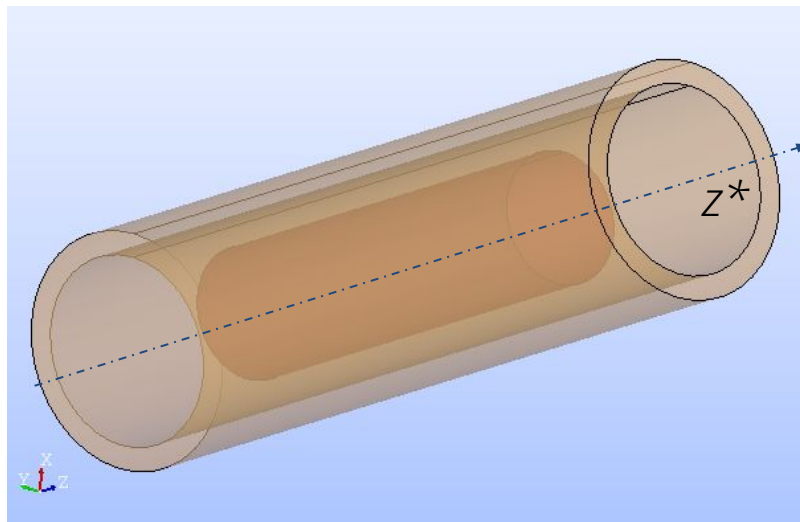
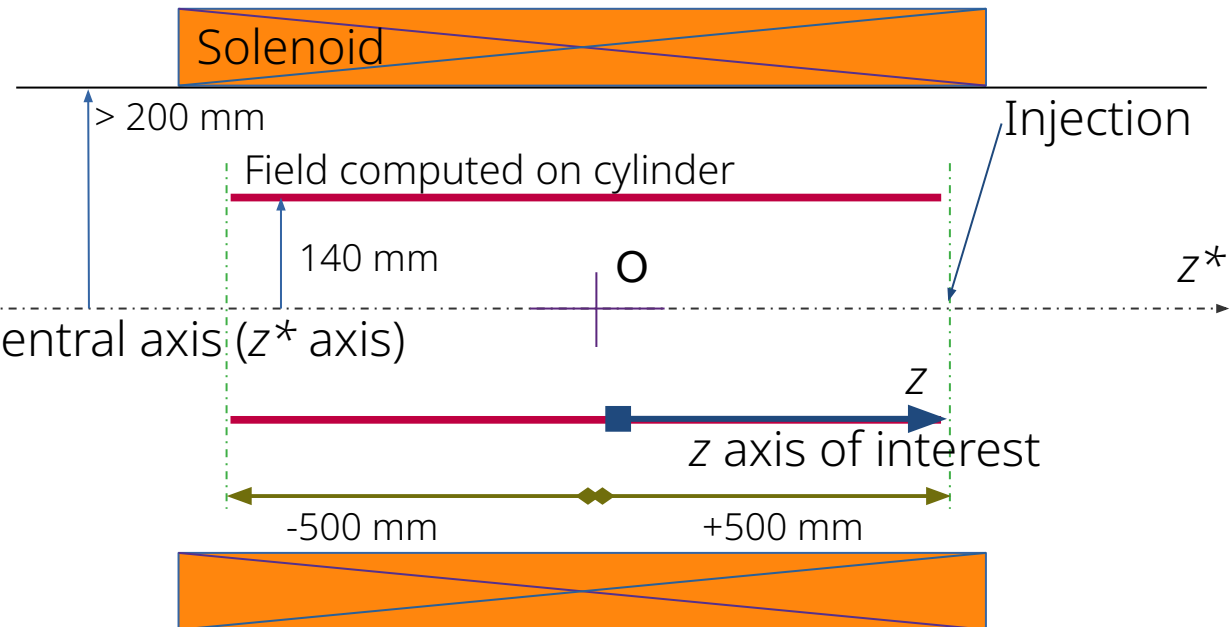
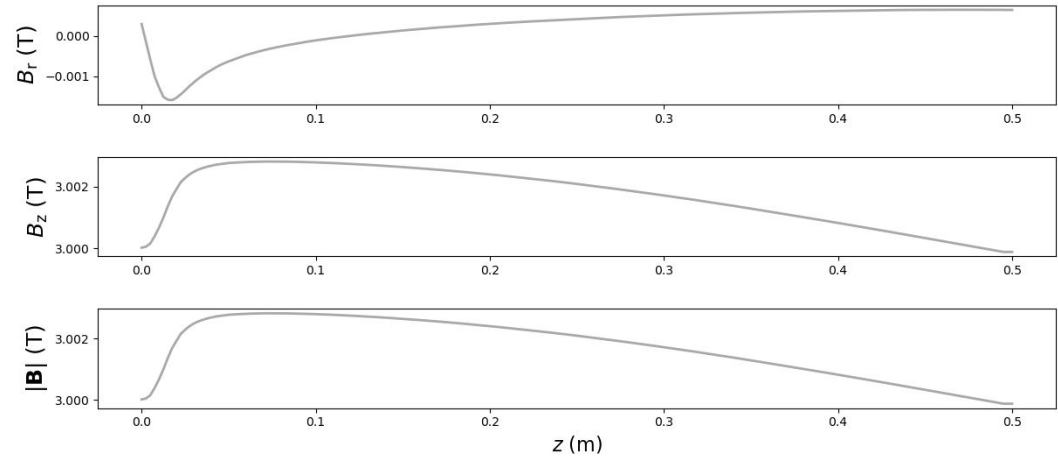
Find the optimum distribution of current densities across the magnet given magnetic field requirements



# Spatial and magnetic specifications



- Cylinder radius:  $R_{cl} = 140^{+8}$  mm
- $B(R_{cl}, 0) = 3^{±0.3}$  T
- Magnetic design spanning  $±500$  mm around the center (covering the injection point)
- $ΔB = B_{max} - B_{min} < 1‰$  over  $±500$  mm
- Inner radius of solenoid:  $> 200$  mm
- No ferromagnetic material

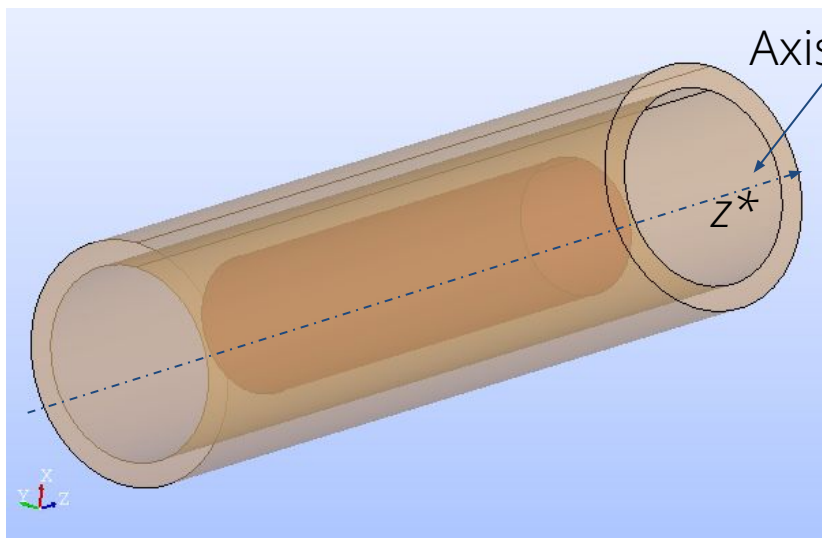


# Axisymmetric model

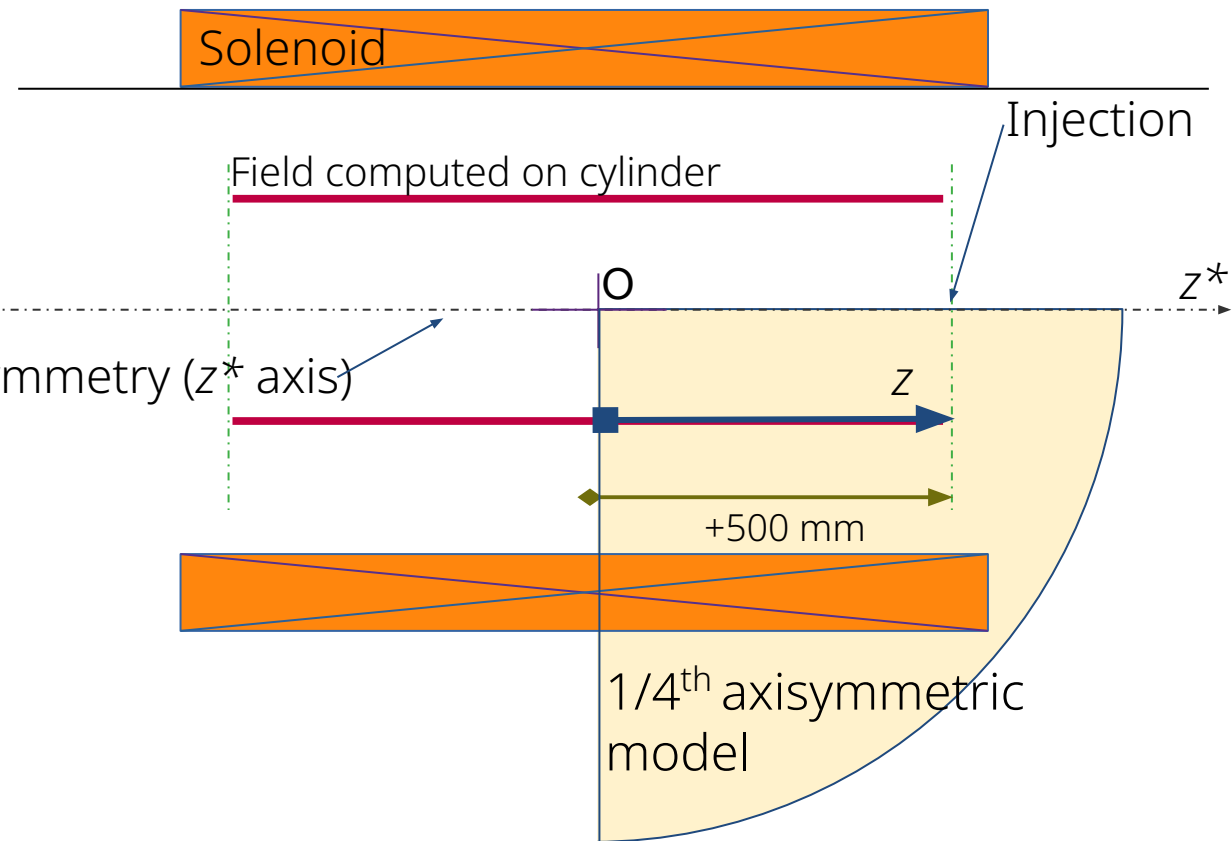


## Basic assumptions:

- Axisymmetry
- Continuous magnet (solenoid as a block, no injection aperture)



Axisymmetry ( $z^*$  axis)





## Not successful

1) Two optimization tools: Genetic Algorithm (GA) and Particle Swarm Optimization (PSO)

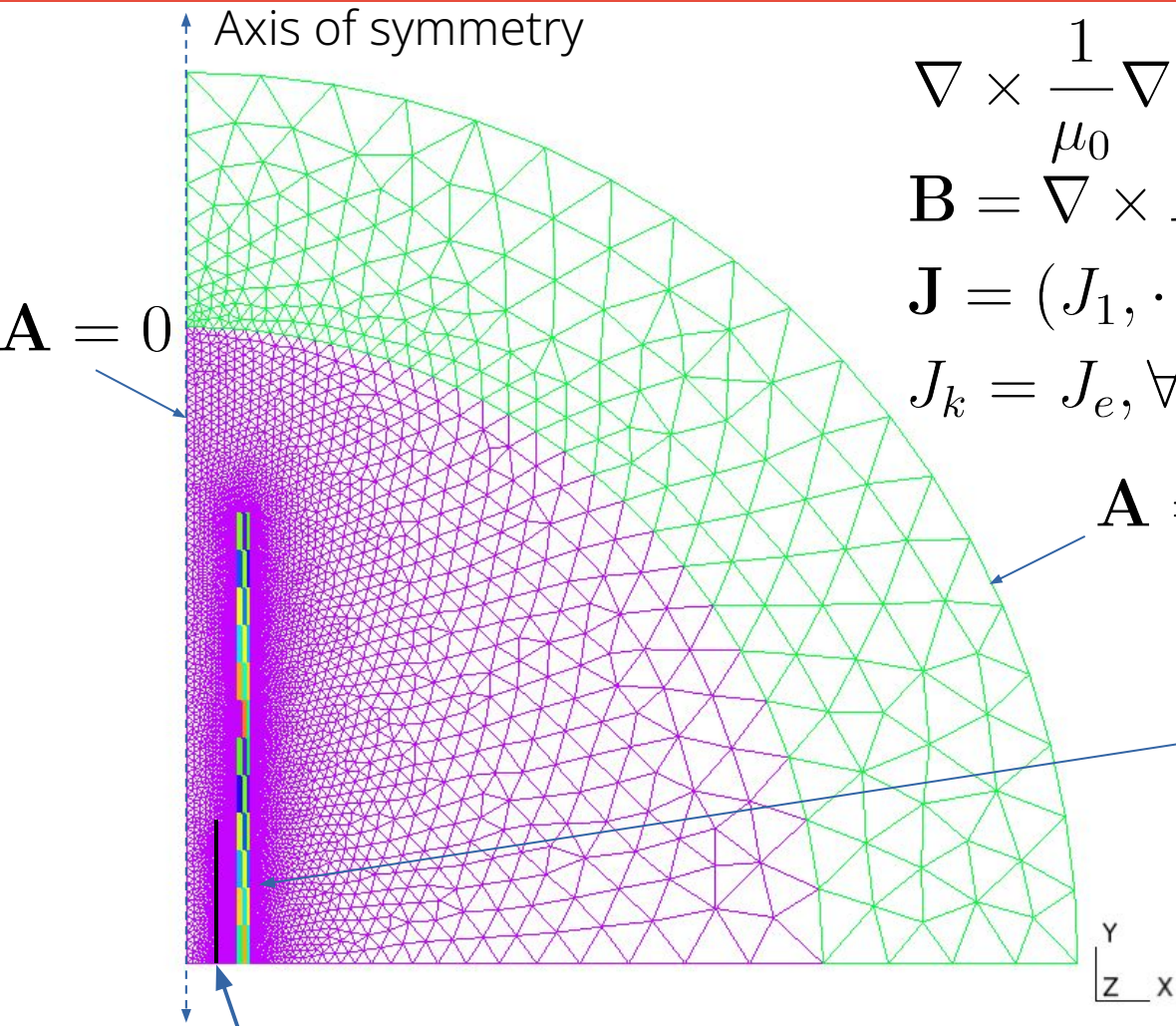
- GA: pygad library (<https://pygad.readthedocs.io/en/latest/>)
- PSO: pyswarms library (<https://pyswarms.readthedocs.io/en/latest/>)

2) Inverse problem (Singular Value Decomposition and regularization)

For 1) and 2), we used Finite Element Model (FEM) to solve the field on the region of interest:

- Gmsh (<https://gmsh.info/>) to build the geometry and the mesh
- GeTDP (<https://getdp.info/>) to solve the magnetic field over the mesh

# FEM



$$\nabla \times \frac{1}{\mu_0} \nabla \times \mathbf{A} - \mathbf{J} = 0$$

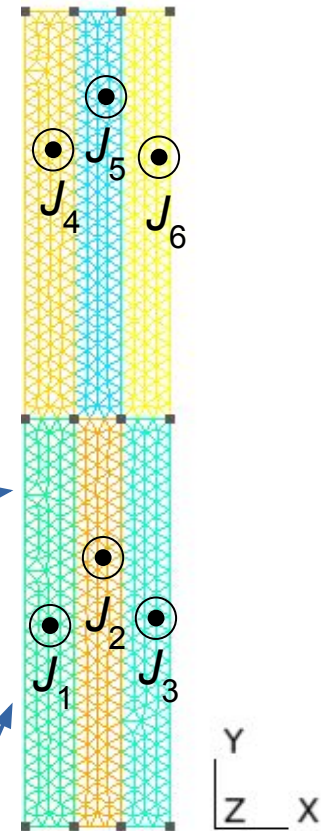
$$\mathbf{B} = \nabla \times \mathbf{A}$$

$$\mathbf{J} = (J_1, \dots, J_m)$$

$$J_k = J_e, \forall k = \{1, \dots, m\}$$

$\mathbf{A} = 0$

$\vdots m = 36$



The solenoid is divided in 36 sub-coils (3x12) having current densities  $J$

# Target field



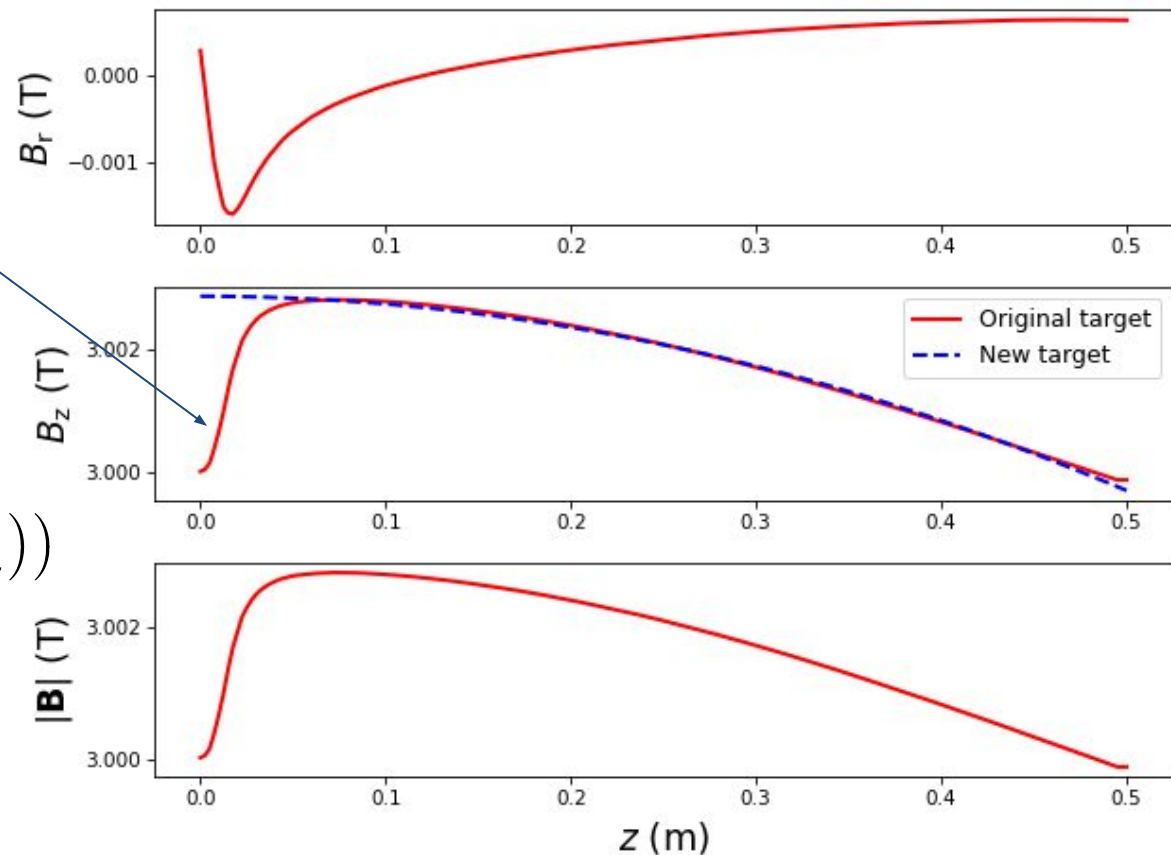
Problematic: providing  $B_r(z)$  and  $B_z(z)$  find the current density in each sub-coil to fit the specifications

To be dealt later

Objective 

$$\mathbf{B}_t = (B_t(z_1), \dots, B_t(z_n))$$

$$\mathbf{z} = (z_1, \dots, z_n)$$



# Inverse problem



Try a different approach based on an inverse problem benefitting from the linearity of the problem

$$\hat{B}_c \mathbf{J} = \mathbf{B}_t$$



$$\mathbf{J}_s = \hat{B}_c^{\dagger} \mathbf{B}_t$$

Singular matrix of computed  $B_z$  field

Vector of current densities

Vector of  $B_z$  target

Pseudo inverse

Computation of the “pseudo inverse” of  $\hat{B}_c$ :

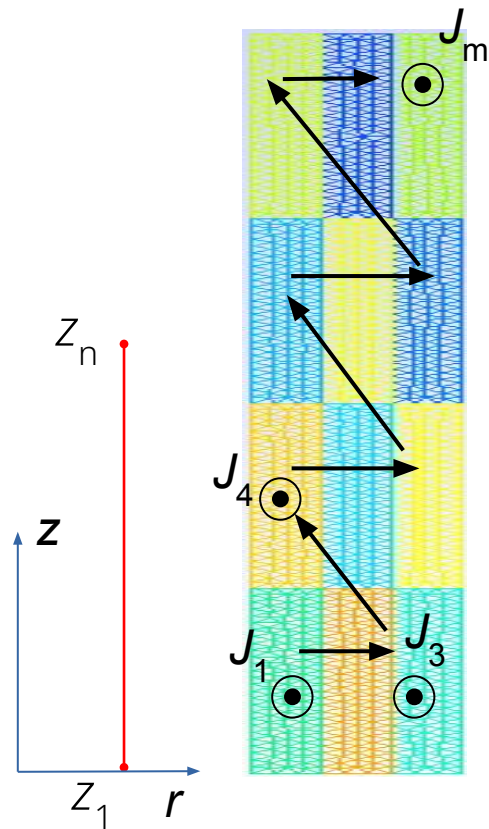
Singular value decomposition and regularization on new target yielding a **good first** solution



# Construction of $B_z$ field matrix



The matrix is built considering the independent contribution of each sub-coil  $k$  to the  $B_z$  field on the line of interest (red line) divided into  $n-1$  segments



$$\hat{B}_c = \begin{pmatrix} J_1 & J_2 & \dots & J_m \\ B_{1,1} & B_{1,2} & \dots & B_{1,m} \\ B_{2,1} & B_{2,2} & \dots & B_{2,m} \\ \cdot & \cdot & \dots & \cdot \\ \cdot & \cdot & \dots & \cdot \\ \cdot & \cdot & \dots & \cdot \\ B_{n,1} & B_{n,2} & \dots & B_{n,m} \end{pmatrix} \begin{matrix} z_1 \\ z_2 \\ \\ \\ z_n \end{matrix}$$

$$\begin{aligned} m &= 36 \text{ (3x12)} \\ n &= 200 \\ J_e &= 1 \text{e6 A/m}^2 \end{aligned}$$

# SVD and regularization



Singular value decomposition (SVD):

$$\hat{B}_c = U \Sigma V^T$$

Regularization, tolerance  $\epsilon = 1e-9$ :

$$\Sigma^\dagger = \left( \Sigma^T \Sigma + \epsilon \lambda_{max} I_{m \times m} \right)^{-1} \Sigma^T$$

Maximum SV

Pseudo-inverse:

$$\hat{B}_c^\dagger = V \Sigma^\dagger U^T$$

Solution:

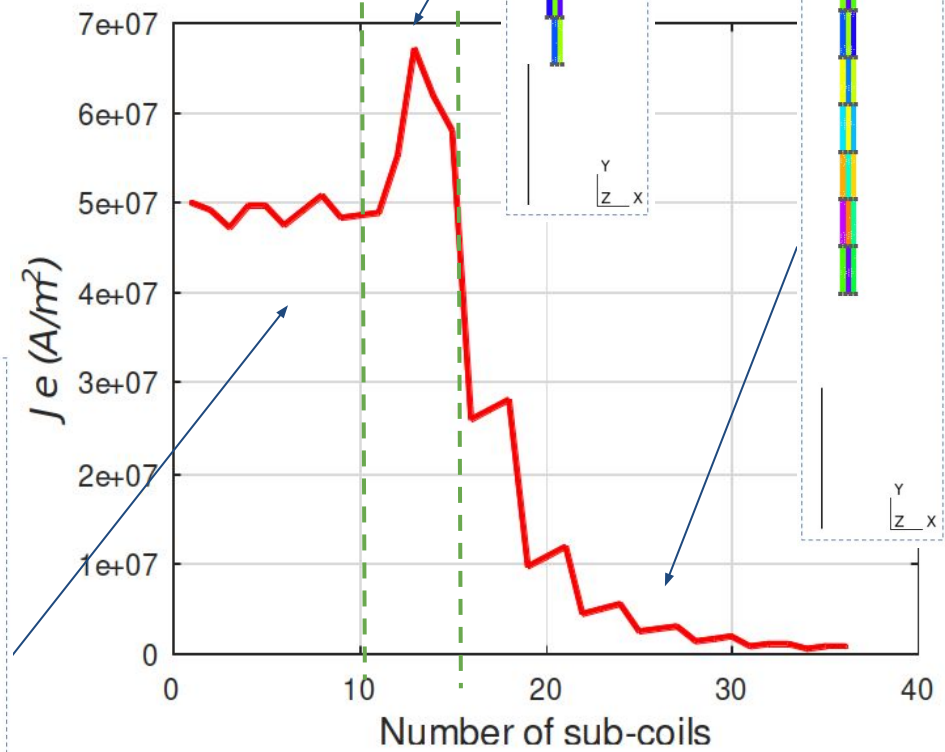
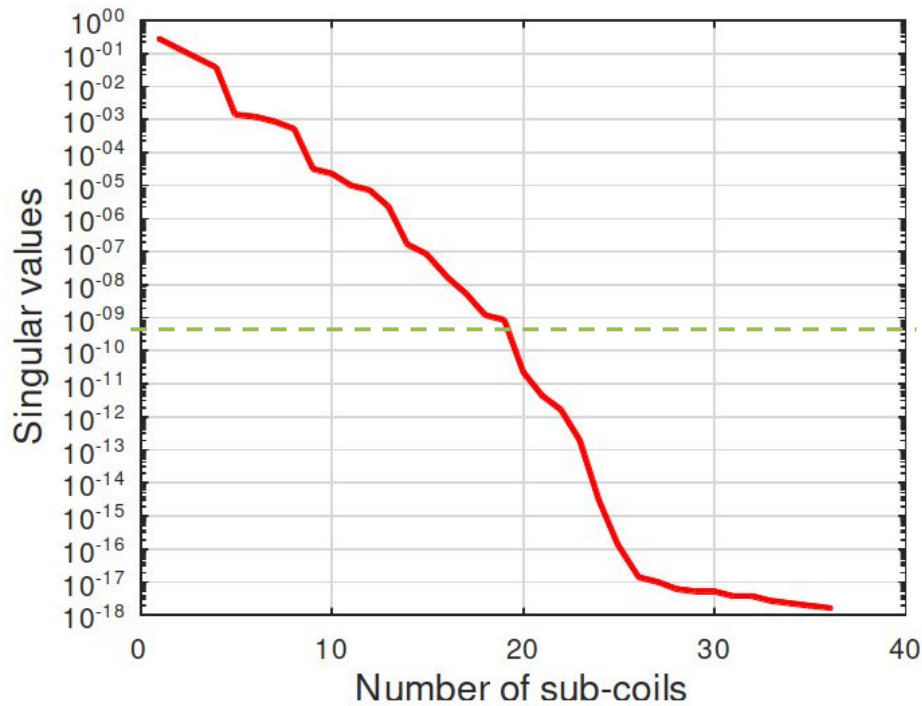
$$\mathbf{J}_s = \hat{B}_c^\dagger \mathbf{B}_t$$

# Results: SVD

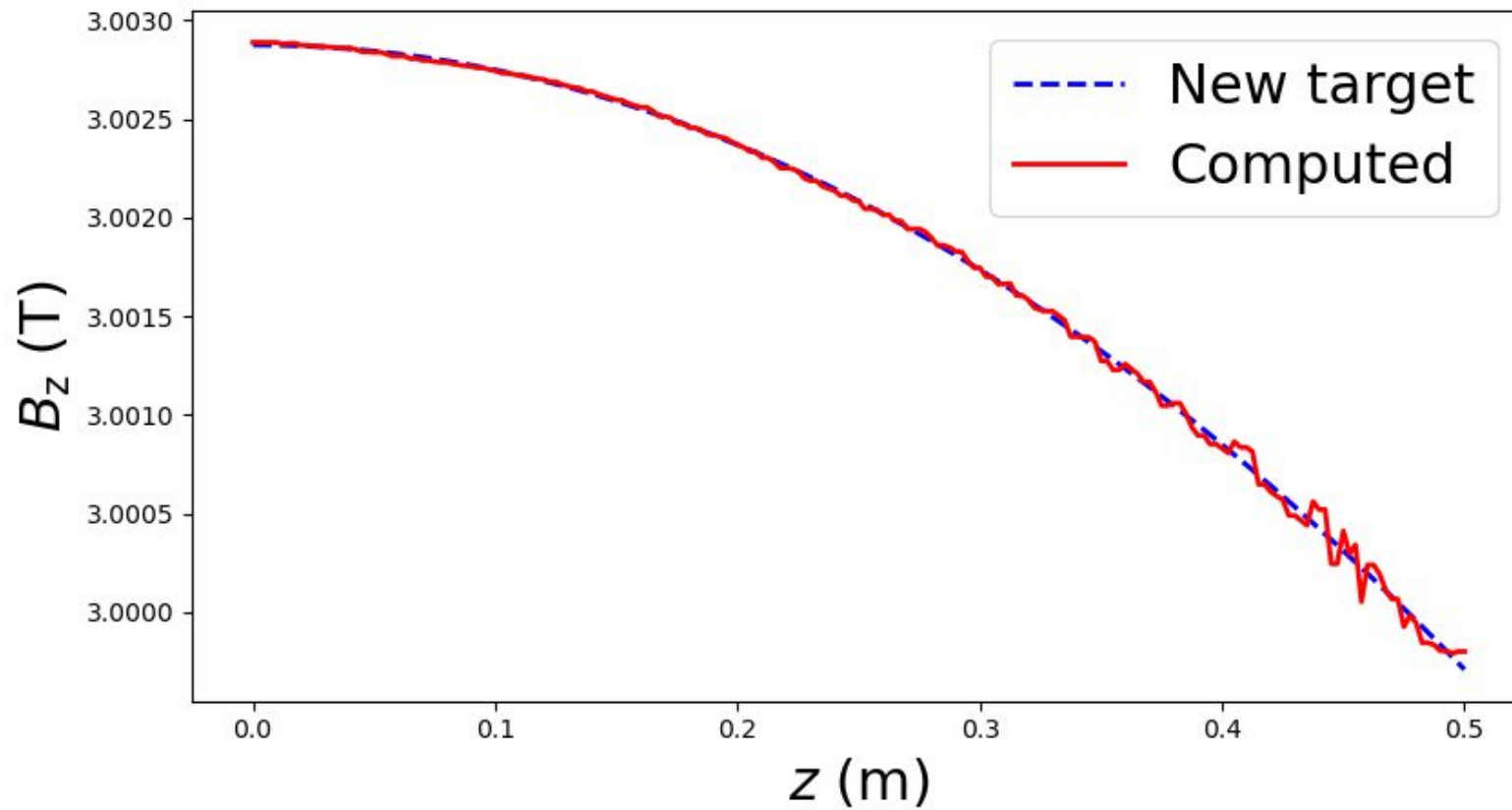


All of the sub-coils

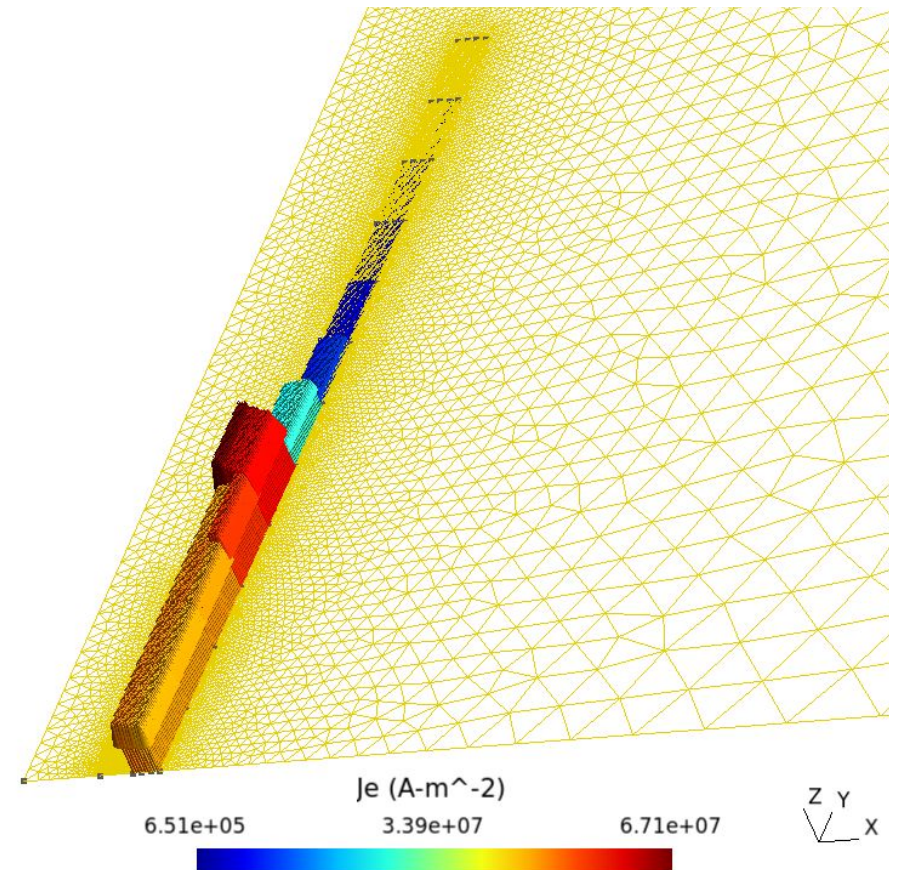
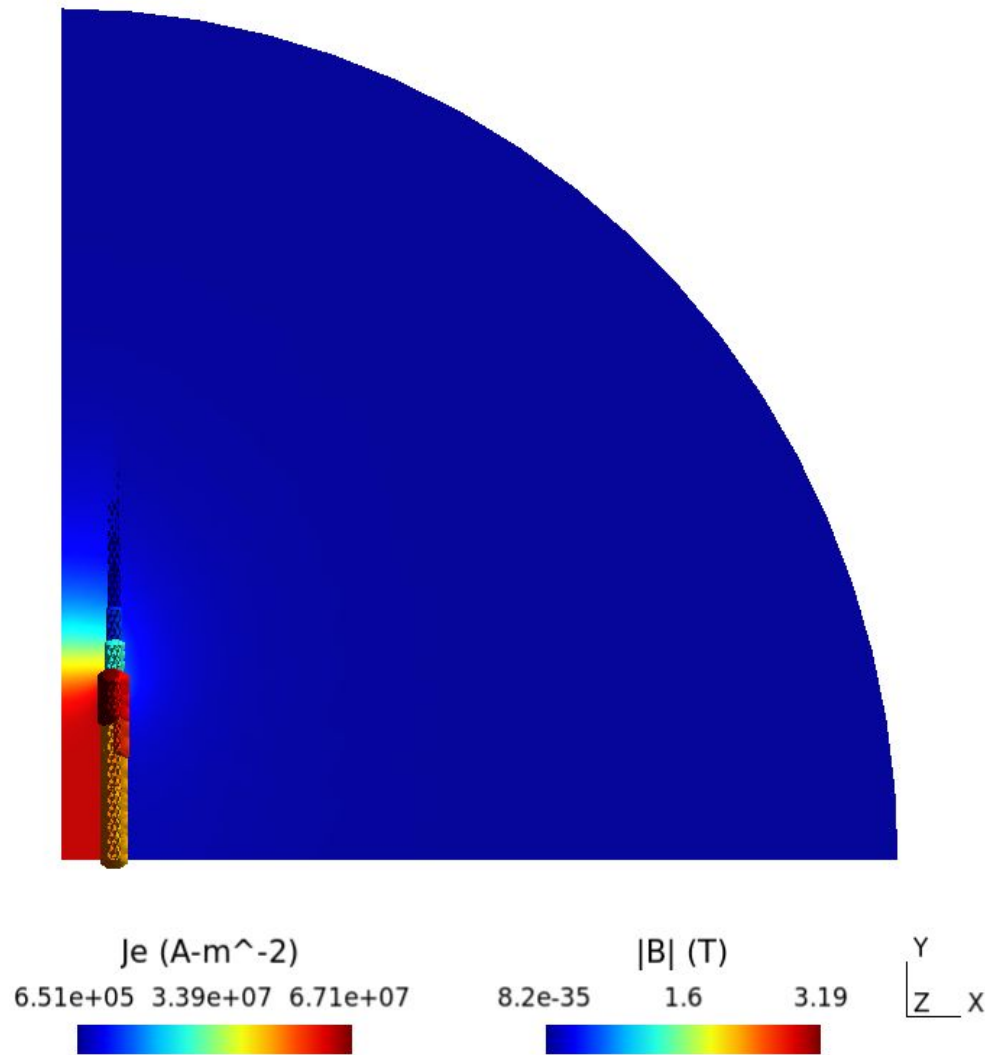
Line of interest



# Results: SVD



# Results: SVD



# Summary



Inverse problem using SVD and regularization -> first **good solution** based on new target (smoother  $B_z$  field)

## Next steps:

- 1) Improve regularization
- 2) Converge on the target fields  $B_z$  and  $B_r$
- 3) Include injection space ( $\sim 100$  mm)
- 4) Optimize blocks for a better current distribution
- 5) Iterate optimization with engineering design