

# Beam dynamics and magnet design challenges for 4<sup>th</sup>-generation storage ring light sources

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# Outline

- What do storage ring light source users want?
- Multi-bend achromat lattices
- Scaling of lattice and magnet properties
- Beam dynamics issues for low-emittance rings
- Example: Advanced Photon Source (APS) upgrade
- Summary of magnet requirements

# What Do SR Users Want?

- No universal agreement!
- Common desire: emittance so small that it might as well be zero
  - Brightness is as high as possible for a given beam current

$$B \propto \frac{N_\gamma}{(\Delta\lambda/\lambda)\Delta t \Sigma_x \Sigma_{x'} \Sigma_y \Sigma_{y'}} \longrightarrow \frac{4\pi^2 N_\gamma}{(\Delta\lambda/\lambda)\Delta t \lambda^2}$$

- Beams are transversely coherent and can be focused tightly
- While not every experiment benefits from brightness
  - It's traditionally the most-emphasized quantity
  - Emittance is well understood and gives a simple goal

# How Close are We to Ultimate Performance?

- Within factors of  $\sim 2$ , we'd like

$$\epsilon_{x,y} \leq \frac{1}{2} \epsilon_r \approx \frac{\lambda}{4\pi}$$

- In more practical terms

$$\begin{aligned} \epsilon_q [pm] &\lesssim \frac{100}{E_p [keV]} \Rightarrow 1 \text{ keV} \rightarrow \epsilon_q \lesssim 100 \text{ pm} \\ \epsilon_q [pm] &\lesssim 8\lambda [\text{\AA}] \Rightarrow 10 \text{ keV} \rightarrow \epsilon_q \lesssim 10 \text{ pm} \end{aligned}$$

- For typical 3rd-generation rings

$$\epsilon_x : [1, 5] \text{ nm} \qquad \epsilon_y : [1, 40] \text{ pm}$$

so we are several orders of magnitude away from DL performance

# Emittance Scaling

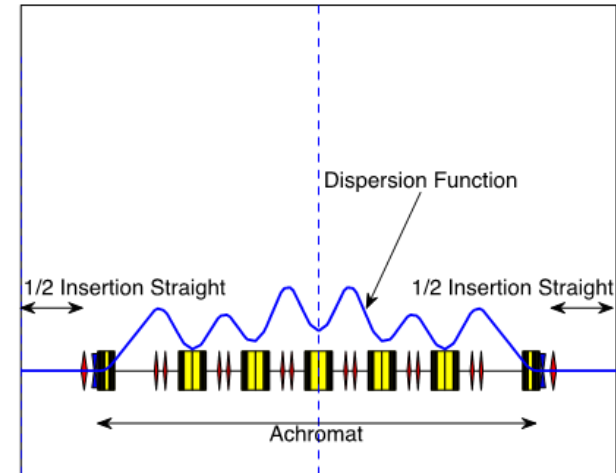
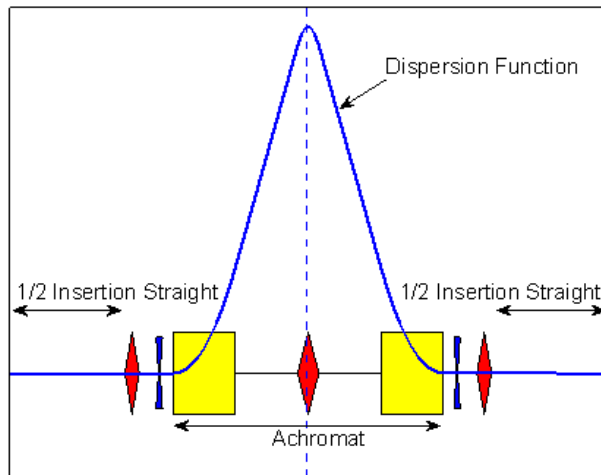
- Emittance is governed by<sup>1</sup>

$$\epsilon_0 = F(\nu, \text{type}) \frac{E^2}{N_d^3} \propto \underbrace{\frac{E^2}{C^3}}_{\text{Fixed cell type}}$$

where  $N_d$  is the number of dipoles in the ring

- Simple explanation
  - Emittance is driven by randomness of photon emission in presence of dispersive (energy-dependent) orbits
  - Breaking up dipoles and putting focusing (quadrupoles) between the parts allows tightly controlling the magnitude of dispersive orbits

# From Double to Multi-Bend Achromats

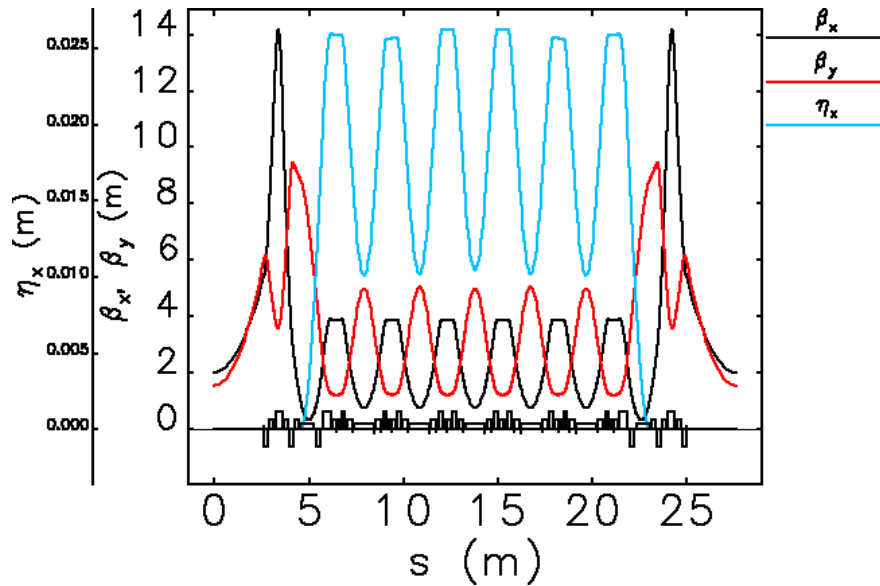


- Rings today have  $N_d = 2N_s$  or (more rarely)  $3N_s$
- Several groups proposed  $N_d/N_s > 3$  lattices in 1990s<sup>1</sup>
- 7BA should have ~40x lower emittance than 2B(A)

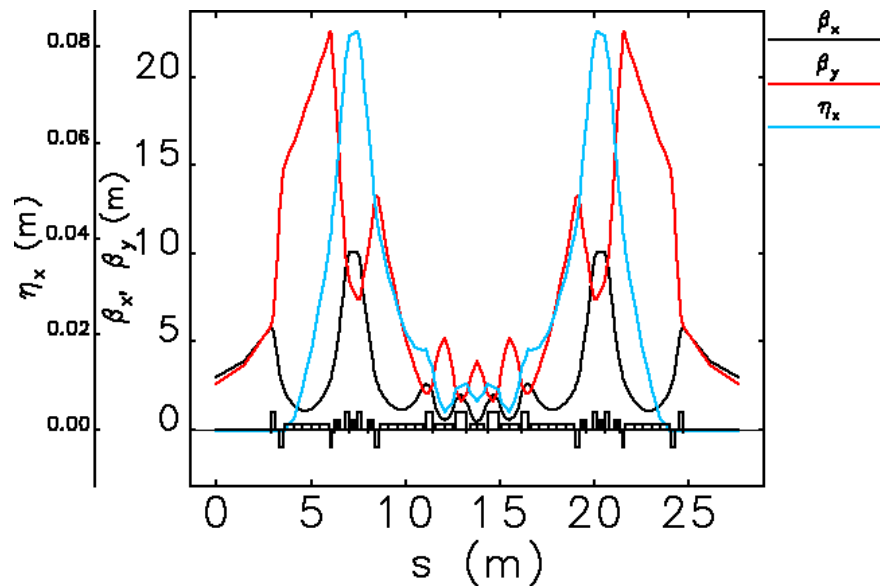
1: Einfeld *et al.*, NIM A 335, 1993; Joho *et al.*, EPAC 94;; Einfeld *et al.*, PAC95; Kaltchev *et al.*, PAC95.

Figures courtesy C. Steier, LBNL.

# MAX-IV<sup>1</sup> vs ESRF<sup>2</sup> Style 7BA Lattices



- “Typical” MAX-IV style lattice
- Small dispersion throughout relatively uniform arcs
- Sextupoles distributed through arcs
- Geometric sextupoles or octupoles outside arcs



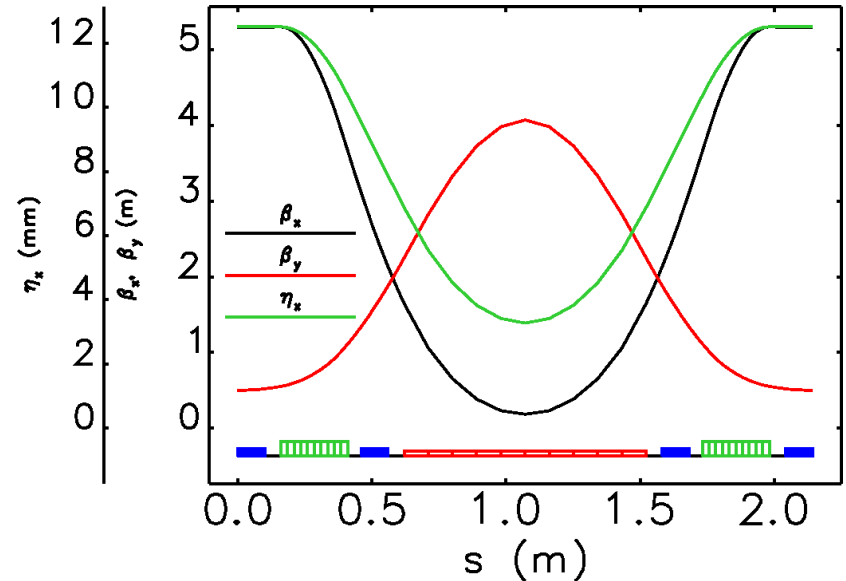
- “Typical” ESRF-style lattice
- Dispersion bump between longitudinal gradient dipoles
- Sextupoles only in dispersion bump
  - Factor of 2 to 4 weaker than in MAX-IV style lattice
- Octupoles possible in dispersion bump

1: S. Leemann *et al.* PRSTAB 12:120701, 2009  
2: L. Farvacque *et al.*, IPAC13, 79.

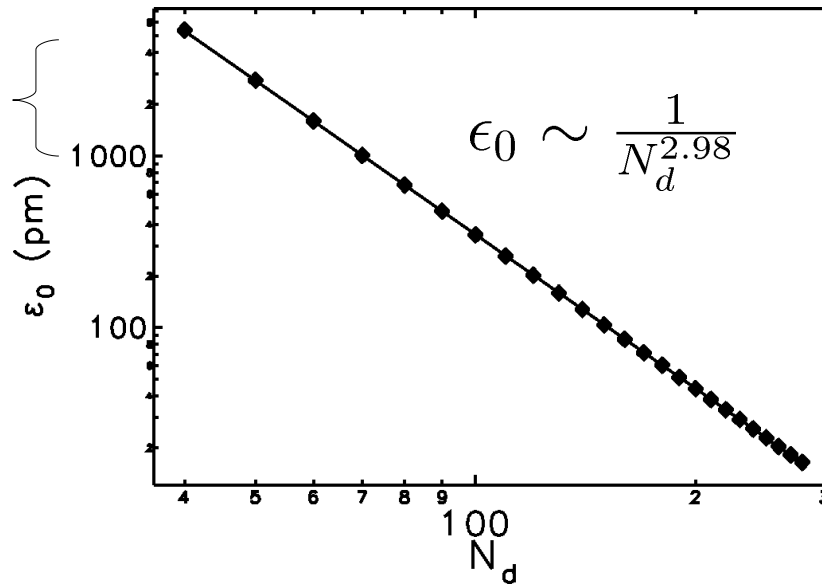


# Model Storage Ring for Understanding Scaling

- We looked at a model storage ring consisting of series of identical cells<sup>1</sup>
  - 600-m circumference, 4.5 GeV
- For fixed circumference, varied number of cells, looked at implications
  - Magnet strength, bore
  - Tolerances
  - Nonlinear dynamics



Present-day rings

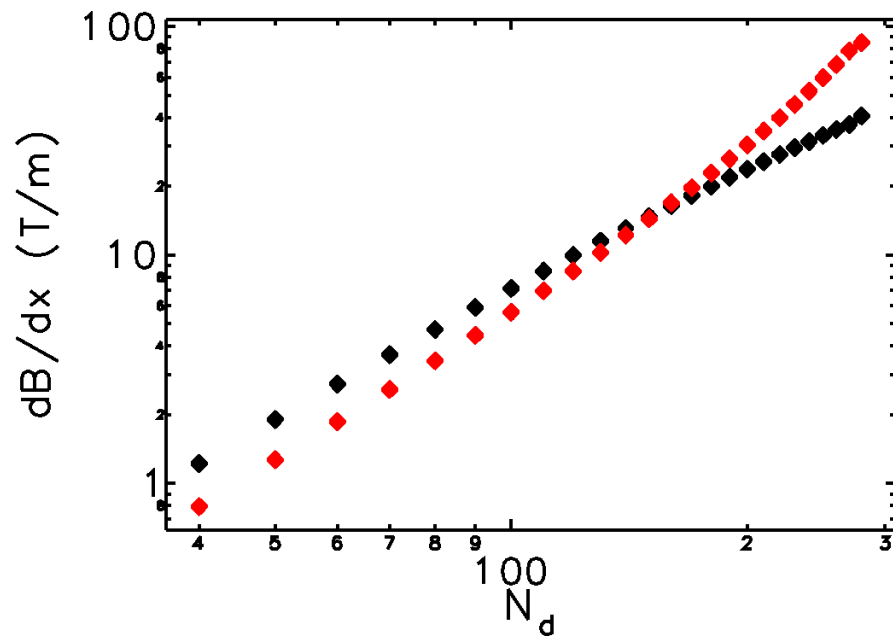


In-construction and next-generation rings and concepts

1: M. Borland *et al.*, J. Synch. Rad., **21**, 912-936 (2014).



# Scaling of Gradients



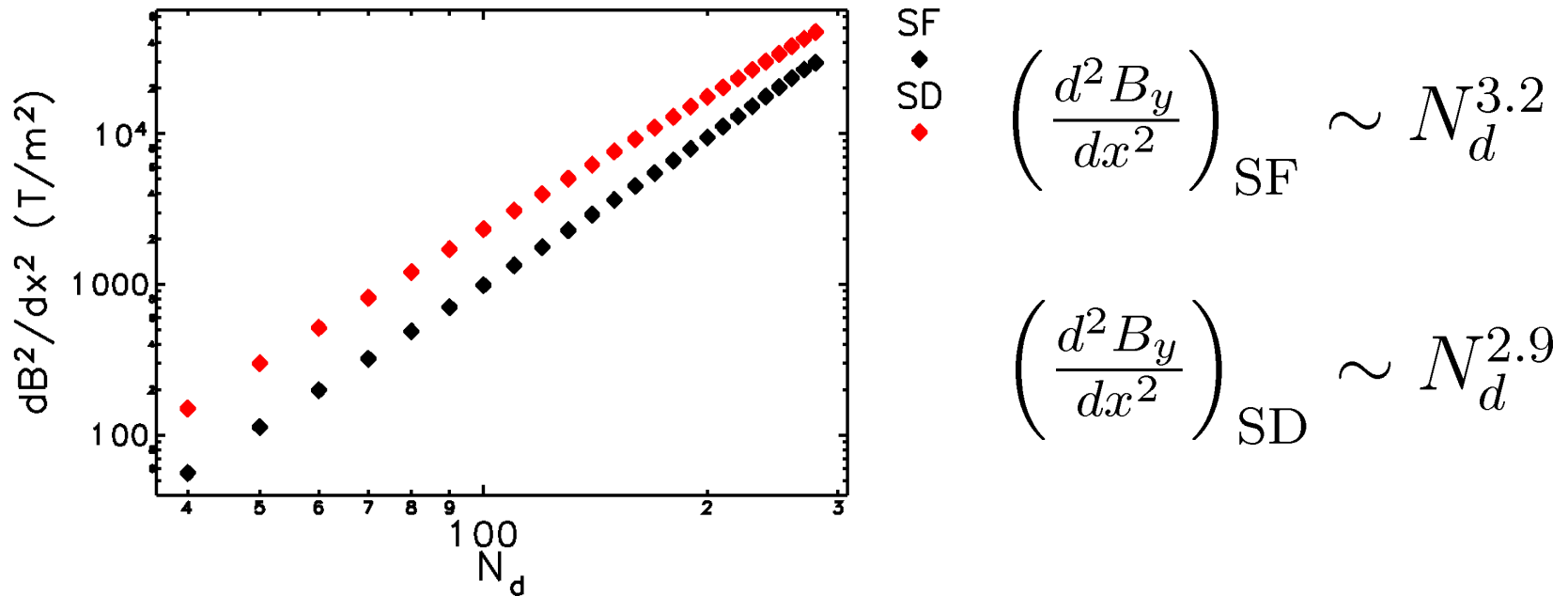
B1  
Q1

$$\left(\frac{dB_y}{dx}\right)_{\text{quads}} \sim N_d^{2.4}$$

$$\left(\frac{dB_y}{dx}\right)_{\text{bends}} \sim N_d^{1.8}$$

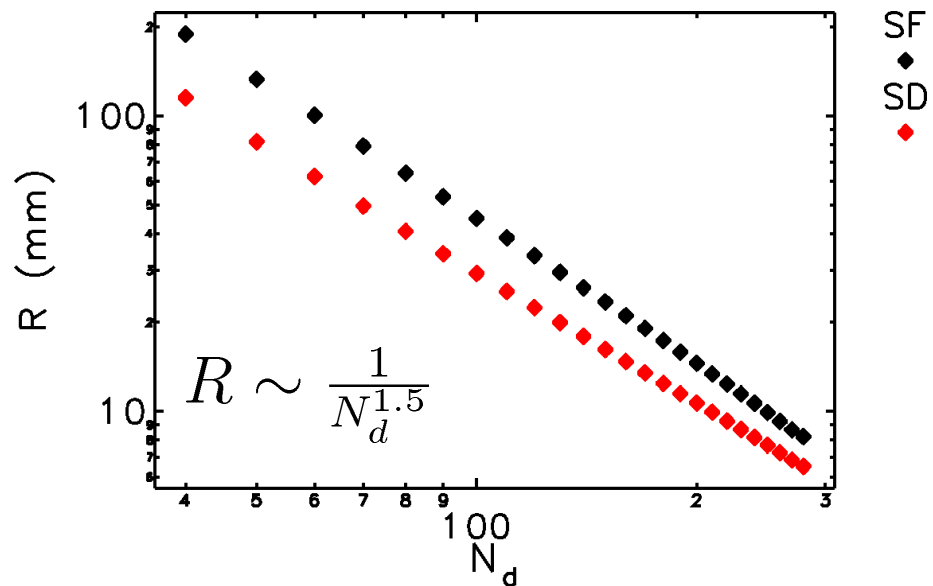
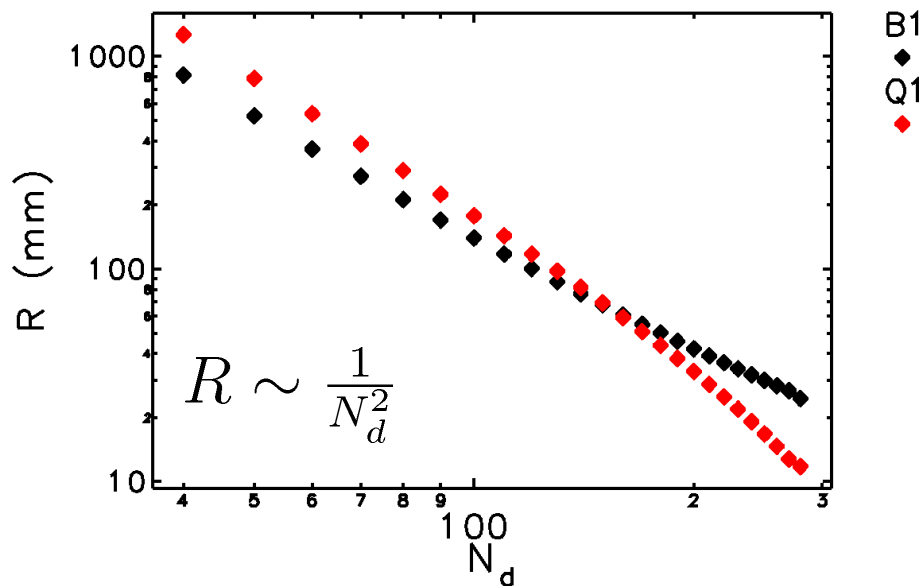
- Explanation:
  - Focal lengths scale like the distance between quadrupoles ( $G \sim N_d$ )
  - Quadrupoles must get shorter due to shrinking cell length ( $G \sim N_d$ )
- If we go from a DBA to a 7BA, expect 10-to-20-fold increase in required gradients
  - In reality, 5-fold increase is being contemplated (e.g., APS upgrade)
    - Keep quadrupoles longer in order to restrain gradients
    - Reduce space between magnets to alleviate pressure lengths

# Scaling of Sextupole Strengths



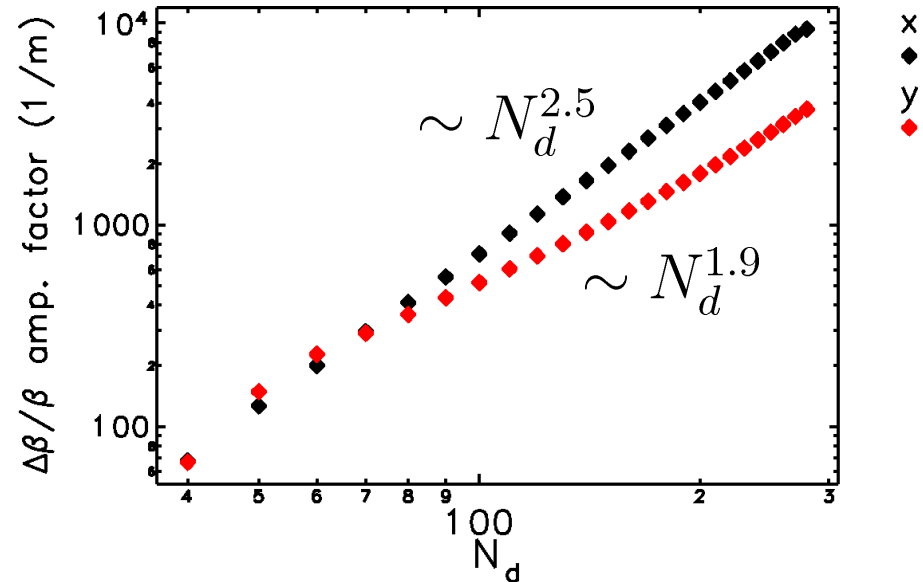
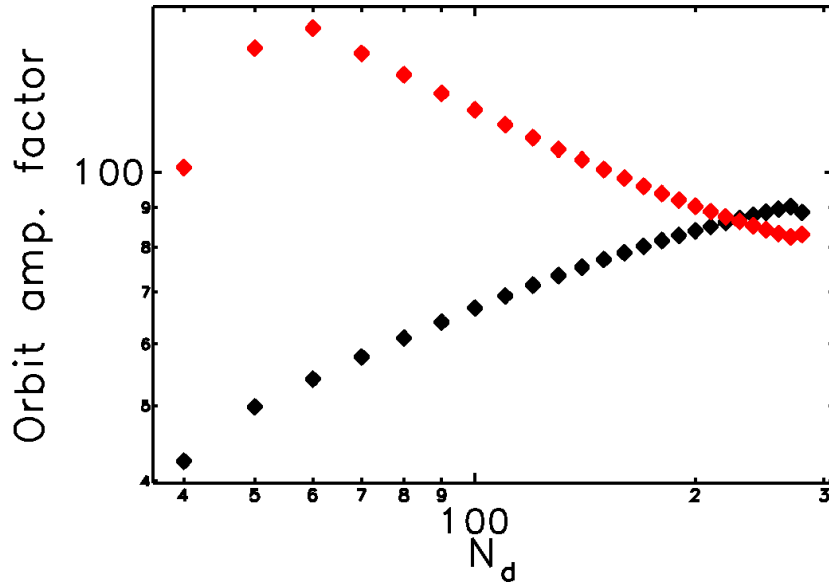
- Explanation:
  - Dispersion scales like  $1/N_d^2$
  - Tune and therefore natural chromaticity scale like  $N_d$
  - Assumed here that sextupole length was fixed
- If we go from a DBA to a 7BA, expect ~50-fold increase in required sextupole strengths
  - This is very close for a MAX-IV-style lattice replacing the existing APS ring

# Scaling of Magnet Bores



- Assumed pole-tip field was fixed at 1 T
- If we go from a DBA to a 7BA, expect
  - 12-fold (6-fold) decrease in quadrupole (sextupole) bore radii
  - E.g., 3-6 mm bore radii for an APS 7BA replacement ring!
- In reality
  - 3<sup>rd</sup> generation ring magnets often have low pole tip fields
  - 4<sup>th</sup> generation ring magnets must be pushed further into saturation
  - 4<sup>th</sup> generation rings must have closer spacing of magnets to maximize length
  - ~12 mm bore radius seems workable for several projects

# Scaling of Alignment Requirements



- Misalignment of magnets creates various issues
  - Misaligned quads/gradient dipoles create orbit errors
  - Misaligned sextupoles create optical errors
- Scaling of orbit amplification factors is weak, partly beneficial
  - Although gradients are stronger, beta functions are smaller
- Scaling of beta-beat factor per unit displacement is very strong
  - Tends to scale with sextupole strength ( $\sim N_d^3$ ) and number ( $\sim \sqrt{N_d}$ )
  - Moderated again by reduction in beta functions
  - Implication is that  $\sim 150 \mu\text{m}$  alignment requirement for 3GSRs becomes 5-15  $\mu\text{m}$ 
    - For APS upgrade, using 30  $\mu\text{m}$  with assumed LOCO-based correction

$$\begin{cases} \beta_x \sim 1/N_d \\ \beta_y \sim 1/N_d^{1.6} \end{cases}$$

# Nonlinear Dynamics Issues

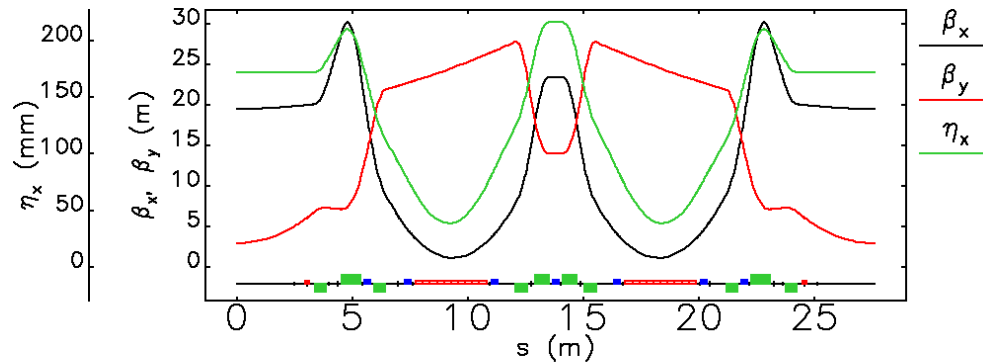
- Focusing elements have chromatic aberrations
  - Sextupole magnets added to correct these
  - Introduces higher-order aberrations that limit dynamic acceptance
  - Scaling analysis indicates that dynamic acceptance decreases like  $1/N_d^2$
  - Indicates that injection efficiency will be a challenge
- Lattices have higher-order chromaticity from sextupoles, gradient dipoles, etc.
  - Scaling study indicates these increase like  $N_d^{1.6}$
  - Momentum acceptance expected to drop precipitously
  - Indicates that Touschek lifetime will be a challenge
- Modern approaches to nonlinear dynamics optimization fight against this
  - Inclusion of many families of sextupoles, as well as octupoles<sup>1,2</sup>
  - Resonant driving term minimization and cancellation schemes<sup>3,2,4</sup>
  - Tracking-based optimization of dynamic and momentum acceptance<sup>5</sup>
- In addition
  - Top-up allows entertaining shorter lifetimes than previously
  - On-axis “swap-out” injection allows working with small DA<sup>6</sup>

1:S.C.Leemann *et al.*, PRSTAB.12.120701; 2:L.Farvacque *et al.*,IPAC13, 79; 3:J.Bengtsson, SLS Note 9/97.

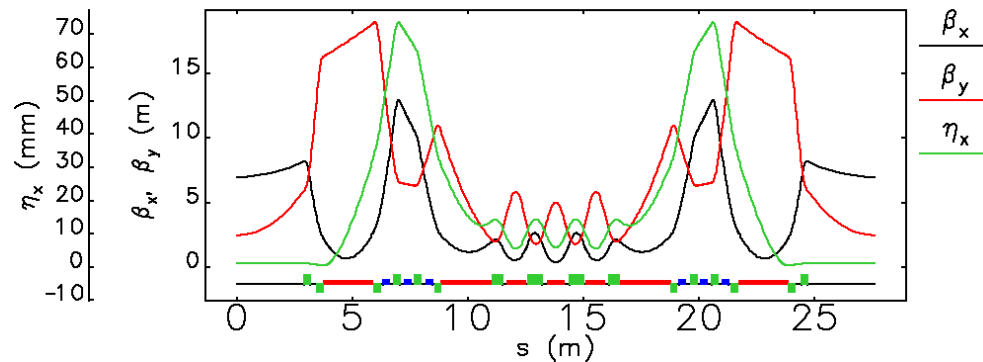
4:Y.Cai *et al.*, PRSTAB.15.054002; 5: See ref. list in M. Borland *et al.*, J. Synch. Rad., **21** (2014); 6: L. Emery *et al.* PAC03, 256.



# APS Upgrade Lattice



APS today:  
7 GeV, 100 mA  
Double-bend sectors  
3100 pm emittance



Proposed upgrade:  
6 GeV, 200 mA  
Hybrid 7-bend sectors  
67 pm emittance

- Upgrade lattice is modeled after ESRF's Hybrid MBA design<sup>1</sup>
- Four longitudinal gradient dipoles (LGDs), three transverse gradient (dipoles)
- LGDs help create dispersion bump that decreases sextupole strength ~3-fold compared to MAX-IV-style lattice
- TGDs help provide requisite phase advance between dispersion bumps to cancel some sextupole kicks

1:L.Farvacque *et al.*, IPAC13, 79;

# Dipole Parameters

Name	Length m	Angle deg	$B_0$ T	$B'$ T/m
<b>M1 (x80)</b>				
M1.1	0.153	0.279	-0.636	-0.000
M1.2	0.203	0.238	-0.410	-0.000
M1.3	0.612	0.423	-0.241	-0.000
M1.4	0.744	0.314	-0.147	-0.000
M1.5	0.388	0.141	-0.127	-0.000
<b>M2 (x80)</b>				
M2.1	0.386	0.127	-0.115	-0.000
M2.2	0.345	0.133	-0.134	-0.000
M2.3	0.557	0.343	-0.215	-0.000
M2.4	0.321	0.243	-0.264	-0.000
M2.5	0.508	0.462	-0.318	-0.000
<b>M3 (x80)</b>				
M3.1	0.390	0.617	-0.553	45.372
M3.2	0.390	0.617	-0.553	45.372
<b>M4 (x40)</b>				
M4.1	0.325	0.562	-0.605	47.215
M4.2	0.325	0.562	-0.605	47.215

Present APS dipoles:  
0.6 T field with no gradient

Two types of 5-segment  
longitudinal-gradient dipole.

Segments have variable length.

Up to 5-to-1 field ratio within magnet.

Curved magnets to preserve GFR.

Want  $\pm 5\%$  variable gradient.

# Quadrupole Parameters

Element Name	Length m	$K_1$ $1/m^2$	$B'$ T/m	
Q1	0.238	3.601	-72.1	} Vanadium permendur pole tips with mushroom poles req'd
Q2	0.238	-2.787	55.8	
Q3	0.238	-2.256	45.1	} All carbon steel construction with mushroom poles. Could use VP tips to reduce lengths.
Q4	0.238	3.203	-64.1	
Q5	0.238	1.693	-33.9	
Q6	0.238	-2.444	48.9	
Q7	0.438	3.562	-71.3	} Vanadium permendur pole tips required. Include steering windings.
Q8	0.592	4.086	-81.8	

In contrast, present APS quadrupoles are 0.5-0.8 m in length with gradients of less than 21 T/m



# Sextupole Parameters

Element Name	Length m	$K_2$ $1/m^3$	$B''$ $T/m^2$
S01A:S1	0.256	-165.1	3305.2
S01A:S2	0.256	227.1	-4545.4
S01A:S3	0.256	-151.3	3028.4
S01B:S3	0.256	-155.9	3121.1
S01B:S2	0.256	230.7	-4616.7
S01B:S1	0.256	-153.0	3061.5
S02A:S1	0.256	-157.5	3151.3
S02A:S2	0.256	227.5	-4553.2
S02A:S3	0.256	-155.9	3120.5
S02B:S3	0.256	-152.3	3048.2
S02B:S2	0.256	233.1	-4665.7
S02B:S1	0.256	-157.0	3142.4

Sextupole pattern repeats every two sectors, giving more knobs for nonlinear dynamics optimization.

Optimization is entirely tracking-based, emphasizing DA and Touschek lifetime

Two groups of magnets:

- S1/S3:  $< 3310 T/m^2$
- S2:  $< 4700 T/m^2$

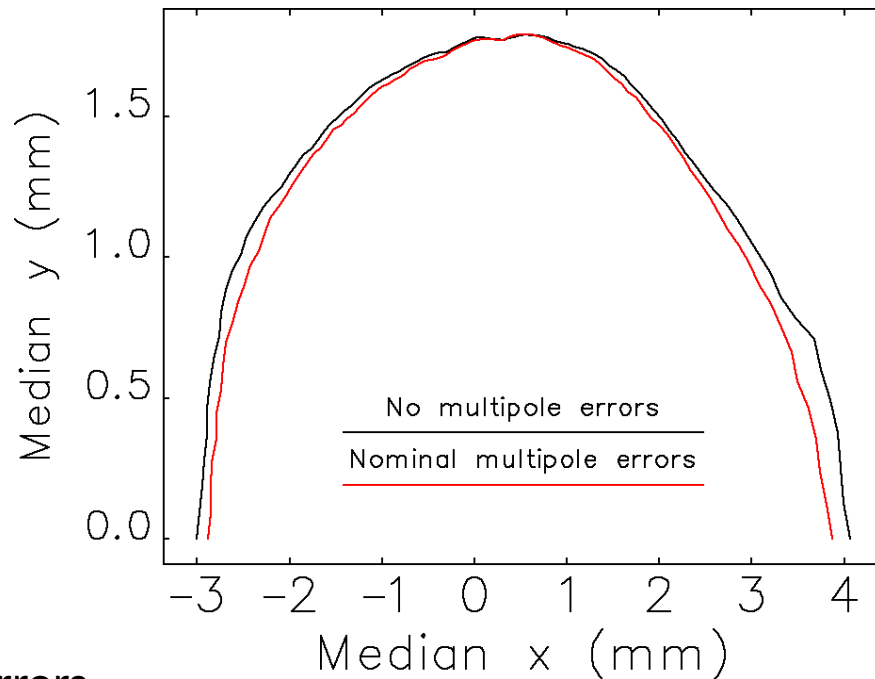
S1/S3 magnets will also include steering windings.

Present APS sextupoles are 0.25 m in length with strength of less than  $500 T/m^2$



# Dynamic Acceptance

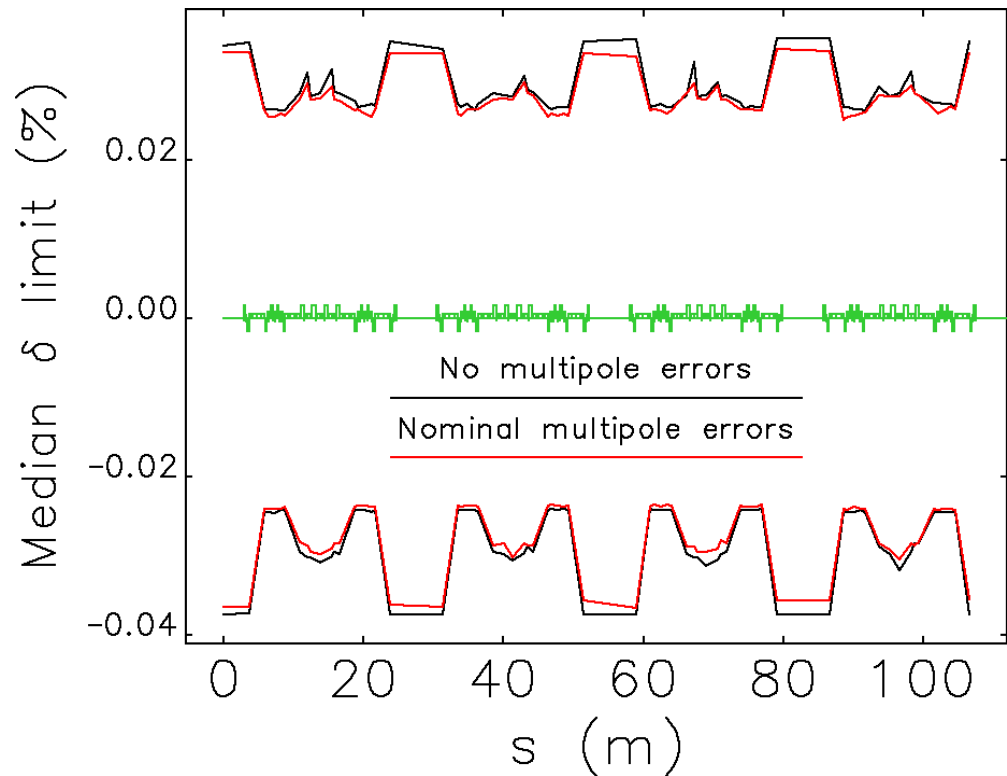
- DA was evaluated by 6D tracking with **elegant** for 1000 turns
- Included 100 ensembles of random errors and “commissioning” simulation<sup>1</sup>
- Included nominal multipole errors from
  - 3D magnet designs<sup>2</sup>
  - Scaling of NSLS-II measured results<sup>3</sup>
  - Estimates from Halbach's method<sup>4</sup>
  - See backup slide for more detail
- DA is only adequate for on-axis injection
- Relatively insensitive to most multipole errors
  - DA is very small, dominated by strong sextupoles
  - Most harmful error is unallowed multiples in quadrupoles
  - If attempting to achieve larger DA, better magnet quality would be needed
- Also developed<sup>5</sup> a higher-emittance lattice with DA sufficient for accumulation
  - Same errors have much greater impact on DA



1: V. Sajaev (ANL); 2: M. Jaski (ANL), V. Kashikin (FNAL); 3: A. Jain (BNL);  
4: K. Halbach, NIM **74-1**, 147 (1969); 5: Y.P.Sun (ANL).

# Local Momentum Acceptance

- LMA evaluated in same way as DA
- Also relatively insensitive to most multipole errors
  - Most harmful error is again unallowed multipoles in quadrupoles
- Earlier, we tried putting steering coils on all quadrupoles
  - Made LMA significantly worse
- Higher-emittance variant has similar but larger LMA compared to nominal design
  - Seems no more sensitive to errors than the nominal design
- This LMA is sufficient to get workable Touschek lifetime provided a bunch-lengthening cavity is used
  - Further improvement possible using octupoles<sup>1,2</sup>



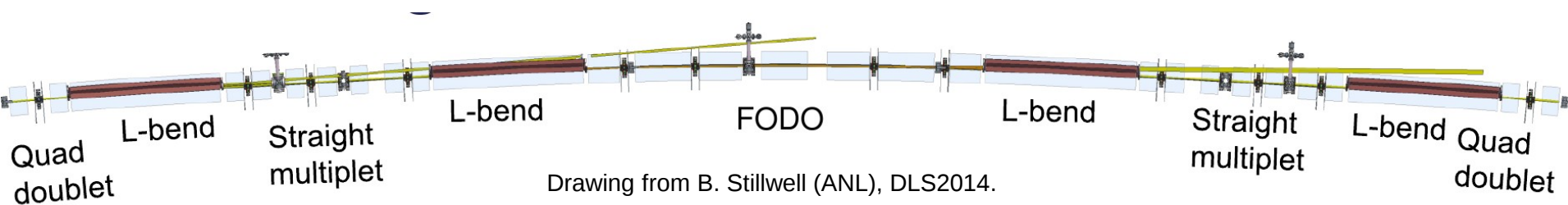
1: P. Raimondi (ESRF); 2: Y.P.Sun (ANL)

# “Magnet-Aware” Accelerator Design

- All accelerator design relies on a model of the magnet capabilities
  - Typically, just the maximum strength of the main components
  - First pass might just use estimates from hand calculations
- To quickly converge on a design, more is needed
- For APS, benefited from curves of maximum  $B_n L$  vs  $L$ 
  - This non-linear function was obtained from 3D magnet models
  - We derated the  $B_n L(L)$  curves to allow explicit overhead for lattice flexibility and evolution
- Similarly, tracking-based optimization could benefit from
  - Early knowledge of magnet quality
  - Early inclusion of end effects
  - Typically, these are put in only after optimization as a check
- An open repository of magnet design information in a standardized format could be very useful jump-starting future accelerator designs

# Other Magnet-Related Issues

- To save space, combining functions on many magnets
  - Strong gradient dipoles with  $\pm 5\%$  gradient variation
  - Some quads (with low beta) have steering windings
  - Use eight-pole magnets for H/V steering plus skew quads<sup>1</sup>
- Need space between poles and between coils to extract photons
  - Particular problem for large rings since photon beams pass through many magnets
  - Limits K of undulator magnets, limits use of helical and vertically-deflecting devices



- For APS upgrade, this has a significant impact on the magnets
  - Limits field quality in the sextupoles
  - Limits field quality and strength in the eight-poles

1: A. Jain, C. Spataro (BNL)

# Summary of Requirements for Magnets

- Significantly larger gradients and sextupole strengths
- Very strong, curved combined-function dipoles
  - Measurement and alignment not simple!
- Smaller bore diameters, e.g., 25 mm instead of 80 mm
  - Limited by vacuum system and impedance constraints
- Accommodation of photon channel imposes constraints on magnet quality, strength
- Closer spacing, e.g., as little as 50 mm instead of typ. >150 mm
- Combined functions on steering, skew quads, etc.
- Tighter alignment, e.g., 30  $\mu\text{m}$  instead of 150  $\mu\text{m}$
- Early knowledge of detailed magnet properties can aid convergence of the design
- Field quality requirements not terribly difficult if swap-out is used
  - Will be somewhat harder with accumulation



# Backup Slides



# Tables of multipole errors used in simulations

Order	P1 $10^{-4}$	P2 $10^{-4}$	P3 $10^{-4}$	P4 $10^{-4}$	P5 $10^{-4}$
1	-3.5	-0.2	1.2	0.6	1.8
2	-7.5	11.5	3.0	1.3	-2.7
3	0.3	0.1	0.1	-0.0	-0.1
4	-2.0	-0.2	-0.5	-0.3	-0.2
5	-0.0	-0.0	-0.0	-0.0	-0.0
6	0.4	-0.1	-0.1	-0.0	-0.0
7	0.0	0.0	-0.0	0.0	-0.0
8	-0.1	-0.0	-0.0	0.0	0.0

M1 and M2 dipoles  
systematic normal  
multipole errors from  
3D models

Order	Normal $10^{-4}$
2	-8.0
3	-11.0
4	-11.0
5	-1.0
6	8.0
7	11.0
8	-5.0

M3 and M4 dipoles  
systematic multipole errors  
from 3D models

Reference radius: 10 mm





# Tables of multipole errors used in simulations

Quadrupole systematic normal multipole errors (from 3D models)

Order	Q1-Q6 $10^{-4}$	Q7-Q8 $10^{-4}$
5	4.9	12.5
9	-4.2	-4.2
13	-2.5	-2.7
17	0.0	-0.1

Quadrupole random multiple errors (scaled from NSLS-II)

Order	Normal $10^{-4}$	Skew $10^{-4}$
2	10.5	16.5
3	12.5	3.5
4	3.0	3.0
5	5.5	2.0
6	1.5	2.0
7	2.0	1.0
8	0.5	0.5
9	1.0	0.5
10	0.5	0.5
11	0.5	0.5
12	0.5	0.5
13	0.5	0.5
14	0.5	0.5
15	0.5	0.5
16	0.5	0.5
17	0.5	0.5
18	0.5	0.5
19	0.5	0.5

Reference radius: 10 mm

# Tables of multipole errors used in simulations

Sextupole systematic  
normal multipole errors  
(from 3D models)

Order	Normal $10^{-4}$
8	-302.5
14	-13.2

These are large because the pole tips must be truncated to make room for the photon channel.

Sextupole random multiple  
errors (from Halbach theory)

Order	Normal $10^{-4}$	Skew $10^{-4}$
1	0.0	0.0
2	0.0	0.0
3	8.9	8.9
4	9.1	5.5
5	4.5	0.9
6	2.6	1.8
7	0.7	0.7
8	0.8	0.3

Reference radius: 10 mm



# Design Your Own Ring

- A free Android app is available that lets you explore storage ring scaling
- Also synchrotron radiation calculations, FELs, top-up/swap-out, magnets, etc.
- Search for “Michael Borland TAPAs” on the Google Play store

## Ring scaling

TAPAs: Toolkit for Accelerator Physics on Androids

**Storage Ring Scaling**

Reference Ring: ESRF\_II

Energy (GeV): 6

Cells: 40

Circumference (m): 1055

Emittance (nm): 0.0727

Energy spread (%): 0.0929

Mom. compaction: 5.6294E-5

En. Loss/Turn (MeV): 2.3688

Horizontal Damping Time (ms): 12.761

Longitudinal Damping Time (ms): 11.123

Overvoltage: 1.5

Rf Freq. (MHz): 351.794371

Harmonic Number: 1238

Rms Duration (ps): 13.24

Bucket HH (%): 3.1604

## Magnet estimation

TAPAs: Toolkit for Accelerator Physics on Androids

**Iron-Dominated Multipole Magnets**

Type: Octupole

n: 3

Kn (1/m^(n+1)): 9000

Beam Energy (GeV): 6

Half gap (mm): 26

Bn (T/m^n): 1.8012E5

BTip (T): 0.5276

NI (kAmp\*Turns): 2.7293

## Undulator estimation

TAPAs: Toolkit for Accelerator Physics on Androids

**Hybrid Permanent Magnet Undulator**

Magnet Type: DejusNdFeB

Enter any two quantities, then press Compute to determine the third.

Period (mm): Compute 23

Full mag. gap (mm): Compute 10.5

B (T): Compute 0.5368

K: 1.1527

Energy (GeV): 6

Ph. Energy (keV): 8.9304

Wavelength (A): 1.3883

## FEL estimation

TAPAs: Toolkit for Accelerator Physics on Androids

**Ming Xie FEL Parametrization**

Beam Energy (GeV): 6

Peak Current (kA): 3

Norm. Emit. (um): 0.2

Frac. Energy Spread (%): 0.01

Beta (m): 4.3

Undulator Period (mm): 23

Undulator K: 1.1527

Pierce Param.: 0.001094

Rad. wavelength (A): 1.388

Photon Energy (keV): 8.931

Gain Length (m): 1.397

Startup Power (kW): 2.486

Saturation Power (GW): 15.048

Saturation length (m): 24.893

Eta Emittance: 0.346

Eta Energy Spread: 0.053

M. Borland, PAC13, 1364-1366 (2013).