





#### Wir schaffen Wissen – heute für morgen

# Paul Scherrer InstitutOxana ActisParametrization of an upstream scanning system

EuCARD<sup>2</sup> Superconductivity and other new Developments in Gantry Design for Particle Therapy





- Sweeper magnets are last active beam elements
- In first order linear correlation between
  - Spot position at isocenter
  - Sweeper current
- Spot shape unaffected for different scan position
- Divergent scanned beam; calibration relies on exact longitudinal alignment at isocenter
- Situation similar to horizontal beam line



Example:

Horizontal beam line, PSI test area, 170 MeV

Spot position with linear current steps





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Example:

Horizontal beam line, PSI test area, 170 MeV

Spot position with linear current steps



- Sweeper magnets placed in-front of last dipole
- Large gap of last dipole
- Field inhomogeneity can affect spot shape
- Beam focus depends on lateral position
- Beam with little / no divergence (= parallel beam)
- Higher order corrections for position-to-current conversion needed



Example: Gantry 2, 100 MeV Spot position with linear current steps



## Gantry size and room volume







**Downstream scanning** 





- (corresponding range 4.3 33 cm)
- Dose down to 5e05 protons per spot



#### Last bending magnet: most challenging element

- Large aperture to accommodate deflected beam => large and heavy
- Special lamination to limit eddy currents effect for fast energy changes => works to a certain level

The GOAL: Parallel beam at isocenter with minimal beam shape and position distortions



- Sweeper current correction
- Magnet current correction
- SC magnet ?

Dose field homogeneity depends on:

## Beam shape

Position



Beam phase space has to be verified @ ISO for

- Full scan area
- all Gantry angles
- beam energies





#### Full scan area @ iso-center

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٠	٠	٠	۰	۰
٠	•	٠	٠	٠



### **Beam phase space measurement**



#### Full scan area @ iso-center









Regular grid 4mm spacing Sigma ~ 5 mm nr Regular grid 4mm spacing Spot size 10% changed sigma + rotation Vertical line of deformed spots 



- Regular grid 4mm spacing
- Sigma ~ 5 mm





- Regular grid 4mm spacing
- Spot size 10% changed
- sigma + rotation









**Dynamic beam focusing correction** 



 $\Rightarrow$  Spot shape is changing with position



## **Dynamic beam focusing correction**

#### Static corrections



Quadrupole corrector in series with U-sweeper ⇒ Invariant spot shape



#### 20x12 cm @ iso-center: beam optics optimized for isocenter



#### 20x12 cm 40 cm above iso-center





#### Beam sigma at isocenter in cm





#### Beam sigma at isocenter in cm





#### Beam sigma at isocenter in cm







## **Challenge: scanning though the last bending magnet**

#### Last bending magnet: most challenging element

- o Large aperture to accommodate deflected beam
- o Special lamination to limit eddy currents effect for fast energy changes

The GOAL: Parallel beam at isocenter with minimal beam shape and position distortions



Dose field homogeneity depends on:

Beam shape





## First measurements & beam transport calculation



Tracking predictionsMeasurements

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## First measurements & beam transport calculation





## Beam transport calculation vs measurements





## Beam transport calculation vs measurements





## Detector for beam position measurements @ ISO

Rotation for all gantry angles controlled remotely • Collimator for device calibration

- Alignment at isocenter < 0.2 mm
  - Room lasers (a)  $\alpha = 0^{\circ}$
  - Nozzle lasers for differentgantry angles

- Automatized parallel readout of all channels
- Data logged in a common log file
- Automatized on-line analysis procedure as for the nozzle chamber

- 2D spot position reconstruction
- Ionization strip chamber identical to nozzle:
  - o 20x12 cm scan area
  - o 2mm strip size









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**Current to position parametrization** 



$$I_{\text{USweeper}}(U,T) = \overbrace{g_1U + g_2T + g_3U^2 + g_4T^2 + g_5U^3 + g_6U^4 + g_6U^5 + g_6U^6 + g_6U^7}^{\text{global function}} + \sum_{q=1}^{4} \underbrace{l_1^q UT + l_2^q U^2T + l_3^q UT^2 + l_4^q U^3T + l_5^q U^2T^2 + l_6^q UT^3 + l_7^q U^4T + l_8^q U^3T^2 + l_9^q U^2T^3 + l_{10}^q UT^3}_{\text{local function for each quadrant}}$$

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## **Current to position parametrization**





- Possible averaging over all gantry angles
- 2 years of operation using average sweeper magnet map in combination with patient specific correction for the lateral position deviations
- Angular dependent calibration performed using same calibration procedure with improved position reconstruction and detector alignment at the isocenter
- Angular dependent maps computed to 8 gantry angles



Angular dependent maps: Gantry @ 90

#### Averaged maps: Gantry @ 90

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## **Nozzle back projection**

## Relevant for downstream scanning as well as upstream scanning (deviation from perfect orthogonality)





First approximation:

- Distance from the source to the nozzle position monitor and to isocenter are known
- Nozzle position monitor would give information about the beam angle
- Linear projection from the source to isocenter

Beam in the nozzle @ any location is identical to isocenter

#### Reality

- The actual position of the nozzle monitor should be translated to isocenter
- Even minimal beam deviation from parallel is giving significant spot displacement at isocenter: beam angle over all scan area in both directions transverse to ISO should be calculated



On-line position verification: spot position measurement and its propagation to the isocenter

Position measurement of two orthogonal profiles

- Measurement with position monitor in nozzle
- Cross check position at iso-center (monitor position correction)

Position monitor  $\rightarrow$  iso-center projection

- Beam angles for full scan range (per position and energy)
  - $\circ$  Projection error should be < 0.2 mm
  - Distance monitor iso-center ~ 70 cm

Measuring beam angel with precision < 0.5 mrad

- Projection calculation off-line: interpolation from LUT
- On-line correction calculation at ISO using position measured in the nozzle











## Conclusions

• For conventional UP-stream scanning system it is feasible to achieve required spot position precision, beam shape translation to the isocenter and homogeneous dose field distribution

#### Benefits of UP-stream system:

- Smaller room volume respect to down-stream systems
- Parallel beam scanning
  - Low skin dose
  - Easily performed field patching and QA

#### Challenge:

- Maintenance of the symmetric spot shape
- Current-to-position calibration
- Back projection
- Limited field size

What does it mean for superconducting gantry?

## Current to position parametrization



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