

# **DEAP V1720 Frontends and Event Builder**

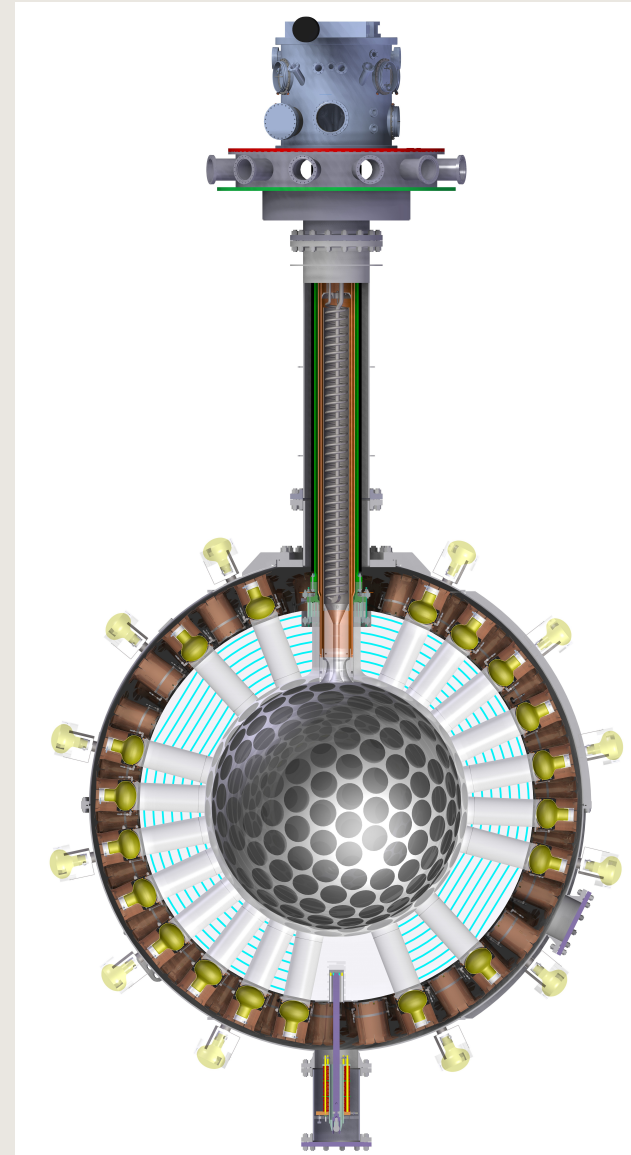
**Thomas Lindner | TRIUMF  
MIDAS Seminar – July 2015**

# Outline

- DEAP Detector
- DTM
- V1720 Digitizers
- Event Builder

# DEAP Introduction

- DEAP-3600 is liquid argon dark matter experiment in SNOLAB, Sudbury, Ontario.
- Liquid argon vessel is imaged by array of 255 PMTs.
- From DAQ point of view, main challenges is  $\sim 3.6\text{kHz}$  rate of Ar-39 decays which produce signal similar to WIMP.
  - Can suppress Ar39 background offline using pulse shape discrimination.
  - But how to handle high rate online?

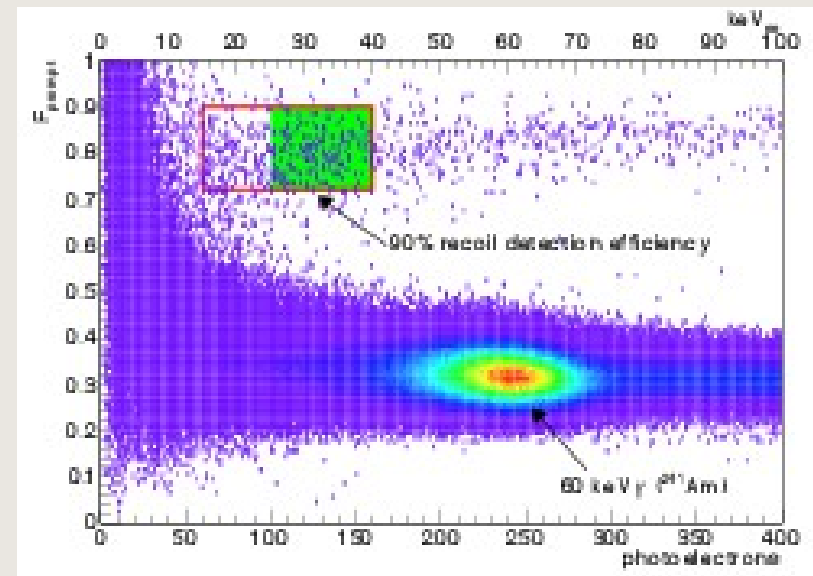


DEAP Multi-threaded frontends

# DEAP Trigger Module (DTM)

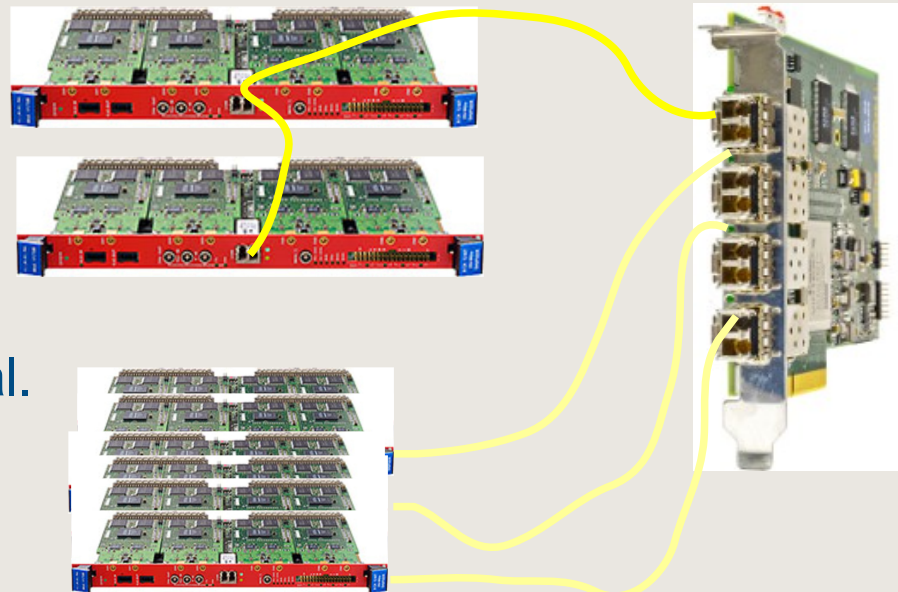
- Summed signals from PMTs fed into DTM digitizer.
- Digitized signal are processed to determine whether events are WIMP-like or background-like.
- DTM has flexible system for deciding, event-to-event, which digitizers to trigger.
- Also, DTM gets busy signals from digitizers; can be used to 'throttle' rate of digitizer triggers.

Pulse shape discrimination in liquid argon  
electrons vs neutrons



# V1720 Digitizers

- Use CAEN V1720 250MHz FADC digitizers: one channel per PMT.
- V1720 FADC signals are processed on-board using Zero Length Encoding algorithm; only save sample below certain threshold (and neighbouring samples).
- Connections to V1720 made using fibre link with CAEN A3818 PCI card. 4 fibres per A3818, 2 V1720 per fibre.
- Each A3818 card can handle up to ~80MB/s.
- V1720 buffers handle 1028 events; when half full V1720 sets 'busy' signal.

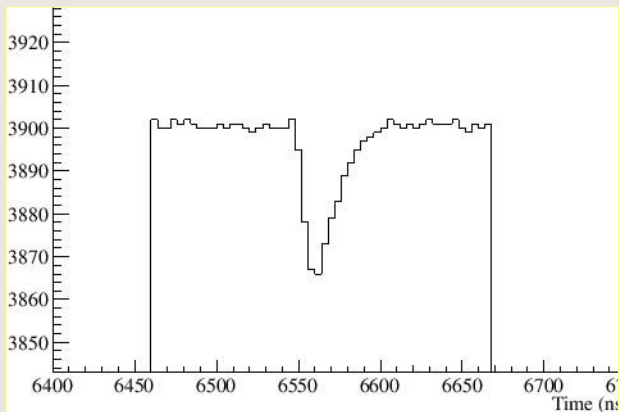


DEAP Multi-threaded frontends

PMT signals are actually shaped and split by custom boards, as well as being readout by slower V1740 FADCs. In this talk mostly focus on V1720 readout.

# V1720 – Further data suppression

- Saving full ZLE for all triggered events would saturate DAQ.
- So in V1720 front-end code we apply another level of data suppression.
- For each V1720 ZLE pulse we calculate QT (charge/time).
- For certain events (background-like, as determined by DAQ) we only save QT and discard ZLE data.



Q/T

# V1720 Frontend Program

- Wrote multi-threaded polling V1720 frontend; each thread handles one fibre link and calculates QTs for that link.
- Collector thread composes sub-event and places it in MIDAS buffer.

MIDAS buffer

Collector (main thread)  
 - Poll on having data ready in each ring buffer  
 - Place assembled sub-event in MIDAS buffer

Thread 0  
 - Collect ZLE data from boards 0,1  
 - Calculate QT  
 - Place Data in ring buffer

Thread 1...

Thread 1...

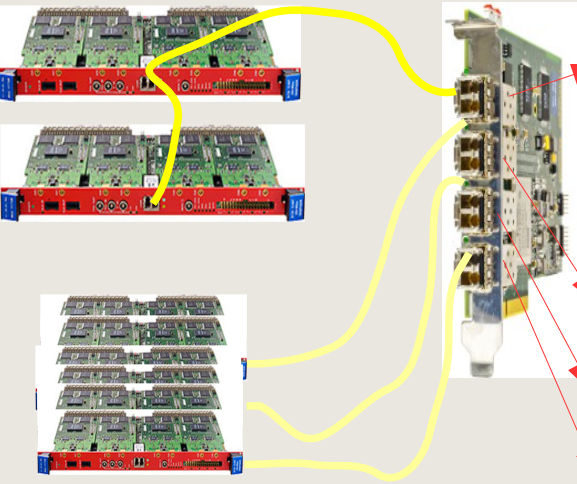
Thread 1...

Ring buffer 0

Ring buffer 1

Ring buffer 2

Ring buffer 3



# V1720 Frontend Program

## Benefits of Multi-threading:

- Better throughput without lots of front-ends.
- QT calculation can be more complicated, since there is 4X more CPU available for calculation.

end; each thread  
s for that link.

MIDAS buffer

Collector (main thread)  
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in each ring buffer  
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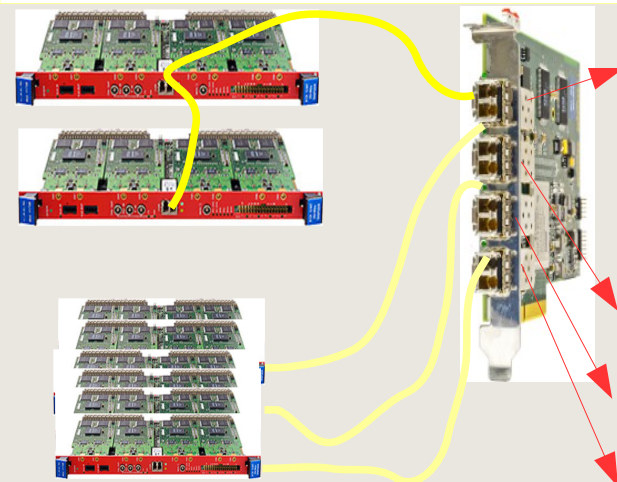
Thread 1...

Ring buffer 0

Ring buffer 1

Ring buffer 2

Ring buffer 3





# V1720 Frontend Program

- V1720 frontend; each thread processes QTs for that link.
- Technical point: Thread-safe communication is handed by making counter atomic (C++11 feature)

```

std::atomic<int> num_events_in_rb_; ///  

//< Number of events stored in ring buffer
/* These are atomic with sequential memory ordering. See below */
void IncrementNumEventsInRB() { ///  

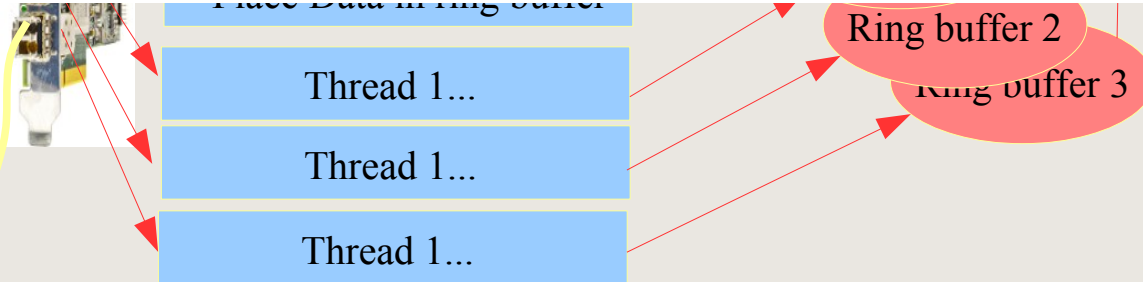
//< Increment Number of events in ring buffer
    num_events_in_rb_++;
}
void DecrementNumEventsInRB() { ///  

//< Decrement Number of events in ring buffer
    num_events_in_rb_--;
}

```

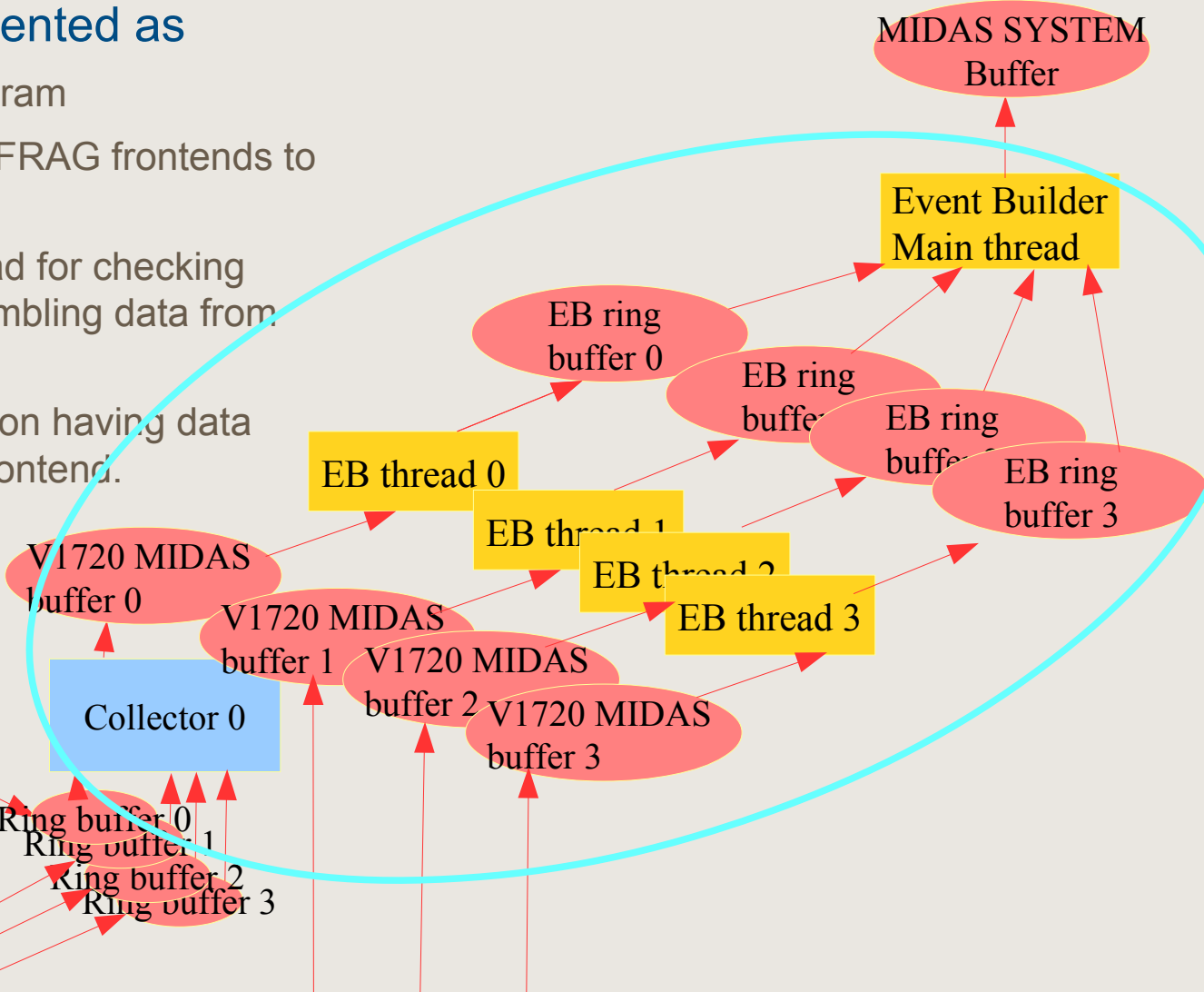
Collector (main thread)  
- Poll on having data ready

MIDAS buffer



# Event Builder

- Event builder implemented as
  - Regular frontend program
  - Constructs list of EB\_FRAG frontends to assemble
  - Uses a separate thread for checking timestamps and assembling data from each frontend buffer.
  - Collector thread polls on having data available from each frontend.



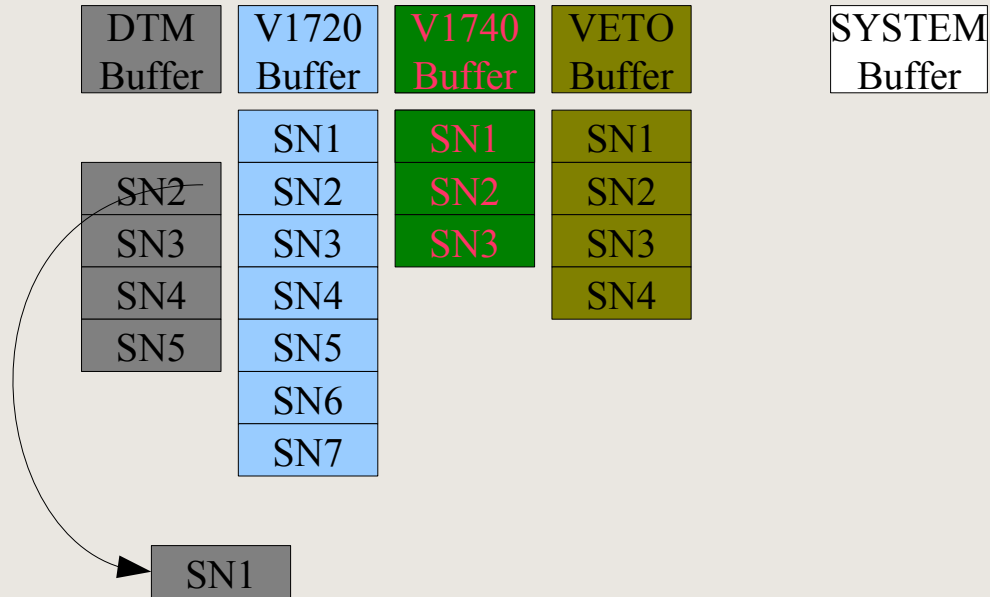
**Example :**  
**DTM running with all V1720 events,**  
**prescaling V1740/VETO by factor of 3.**

DTM Buffer	V1720 Buffer	V1740 Buffer	VETO Buffer	SYSTEM Buffer
SN1	SN1	SN1	SN1	
SN2	SN2	SN2	SN2	
SN3	SN3	SN3	SN3	
SN4	SN4		SN4	
SN5	SN5			
	SN6			
	SN7			

Notes:

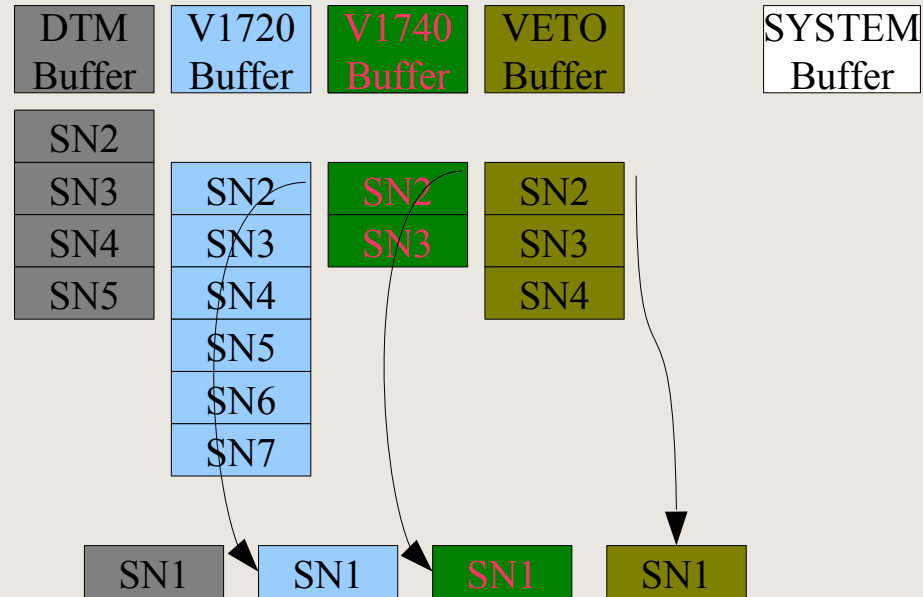
- SN = Serial number. Each event fragment is assigned a sequential serial number by front-end.
- Show a single V1720 buffer above, for simplicity. But in reality there are four V1720 buffers, one per front-end.
- Also, I'm omitting other front-ends like CALIB, though the same concept will apply.
- Buffers are being filled asynchronously and at different rates for each front-end. So don't expect same number of event fragments in each buffer.

**Example :**  
**DTM running with all V1720 events,**  
**prescaling V1740/VETO by factor of 3.**



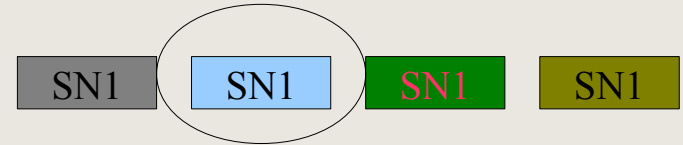
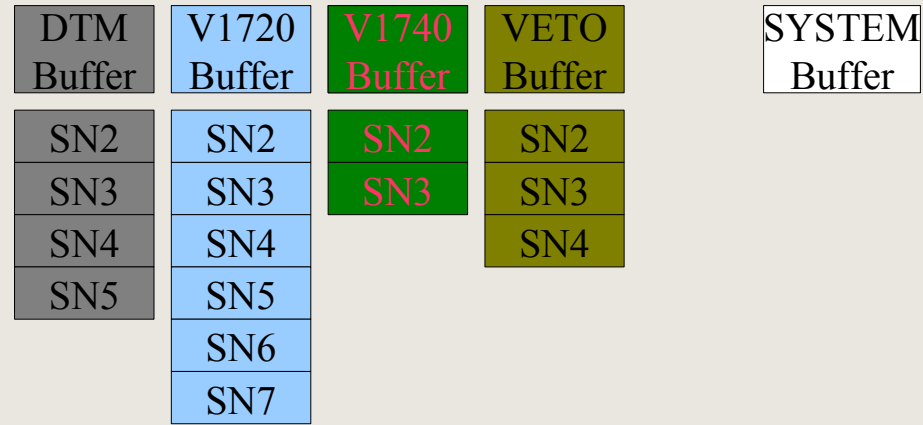
Step 1: Check DTM event. In this case, find that DTM triggered all the equipments.

**Example :**  
**DTM running with all V1720 events,**  
**prescaling V1740/VETO by factor of 3.**



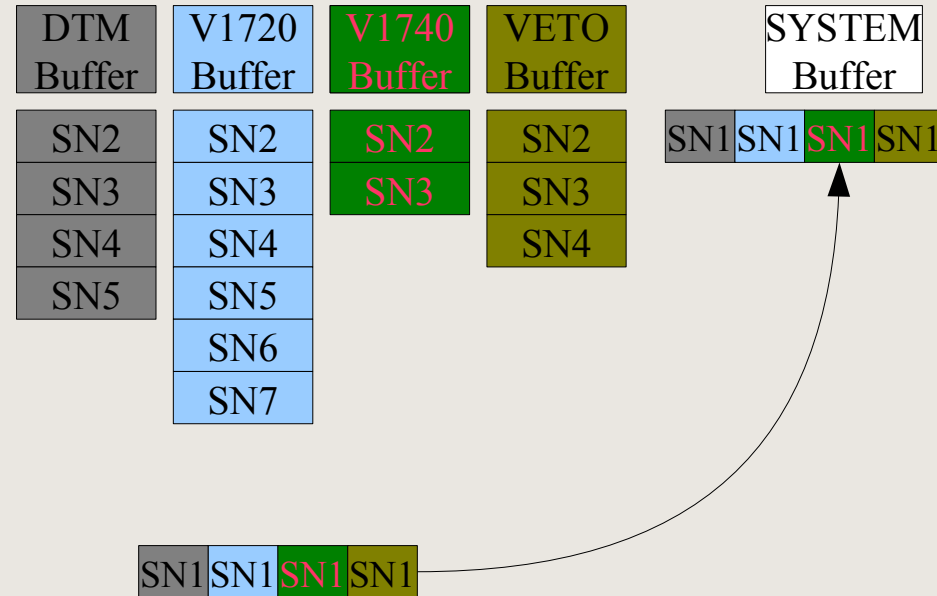
Step 2: Get each of the front-end fragments from buffers. Compare timestamps; assume they match.

**Example :**  
**DTM running with all V1720 events,**  
**prescaling V1740/VETO by factor of 3.**



Step 3: Use QT information from V1720s to create summed histograms for filtering decision.

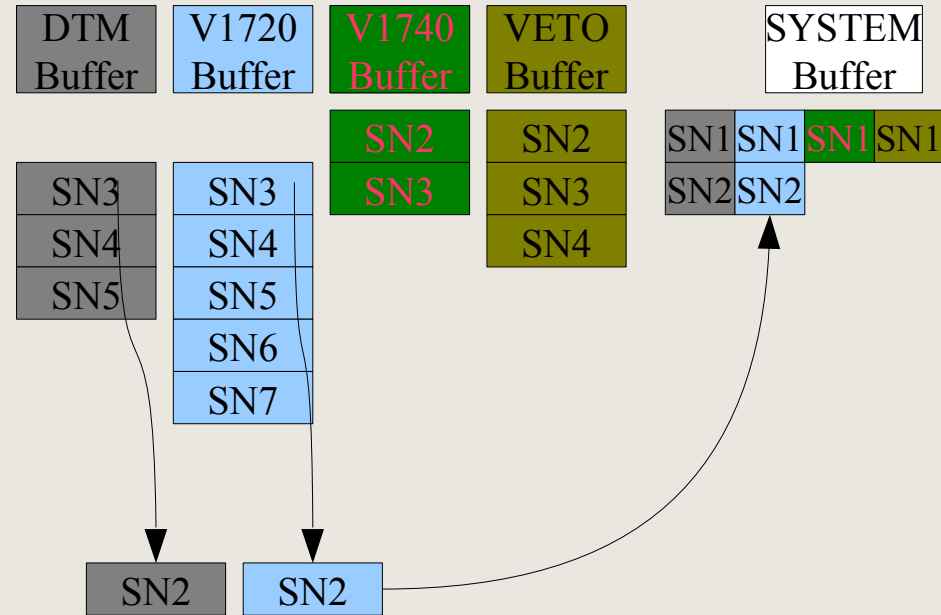
**Example :**  
**DTM running with all V1720 events,**  
**prescaling V1740/VETO by factor of 3.**



Step 4: Make filtering decision; in this case, assume we keep all information. Compose final event.

Note: we don't actual store the 'serial number' for each fragment in the final event. There is just a single serial number for the final event. I only show the individual serial numbers here so it is clear how the fragments are getting assembled

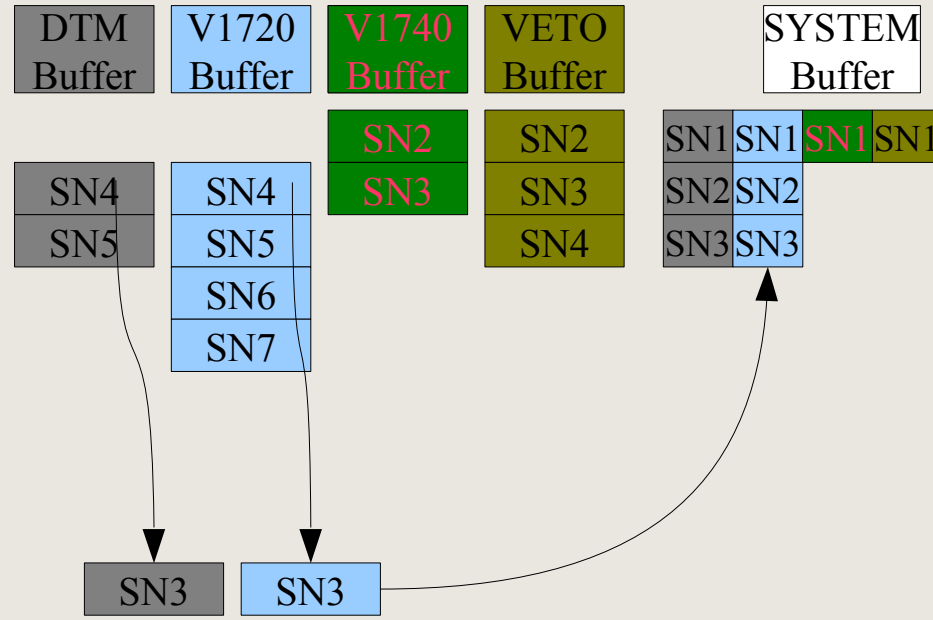
**Example :**  
**DTM running with all V1720 events,**  
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Next event: same sequence as last time, except that in this case the DTM only triggered the V1720s. So we only take the fragments from the DTM and V1720 buffers.

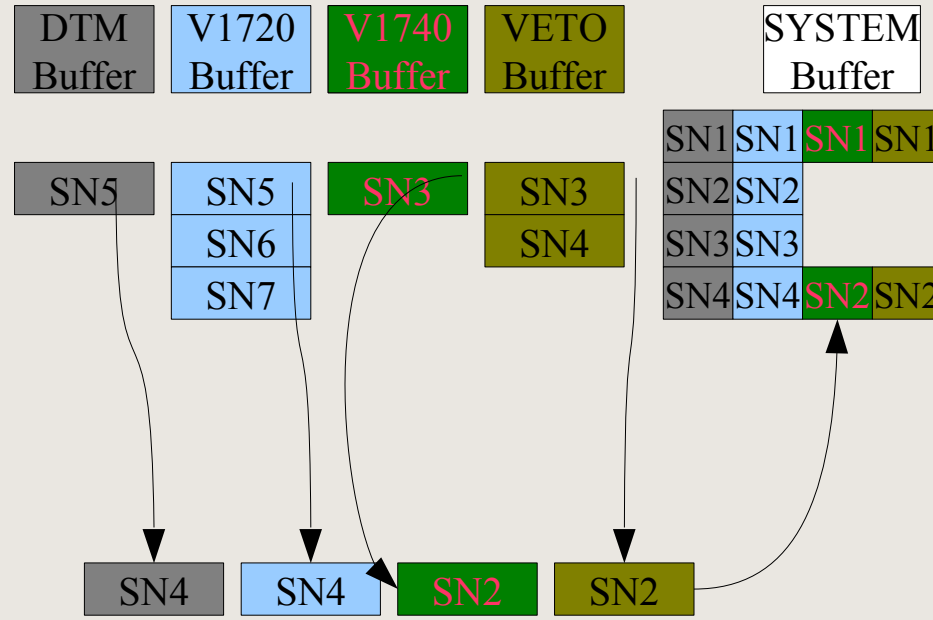


**Example :**  
**DTM running with all V1720 events,**  
**prescaling V1740/VETO by factor of 3.**



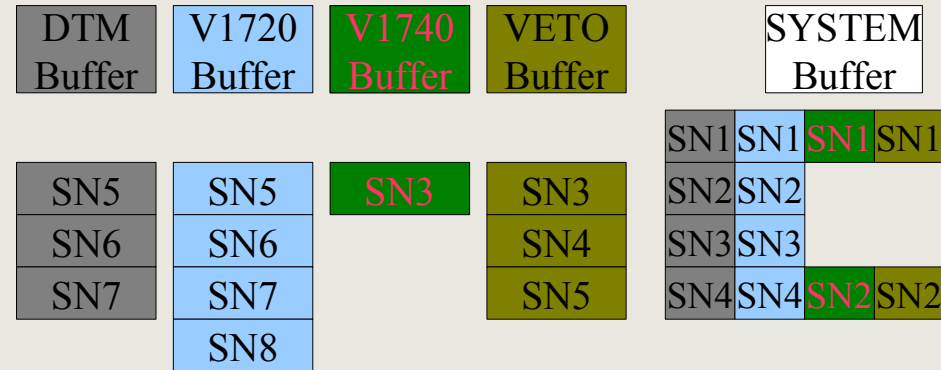
Third event: same again...

**Example :**  
**DTM running with all V1720 events,**  
**prescaling V1740/VETO by factor of 3.**



Fourth DTM event: now we need all the equipment again.

**Example :**  
**DTM running with all V1720 events,**  
**prescaling V1740/VETO by factor of 3.**

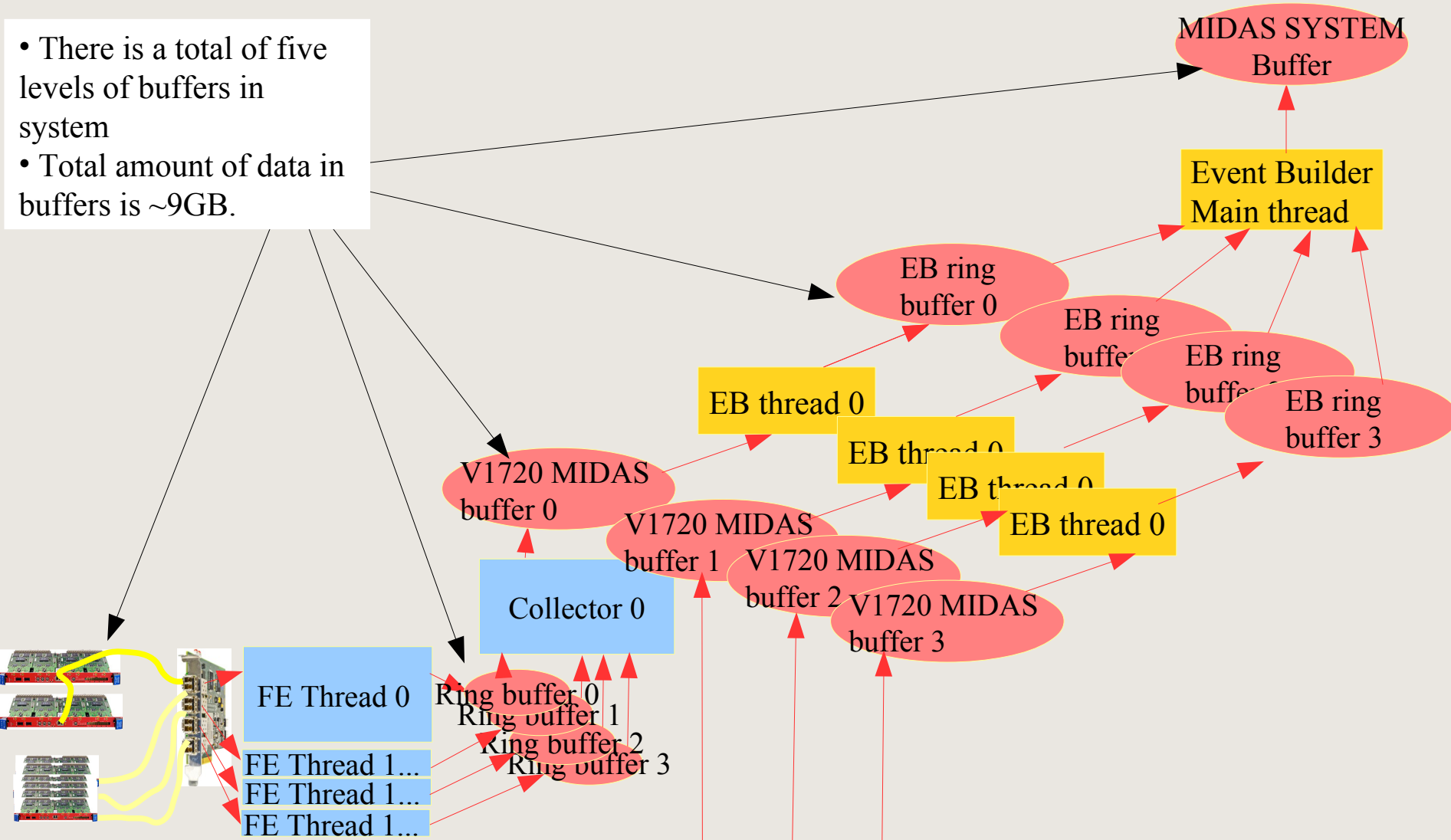


And so on...

Of course we are also adding event fragments to the front-end buffers asynchronously as the event handlers removes event fragments from those buffers...

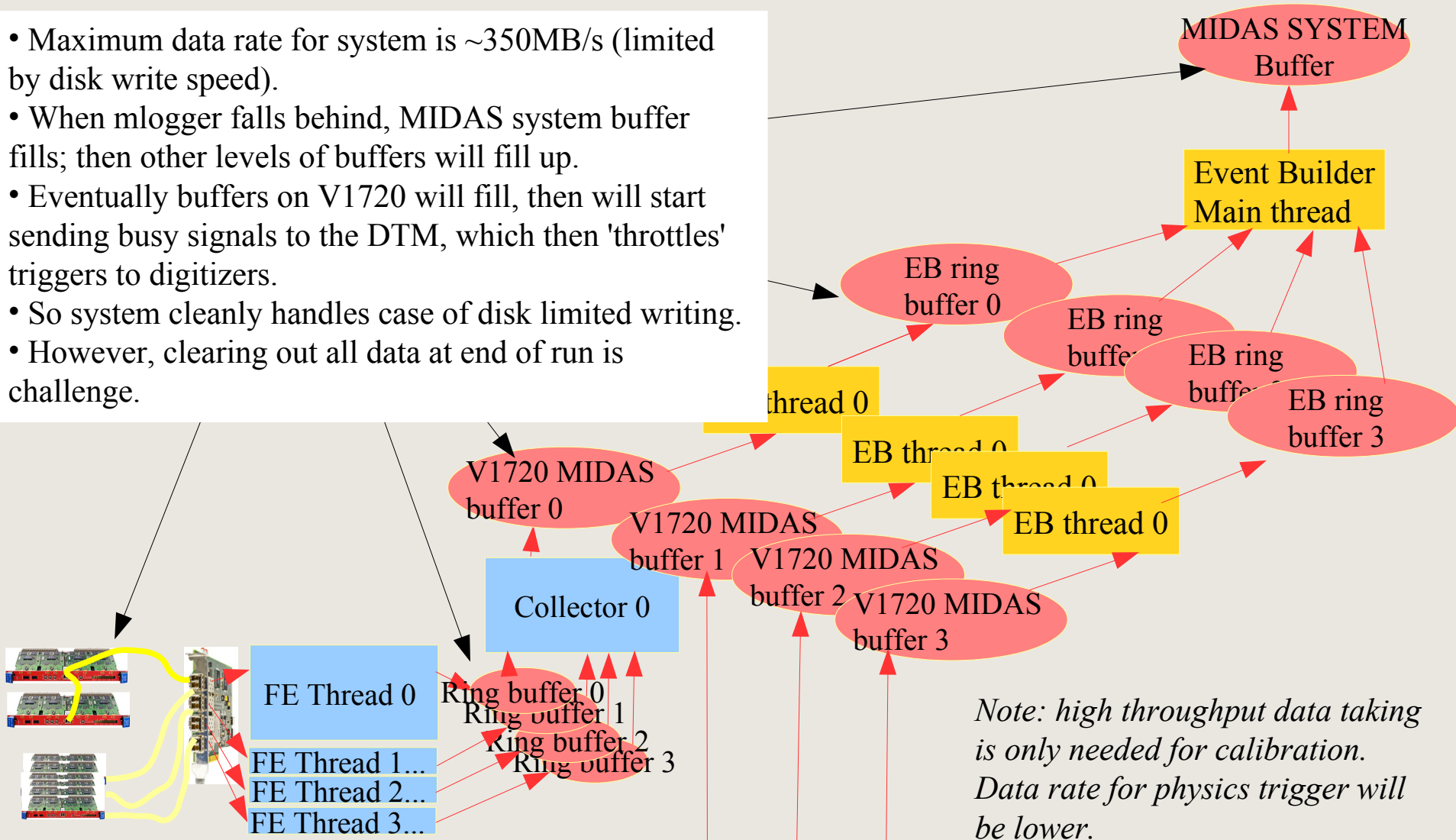
# Event Builder Performance

- There is a total of five levels of buffers in system
- Total amount of data in buffers is ~9GB.



# Event Builder Performance

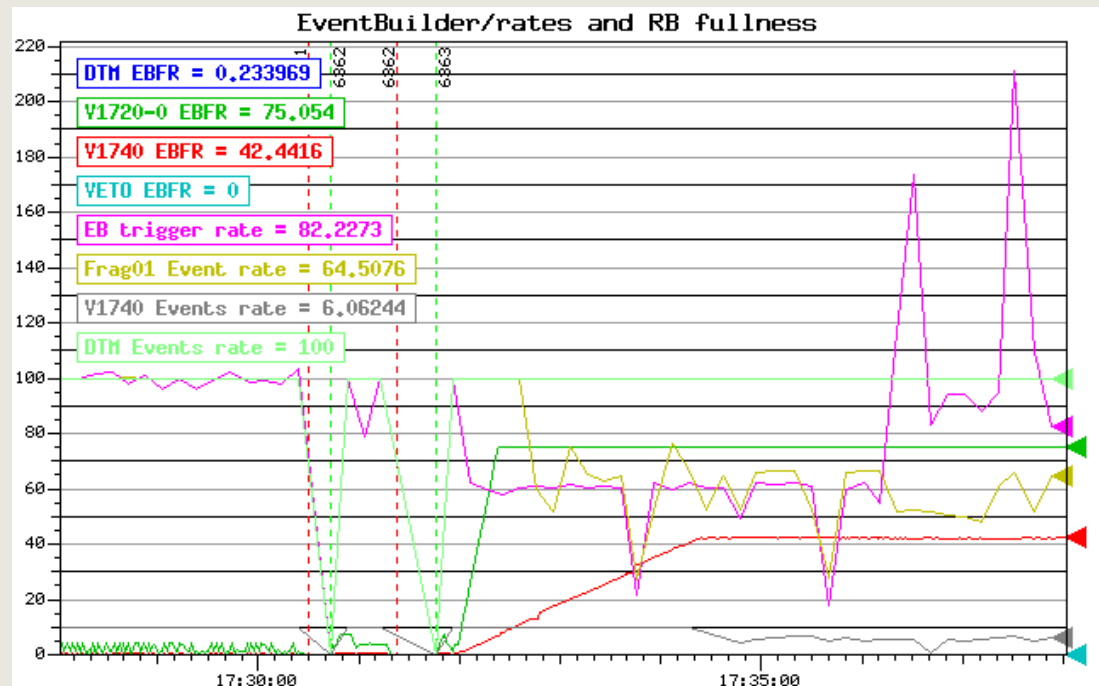
- Maximum data rate for system is ~350MB/s (limited by disk write speed).
- When mlogger falls behind, MIDAS system buffer fills; then other levels of buffers will fill up.
- Eventually buffers on V1720 will fill, then will start sending busy signals to the DTM, which then 'throttles' triggers to digitizers.
- So system cleanly handles case of disk limited writing.
- However, clearing out all data at end of run is challenge.



*Note: high throughput data taking is only needed for calibration. Data rate for physics trigger will be lower.*

# Event Builder: Data Throughput

- Results can be difficult to interpret, as system evolves over first couple minutes of data taking.
- But stable operation possible in the maximize data rate mode.



# Conclusion

- Use multi-threading for DEAP frontends and event builder in order to maximize throughput and available CPU for data processing.
- DAQ is working and shown to be (reasonably) stable with high data throughput and variable trigger conditions.
- All code available for inspection here:  
<https://bitbucket.org/ttriumfdaq/deap/src/>