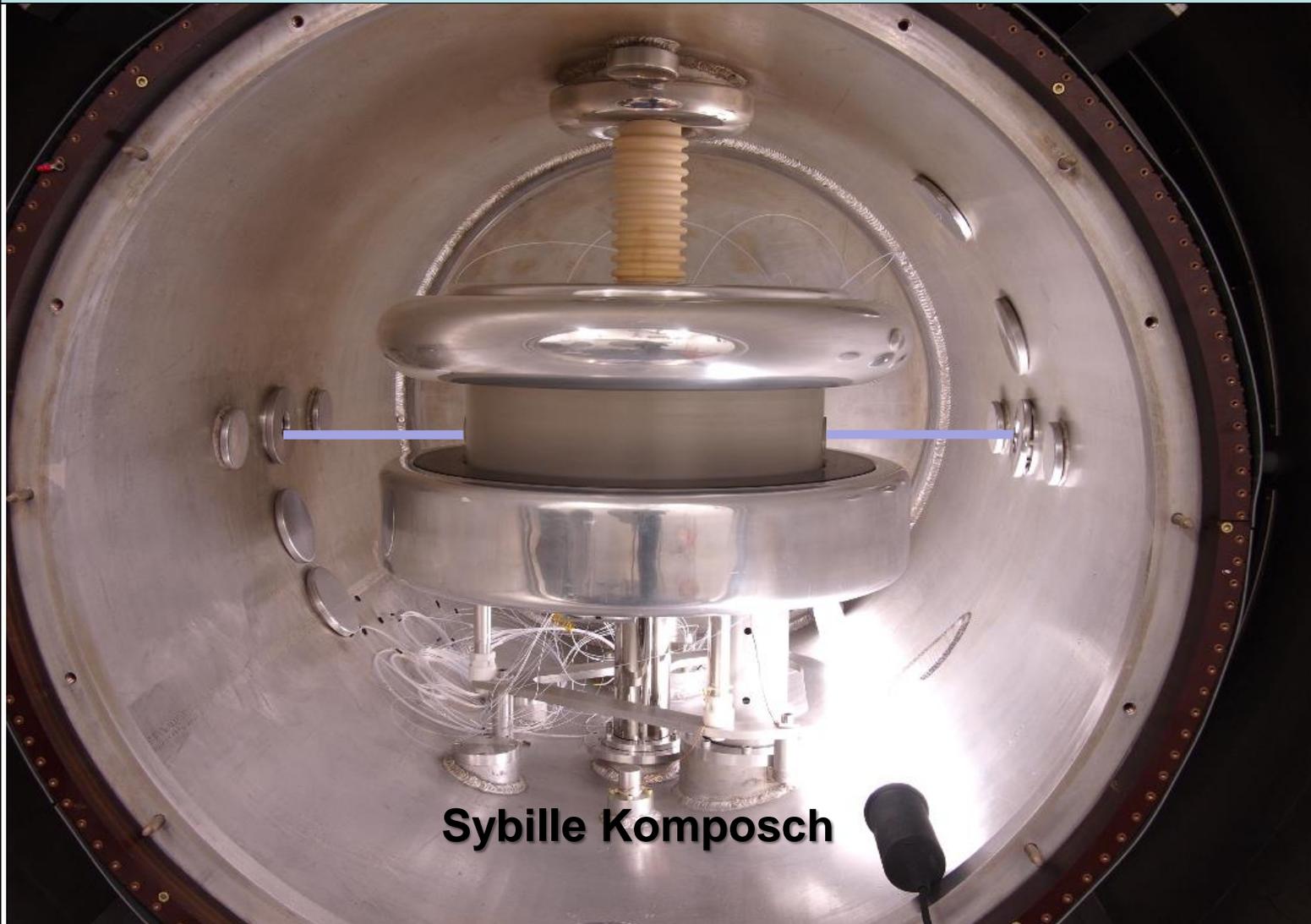


# Realization of a high-performance laser-based mercury magnetometer for neutron EDM experiments



Sybille Komposch



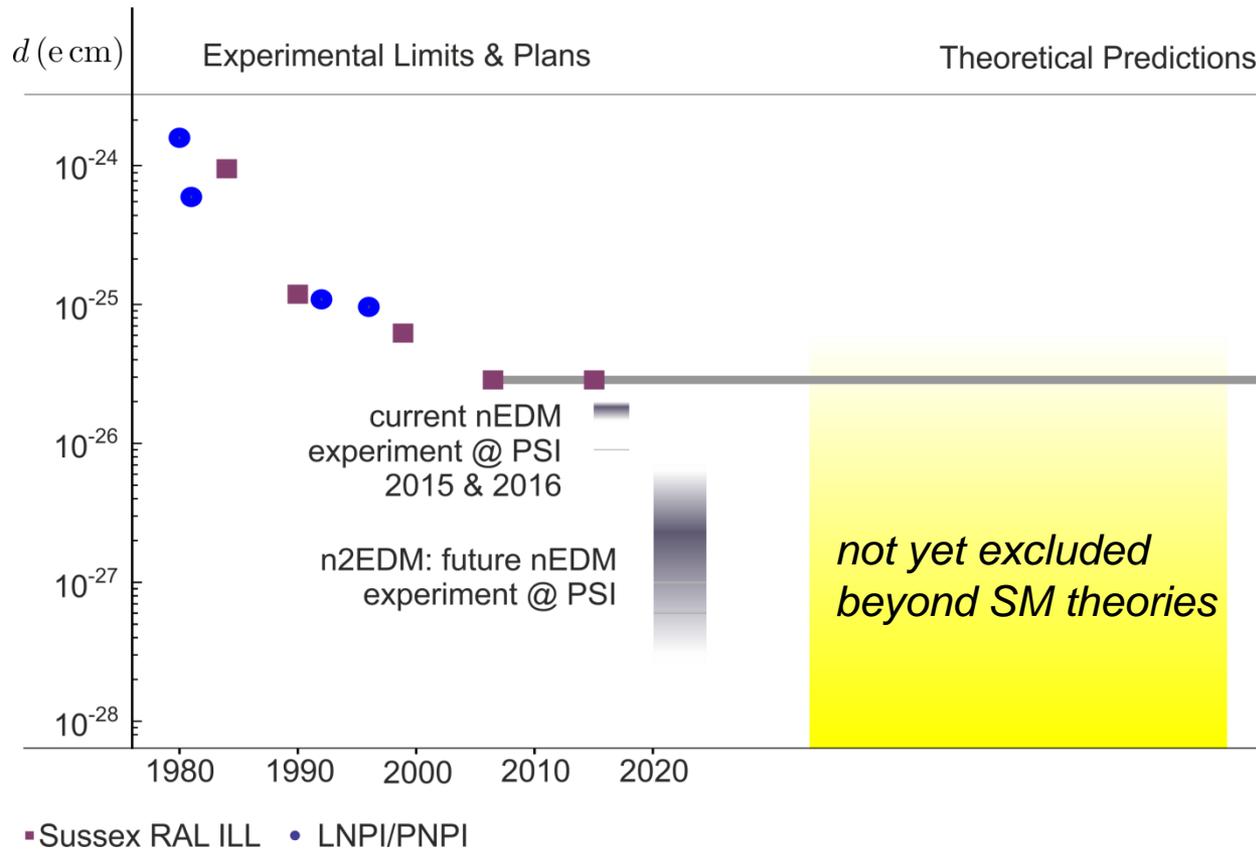
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**PSI**

# Why?



nEDM → new source of CP violation → important guide to explain the baryogenesis



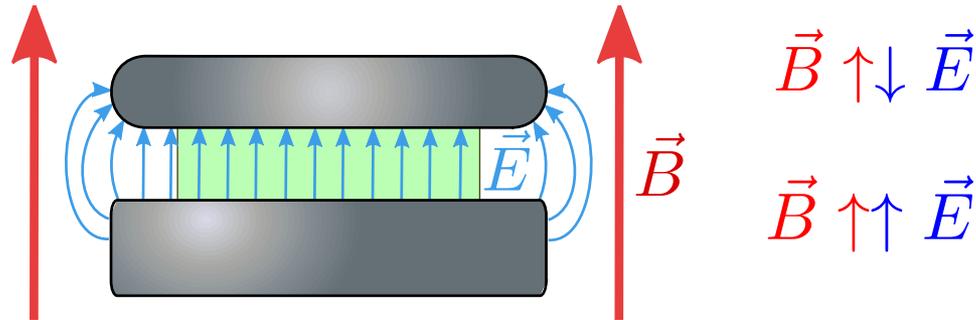
→ Predicted value by the Standard Model:  
*Khriplovich et al, Physics Letters B 109 (1982)*

$$d_n \approx 2 \cdot 10^{-32} \text{ e} \cdot \text{cm}$$

# The measurement principle



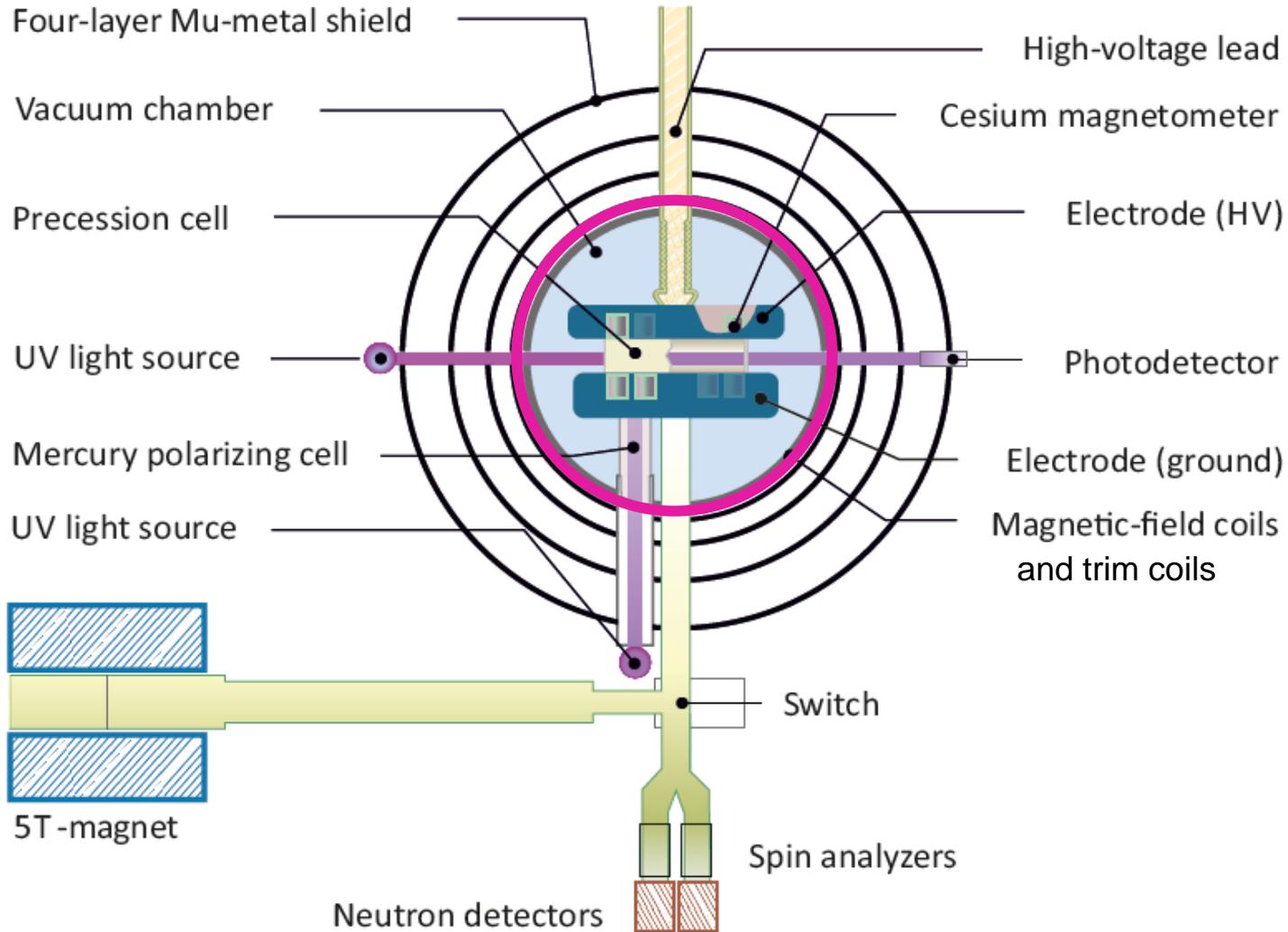
$$f_n = \frac{2}{h} \left( \vec{\mu}_n \cdot \vec{B} + \vec{d}_n \cdot \vec{E} \right)$$



$$d_n = \frac{1}{2E} \left( h \left( f_n^{\uparrow\uparrow} - f_n^{\uparrow\downarrow} \right) + \mu_n \left( B^{\uparrow\uparrow} - B^{\uparrow\downarrow} \right) \right)$$

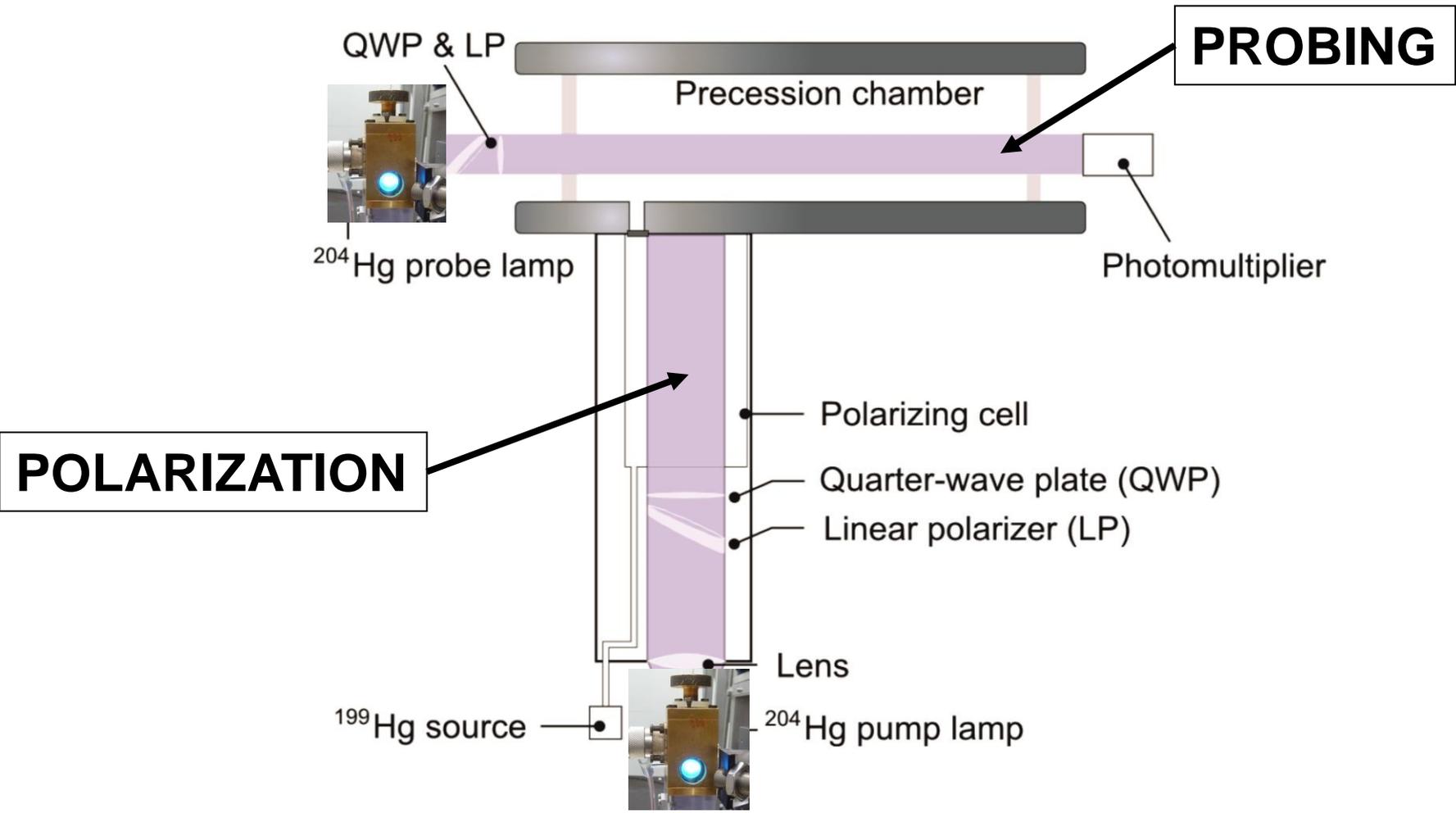
Correction of magnetic field drifts

# The nEDM apparatus

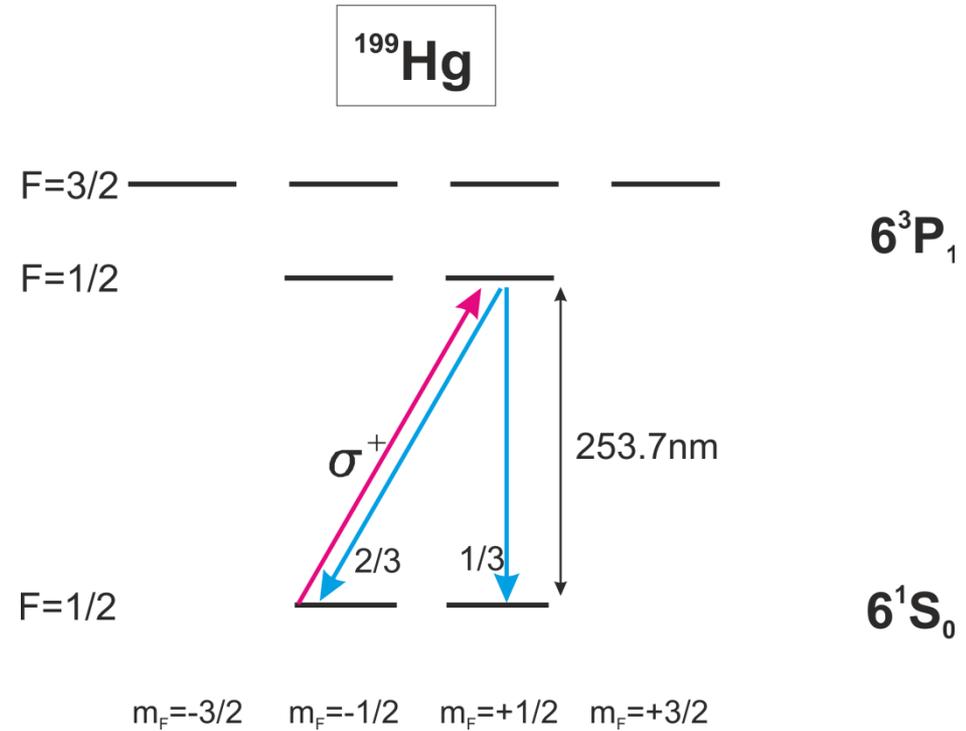
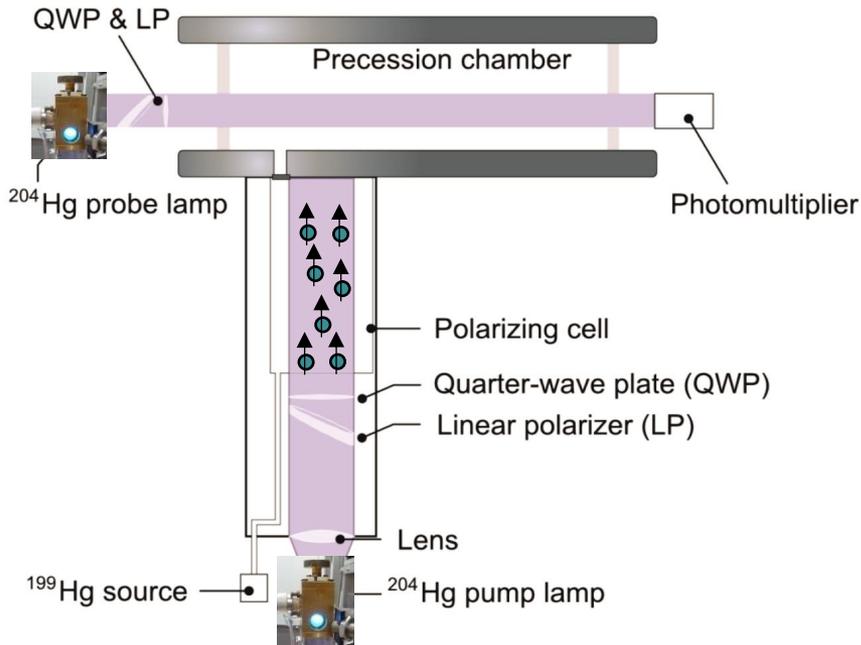


surrounding field compensation

# Hg co-magnetometer



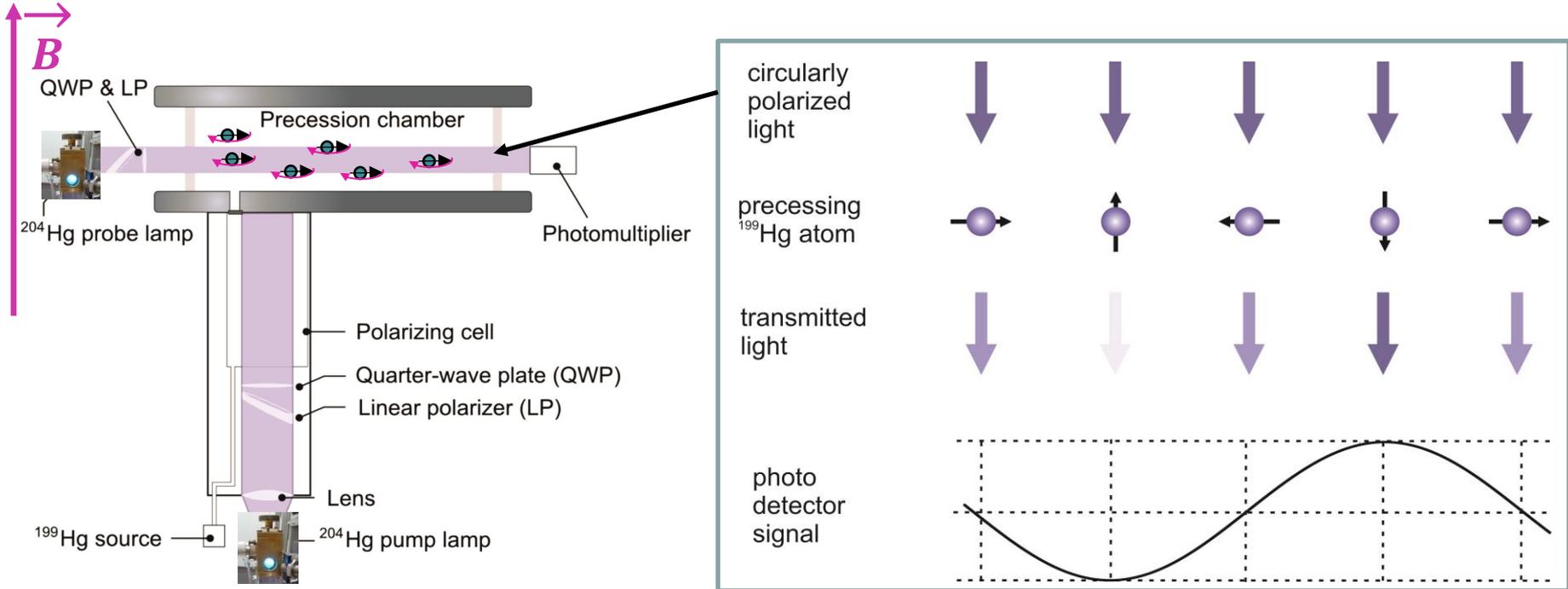
# Optical Pumping



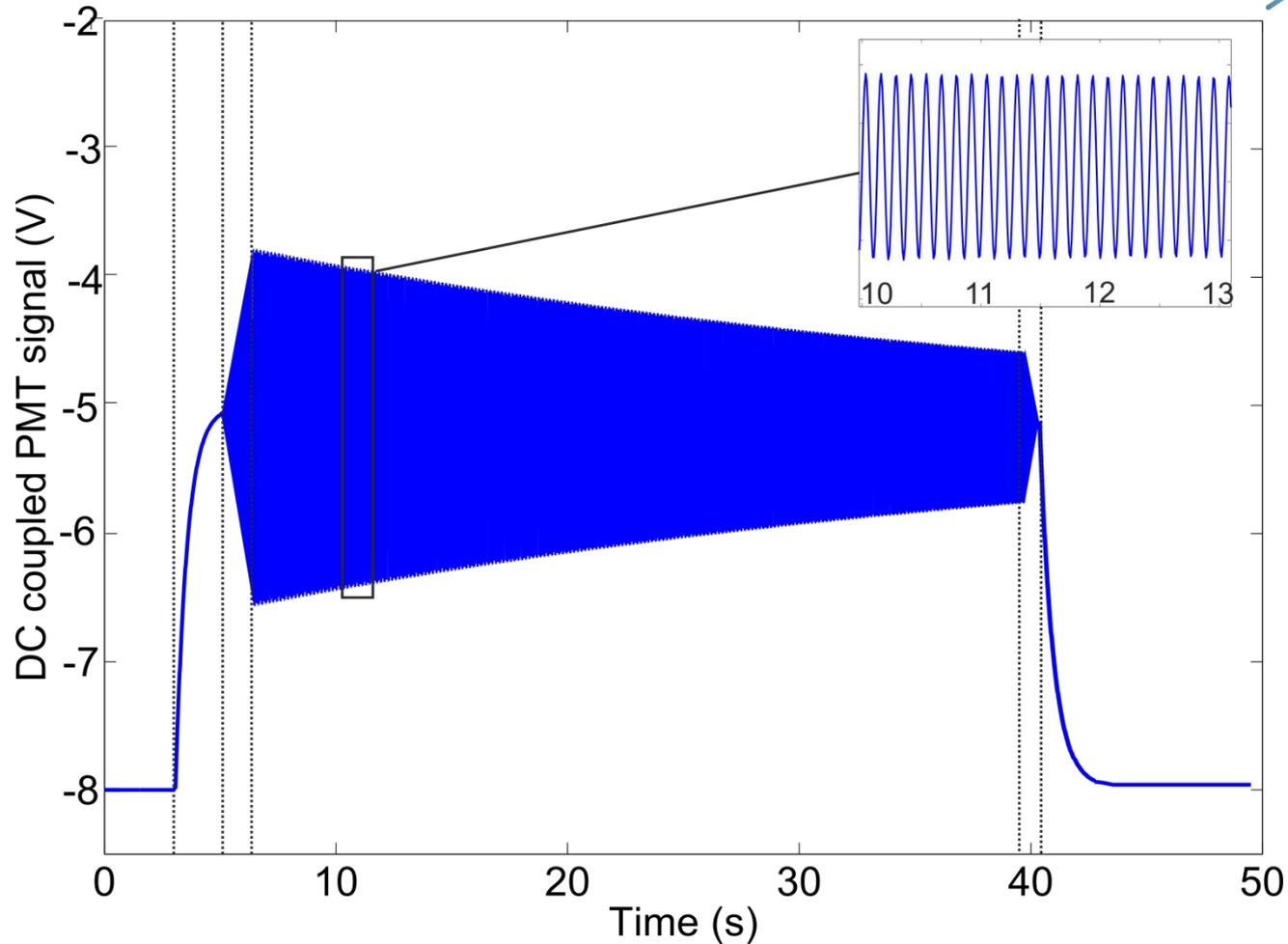
# Probing



$$f_{\text{Hg}} = \frac{\gamma_{\text{Hg}} B}{2\pi} \approx 8 \text{ Hz @ } 1 \mu\text{T}$$

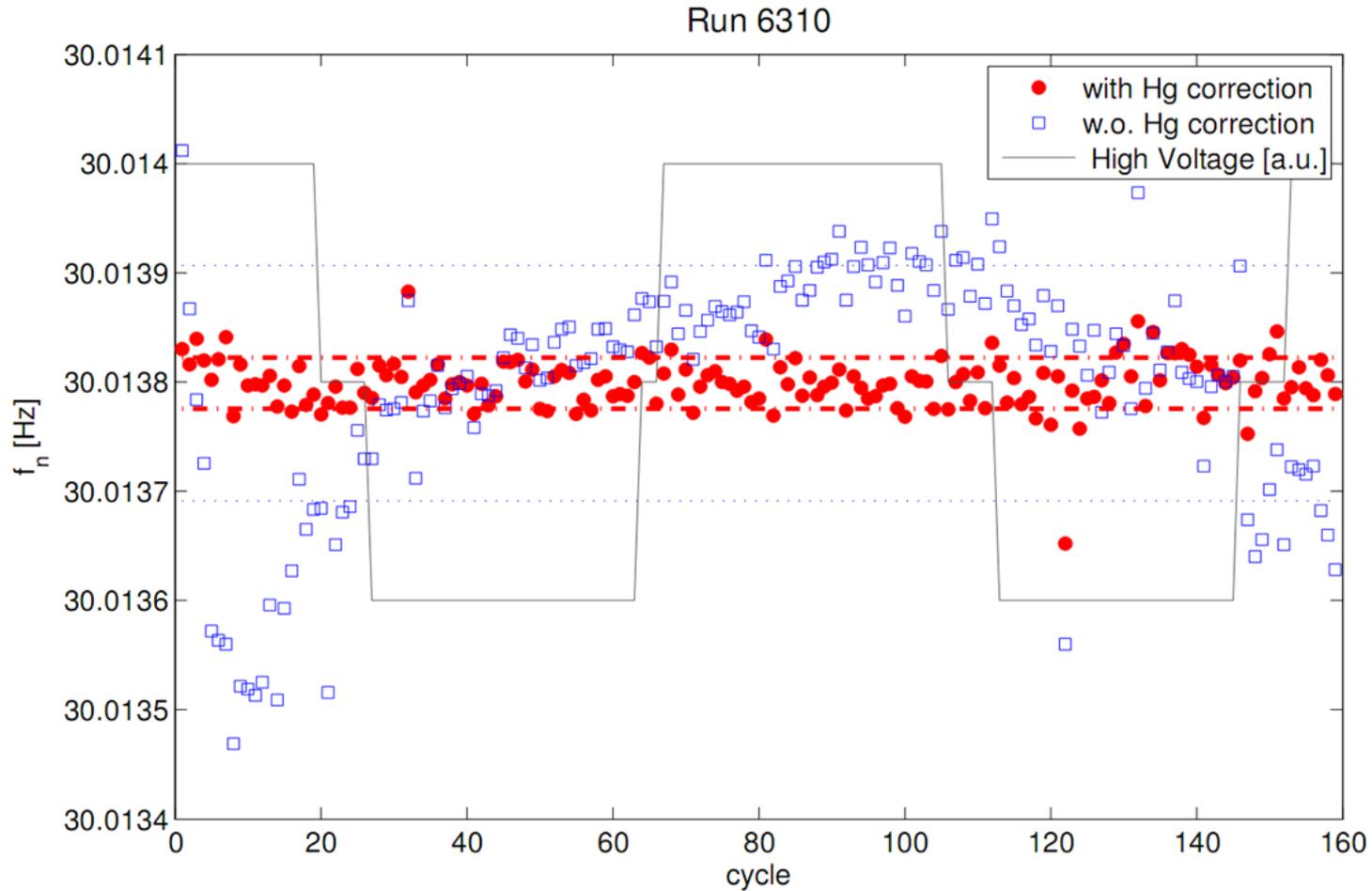


# Hg Cycle



$$A(t) = a_s e^{-t/\tau} \sin(2\pi ft + \phi_0)$$

# Magnetic field drift correction



# Requirements



**Correction:** 
$$\omega_n^* = \omega_n - \frac{\gamma_n}{\gamma_{\text{Hg}}} \omega_{\text{Hg}}$$

**Error propagation:** 
$$\Delta\omega_n^* = \sqrt{\Delta\omega_n^2 + \left(\frac{\gamma_n}{\gamma_{\text{Hg}}} \Delta\omega_{\text{Hg}}\right)^2} = \Delta\omega_n K$$

**Increase of the statistical error due to correction:** 
$$K = \sqrt{1 + \left(\frac{\Delta\omega_{\text{Hg}}/\omega_{\text{Hg}}}{\Delta\omega_n/\omega_n}\right)^2}$$

**For nEDM:  $K < 1.05$**   $\longrightarrow$  
$$\frac{\Delta\omega_{\text{Hg}}}{\omega_{\text{Hg}}} = \frac{\Delta B}{|B_0|} < \frac{1}{3.1} \frac{\Delta\omega_n}{\omega_n}$$

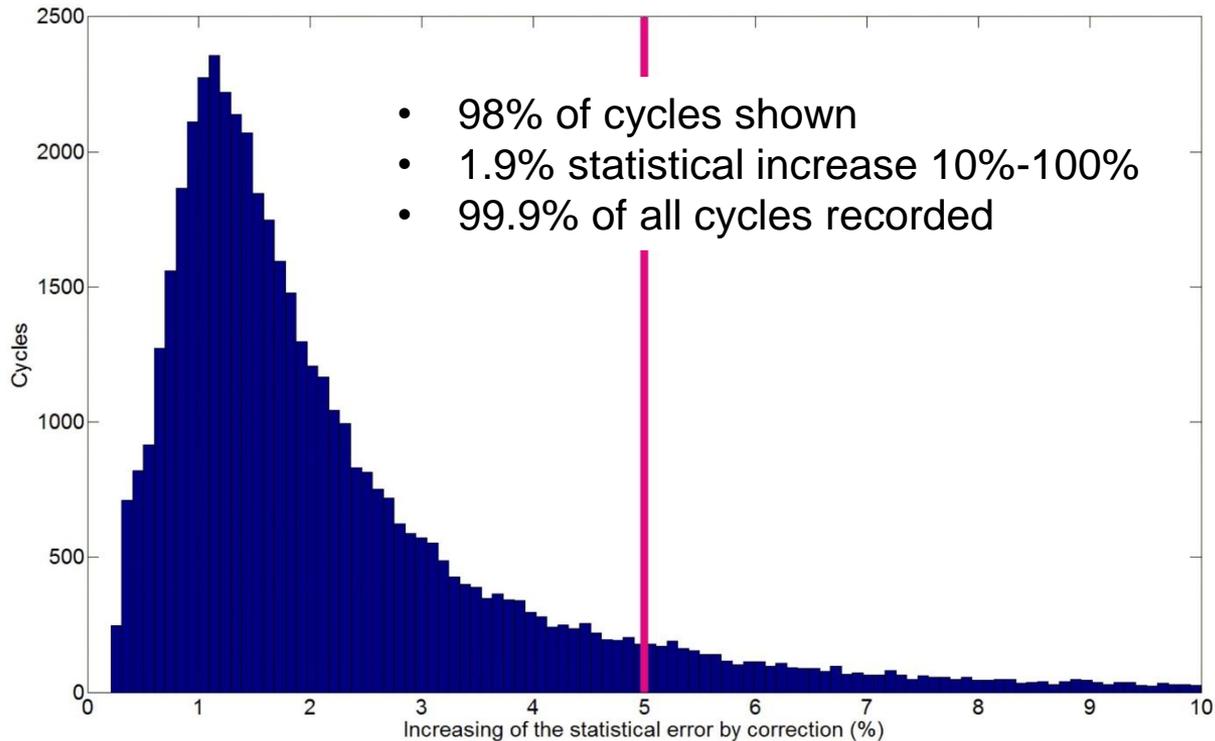
$$\Delta\omega_n/\omega_n = 0.25 \text{ ppm} \longrightarrow \Delta\omega_{\text{Hg}}/\omega_{\text{Hg}} < 0.08 \text{ ppm}$$

**Magnetometric resolution:** 
$$\Delta B < 80 \text{ fT}$$

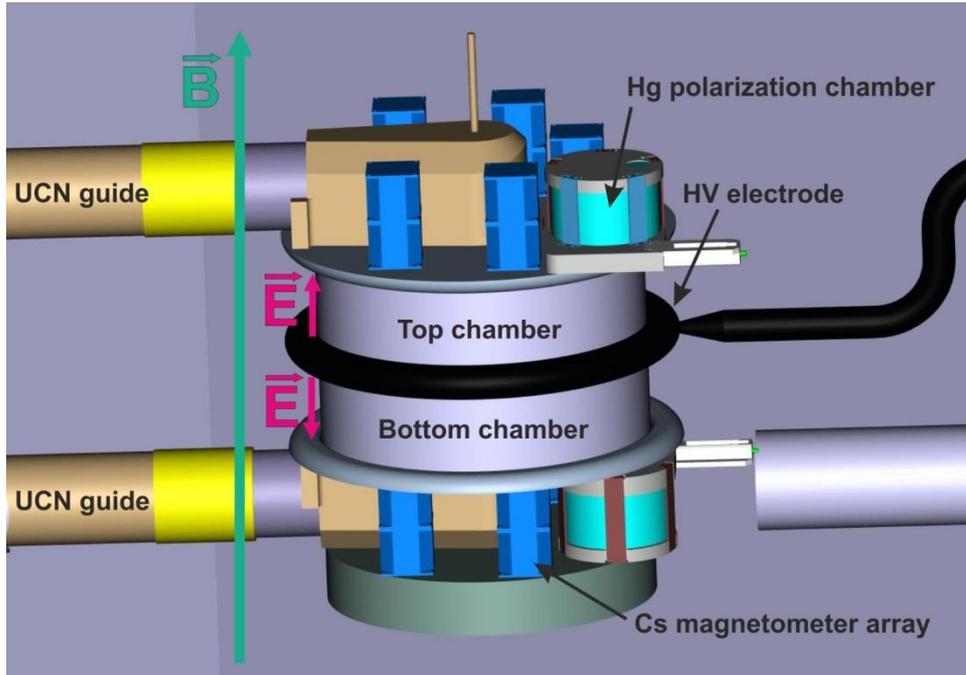
# Performance Hg magnetometer in nEDM



Data taking 2015-2016: 56007 cycles in total



# Preview: n2EDM setup



Magnetometric resolution per cycle:

$$\Delta B = 16 \text{ fT}$$

	d chamber (cm)	Coating	$\alpha$	$E$ (kV/cm)	$N$ UCN per cycle after 180s	$\sigma(d_n)$ (e·cm) per day	$\sigma(d_n)$ (e·cm) 500 data days
nEDM	47	dPS, DLC	0.75	11	15000	$11 \times 10^{-26}$	$5.0 \times 10^{-27}$
n2EDM	47	dPE, DLC	0.8	15	100300	$2.8 \times 10^{-26}$	$1.3 \times 10^{-27}$
n2EDM	80	dPE, DLC	0.8	15	292000	$1.7 \times 10^{-26}$	$7.5 \times 10^{-28}$
n2EDM	100	dPE, DLC	0.8	15	400000	$1.4 \times 10^{-26}$	$6.4 \times 10^{-28}$

n2EDM - Design status report 2017

# Sensitivity lamp-based magnetometer



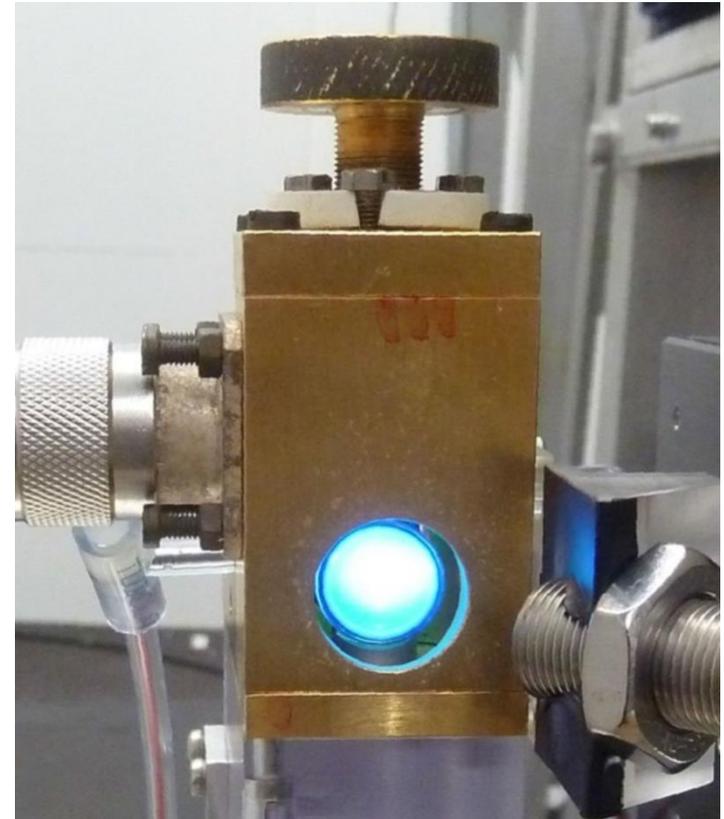
## Sensitivity: > 35 fT

Large uncertainty on the output frequency  
Spectrum:

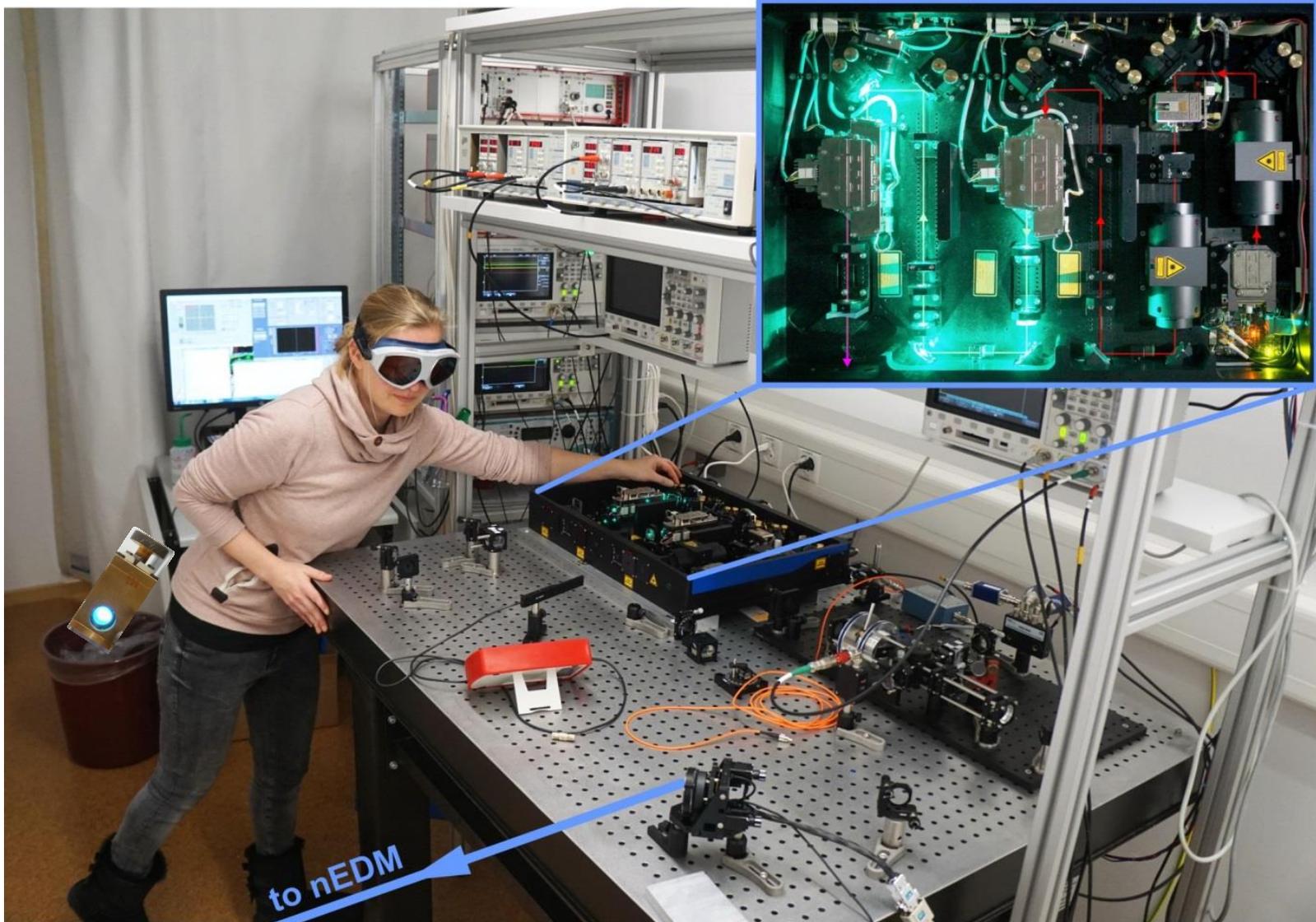
- **Emission light is Doppler-broadened**
- **Self absorption**
- **Light cannot be focused / collimated**
- ....

→ **Improve with UV-laser-system**

Proof of principle measurement:  
5-fold signal increase  
(Thesis M. Fertl 2013, ETHZ)



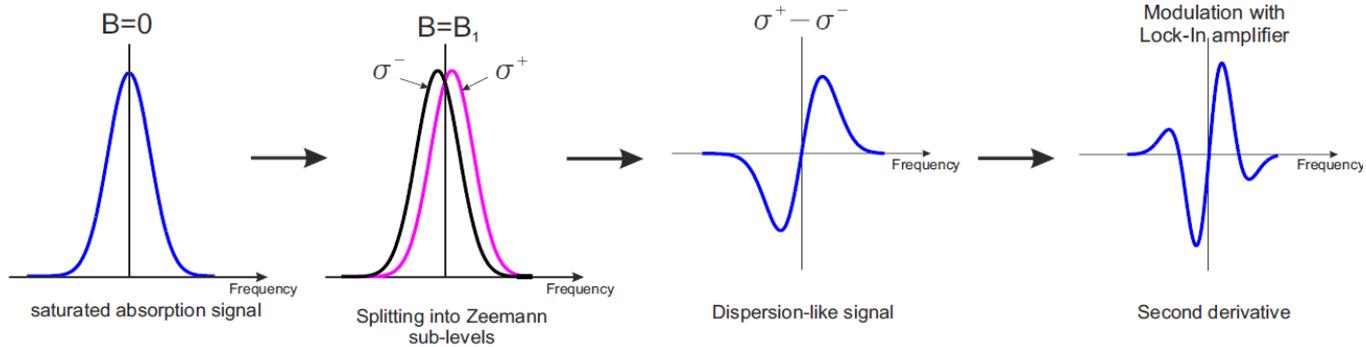
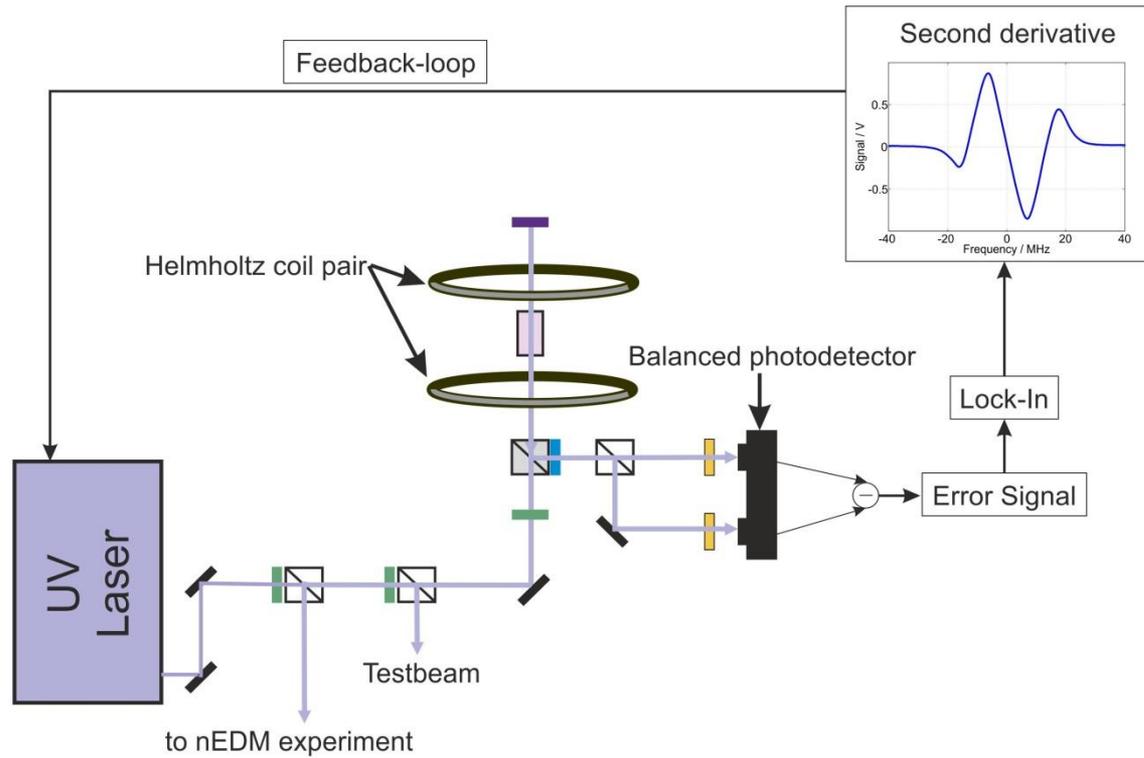
# The UV laser



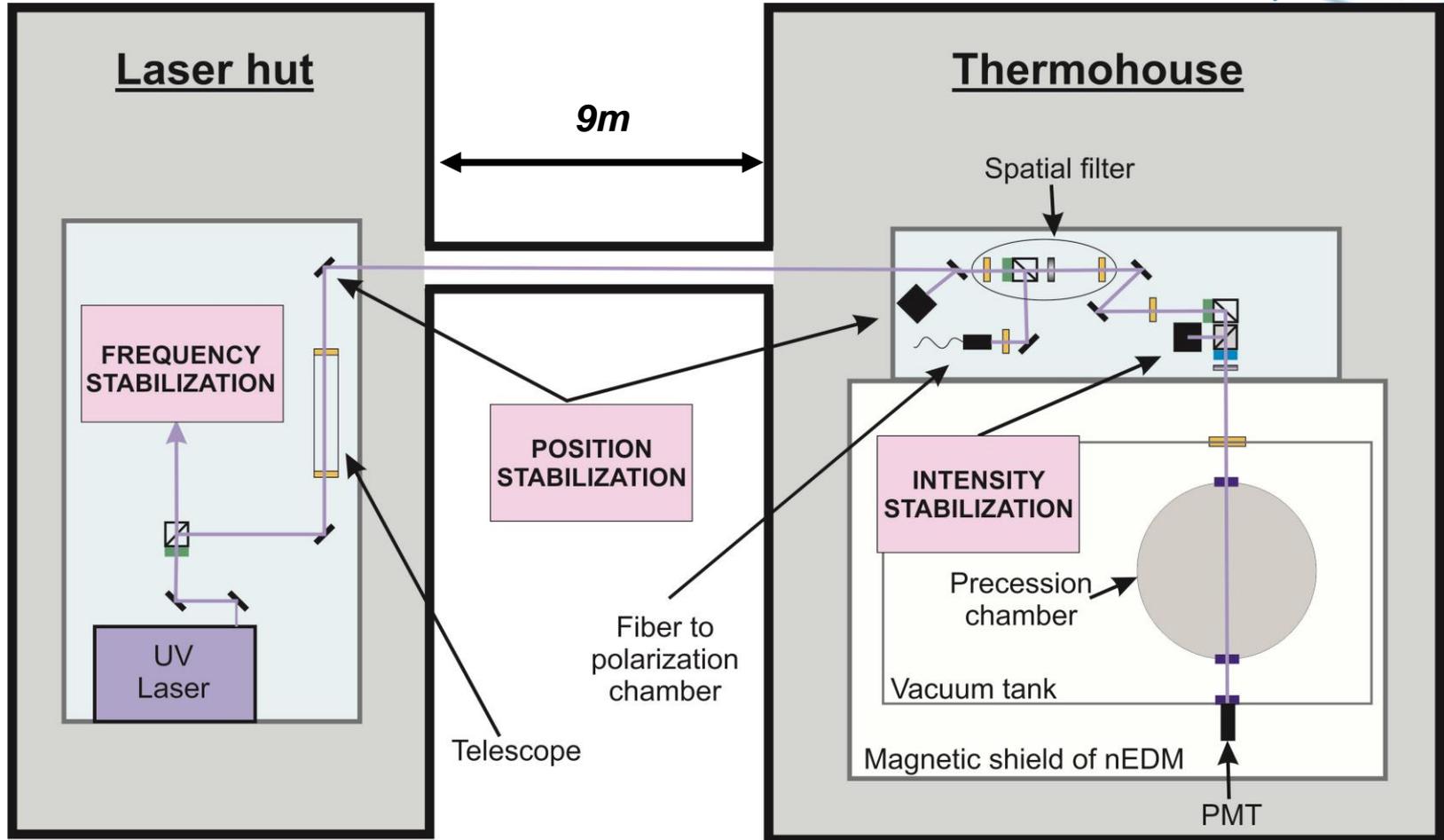
# Frequency stabilization



Dichroic atomic vapor laser lock



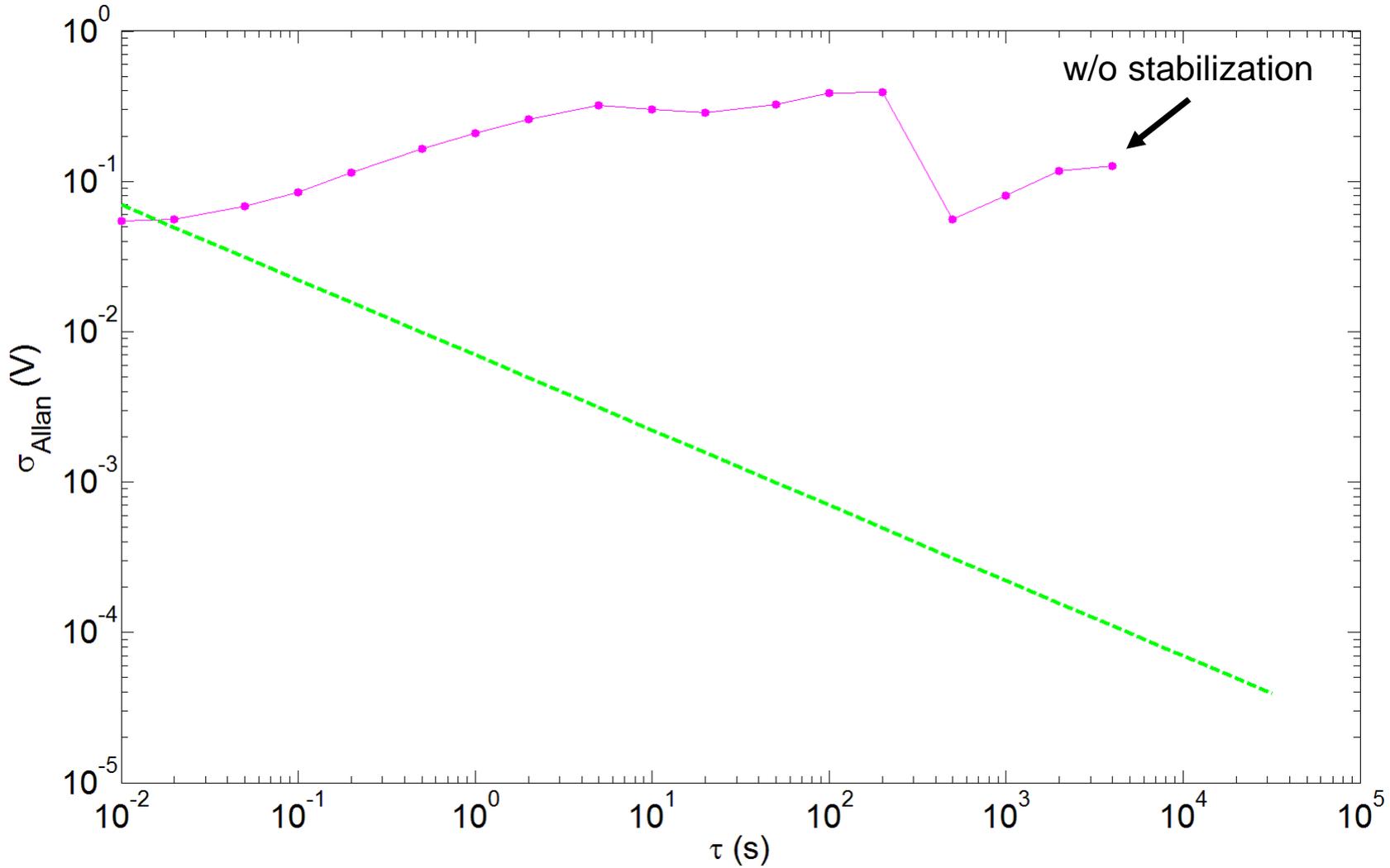
# Sketch of the laser system



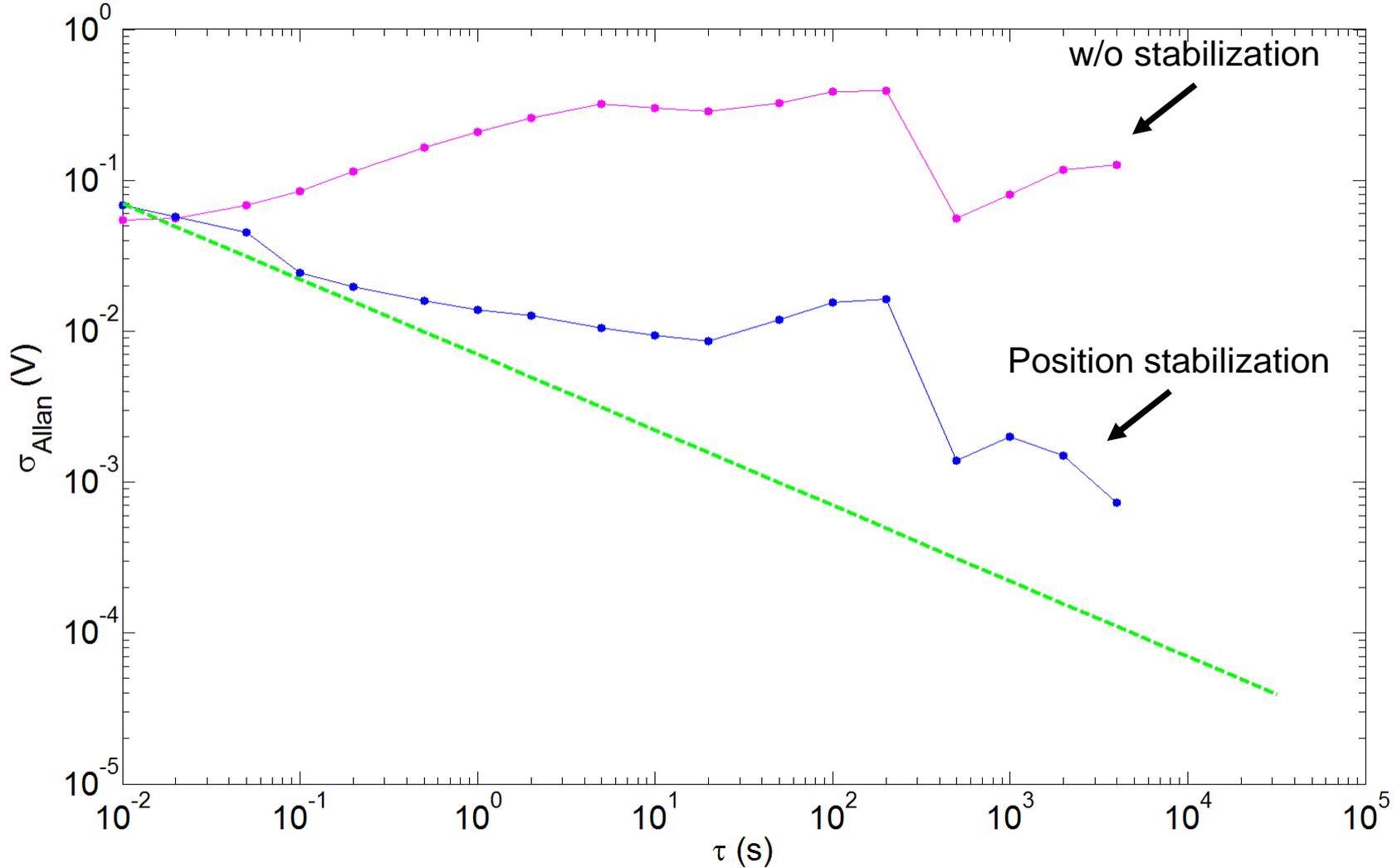
- Polarizing beam splitter
- Non polarizing beam splitter
- Lens

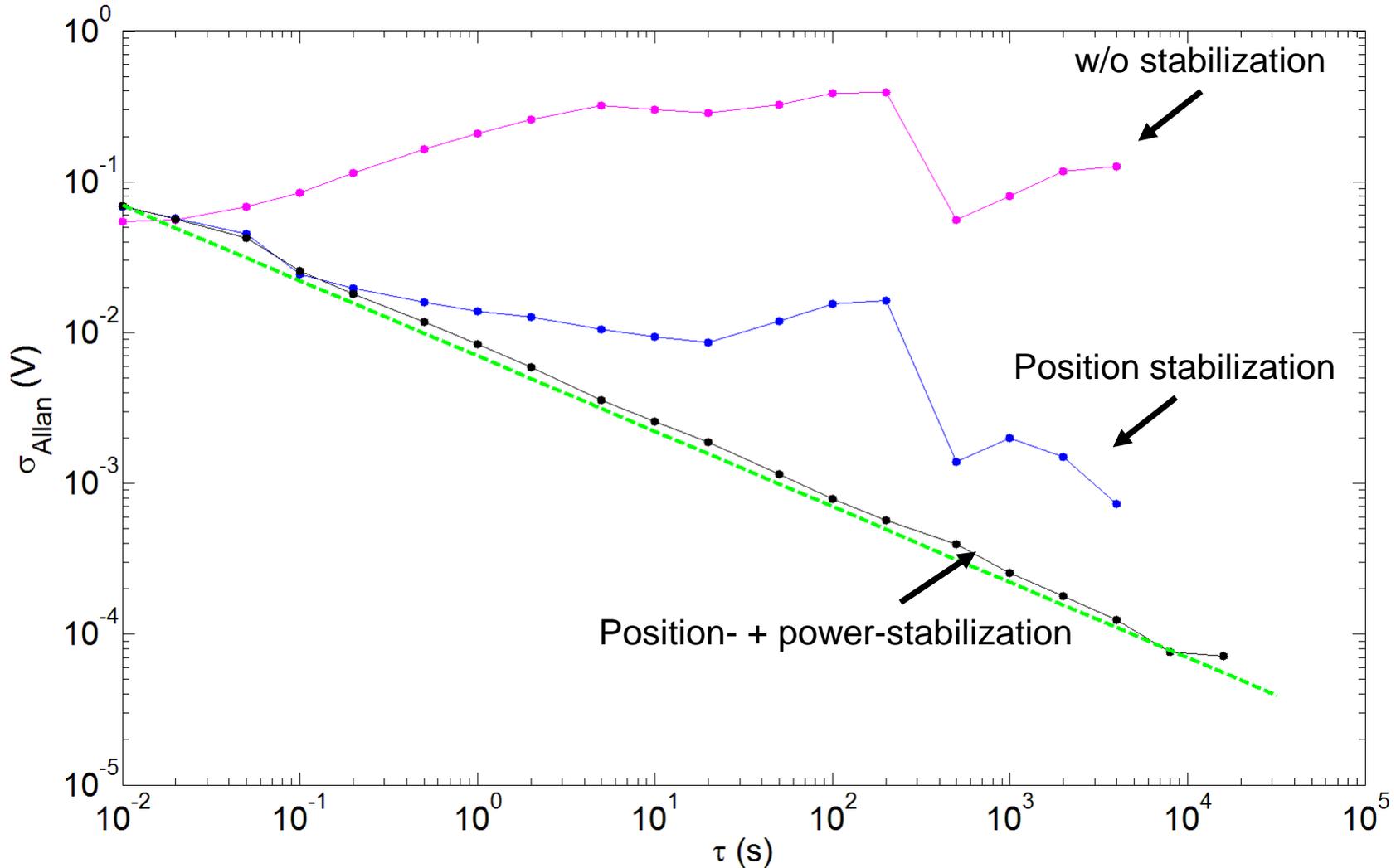
- UV transmitting window
- Photo detector
- Mirror

- λ/2 plate
- λ/4 plate
- Neutral density filter

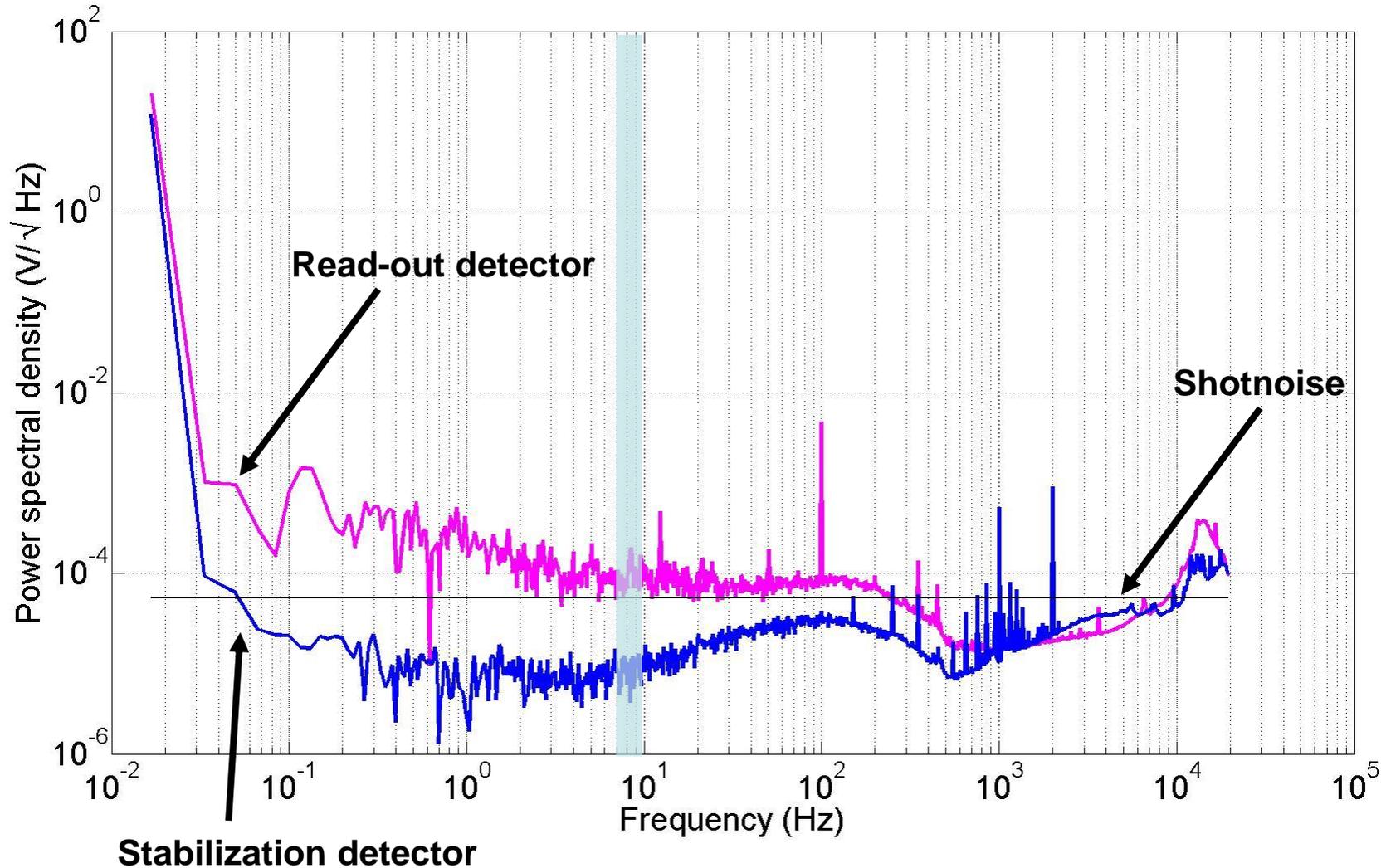


# Position- and Power-stabilization

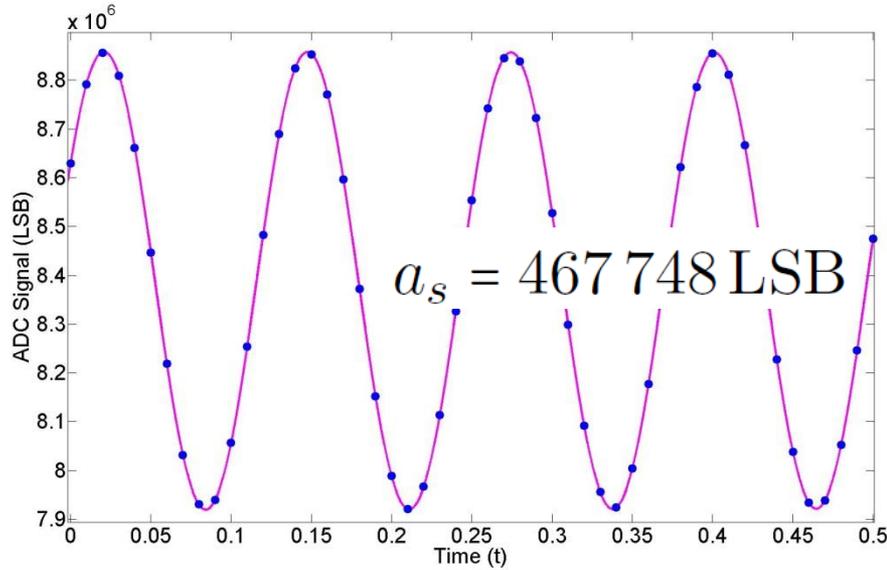




# Position- and Power-stabilization



# Performance



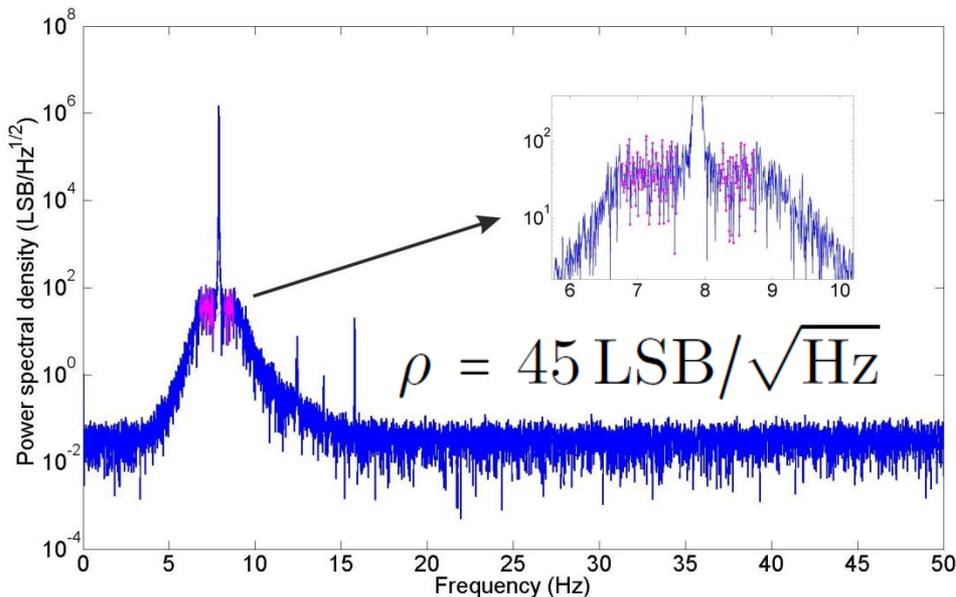
→ SNDR of  $10\,405 \sqrt{\text{Hz}}$

**Cramer-Rao-Lower bound:**

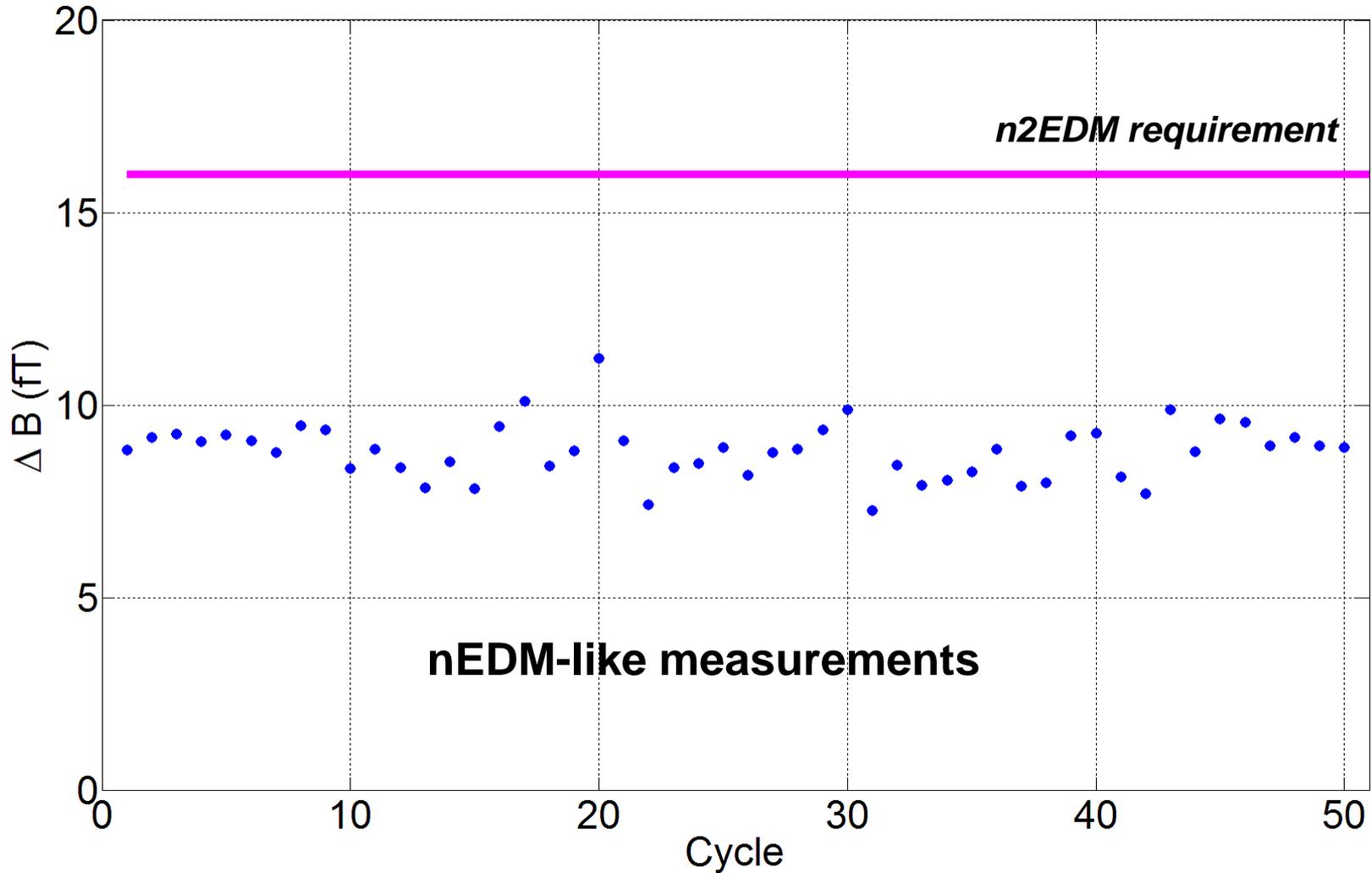
$$\delta B \geq \frac{\sqrt{12}}{\gamma \frac{a_s}{\rho} T^{3/2}} C(r)$$

$$C(r) = \sqrt{\frac{e^{2/r} - 1}{3r^3 (\cosh(2/r) - 1) - 6r}}$$

→  $\delta B = 7.5 \text{ fT}$



# Performance



# Conclusion



- $$d_n = \frac{1}{2E} \left( h \left( f_n^{\uparrow\uparrow} - f_n^{\uparrow\downarrow} \right) + \mu_n \left( B^{\uparrow\uparrow} - B^{\uparrow\downarrow} \right) \right)$$
- Very good performance of the Hg magnetometer in the nEDM experiment :  
99.9% of all nEDM cycles recorded, induced statistical error 2.88% (goal <5%)
- Laser-based Hg magnetometer realized exceeding the performance requirements of n2EDM  
Magnetometric resolution a factor 2 better (shown: 8fT, goal:<16fT)

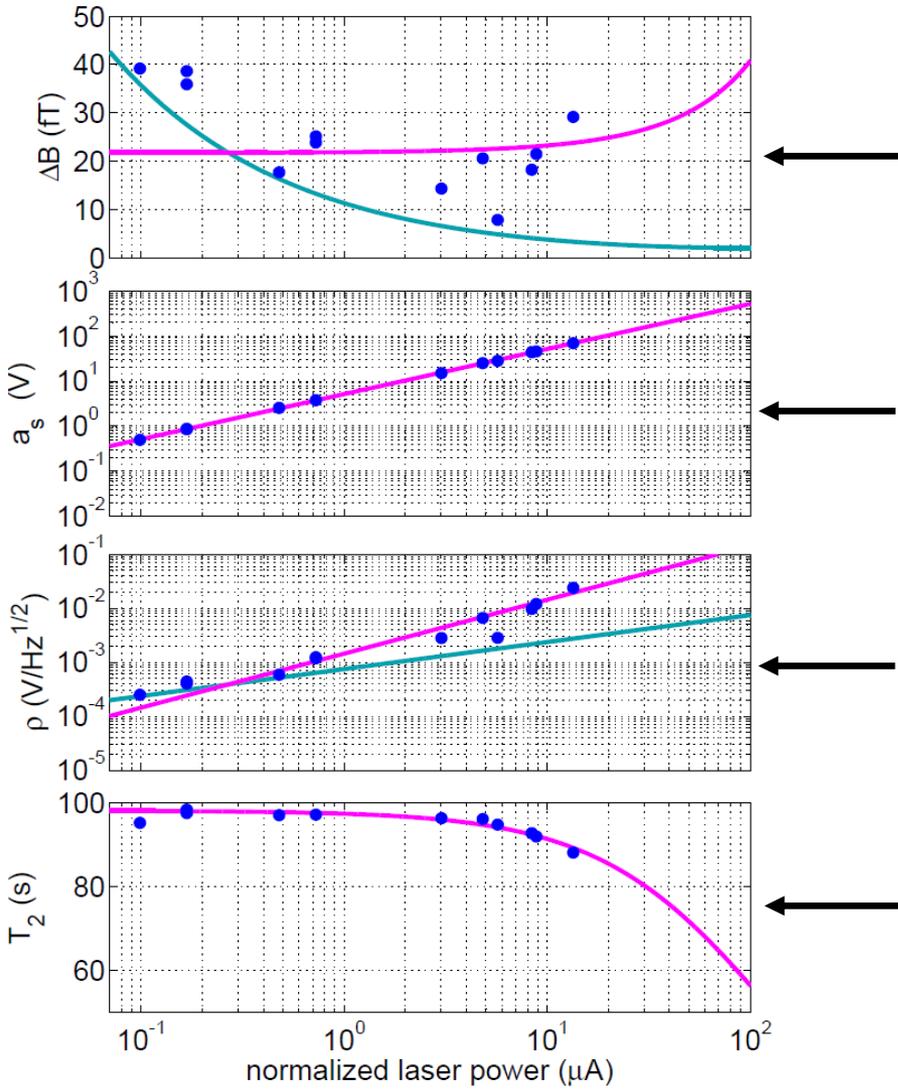
# Thank You!



*and  
the nEDM collaboration*



# Laser power optimization



Magnetometric resolution calculated with Cramer-Rao Lower Bound

Amplitude

Noise density (Shot noise and technical noise)

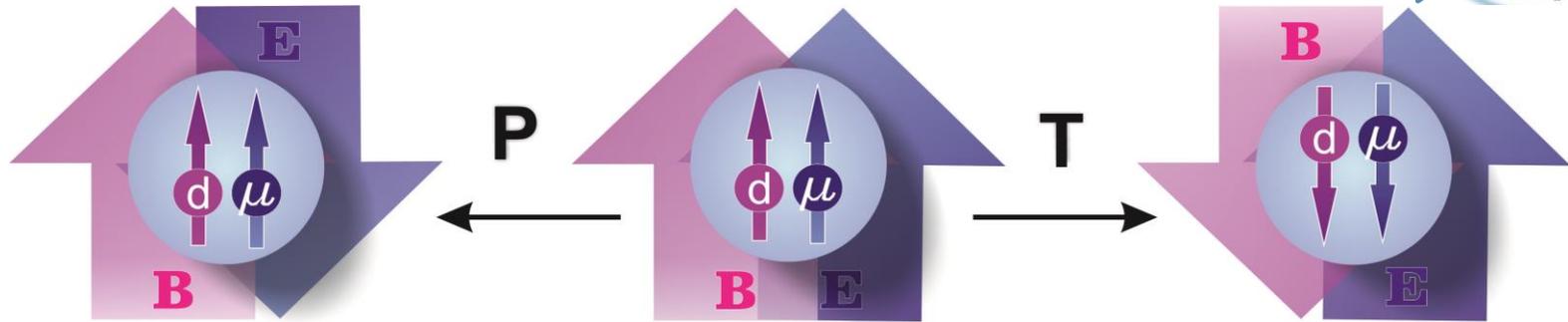
Depolarisation by light:

$$T_2 = \frac{1}{\frac{1}{T_i} + \frac{P}{L_P}}$$



# *Back Up*

# CP violation and nEDM

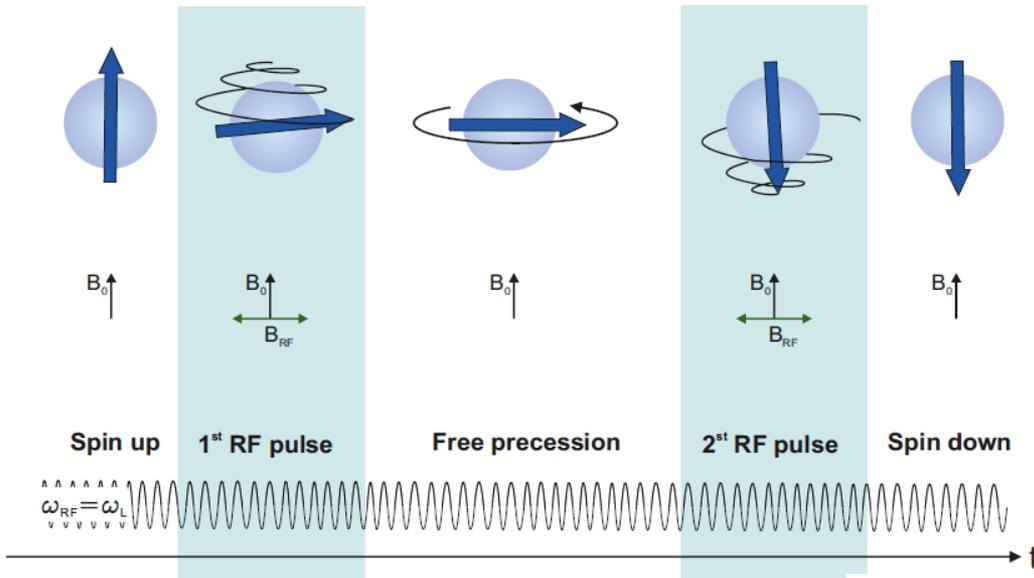


$$\mathcal{H} = -d \frac{\vec{s}}{|\vec{s}|} \vec{E} - \mu \frac{\vec{s}}{|\vec{s}|} \vec{B}$$

$$\hat{P}\mathcal{H} = -d \frac{\vec{s}}{|\vec{s}|} (-\vec{E}) - \mu \frac{\vec{s}}{|\vec{s}|} \vec{B} \neq \mathcal{H}$$

$$\hat{T}\mathcal{H} = -d \frac{-\vec{s}}{|\vec{s}|} \vec{E} - \mu \frac{-\vec{s}}{|\vec{s}|} (-\vec{B}) \neq \mathcal{H}$$

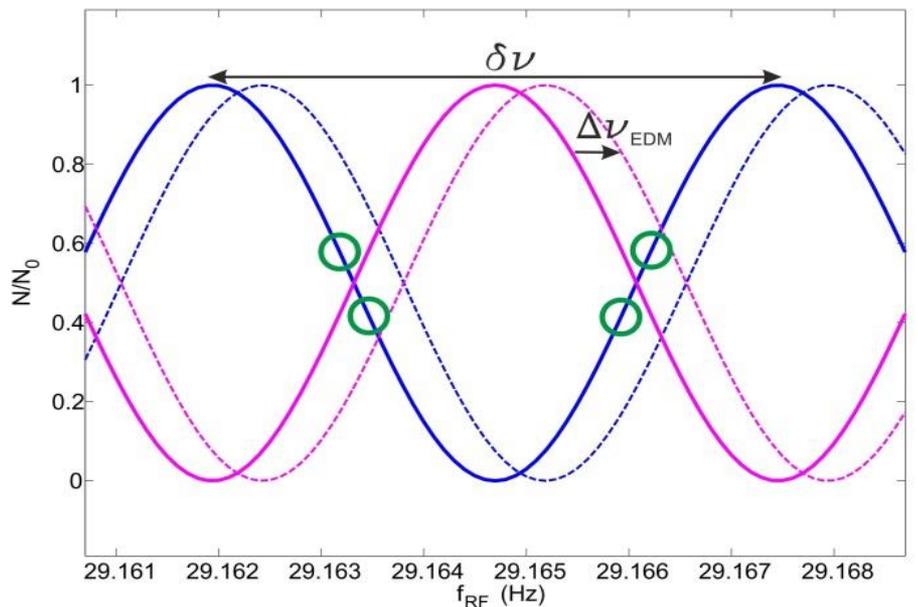
# How to measure the nEDM?



$$N_{\uparrow}(\Delta\nu) = \frac{N_0}{2} \left[ 1 - \alpha \cos \left( \frac{2\pi \Delta\nu}{\delta\nu} \right) \right]$$

$$\Delta\nu = \nu_{\text{rf}} - \nu_{\text{N}}$$

$$\delta\nu = \frac{1}{T_{\text{FP}} + \frac{4T_{\text{rf}}}{\pi}}$$

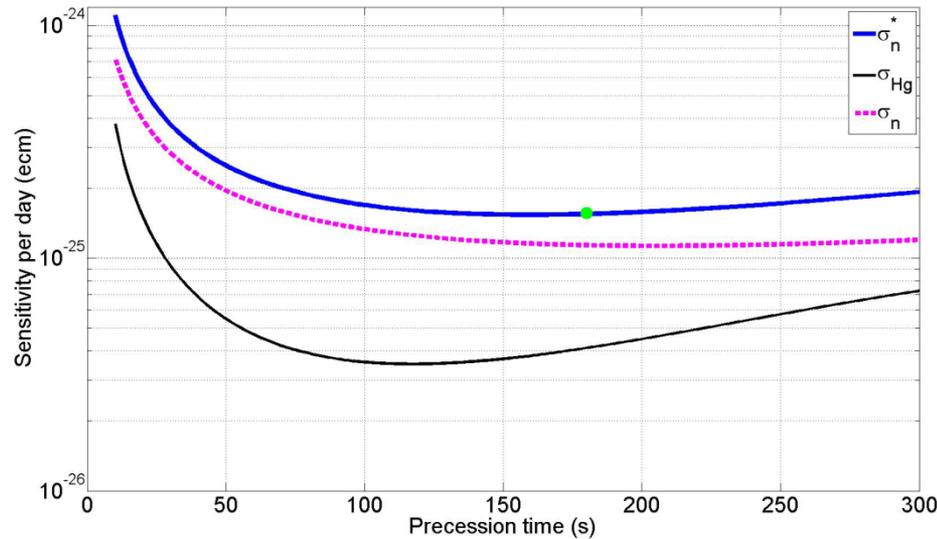


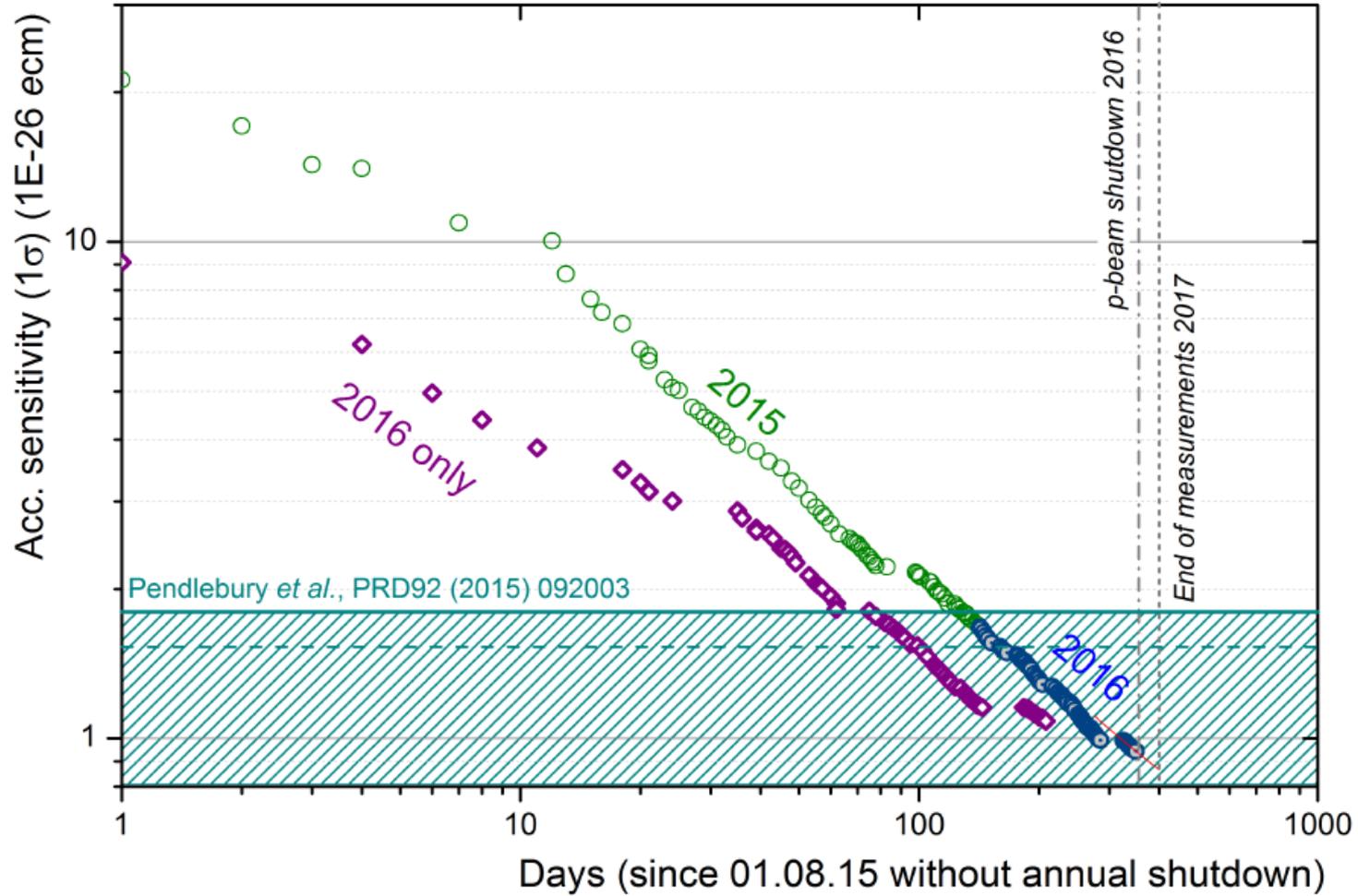
# Sensitivity



$$\sigma(d_n) = \frac{\hbar}{2\alpha ET_{FP} \sqrt{N_0}}$$

	d chamber (cm)	Coating	$\alpha$	$E$ (kV/cm)	$N$ UCN per cycle after 180s	$\sigma(d_n)$ (e·cm) per day	$\sigma(d_n)$ (e·cm) 500 data days
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$f_{\text{Hg}}$  VS  $f_{\text{n}}$ 

$$f_{\text{n}} = \frac{\gamma_{\text{n}} B}{2\pi} \approx 30 \text{ Hz @ } 1 \mu\text{T} \quad \tilde{v}_{\text{UCN}} \approx 4 \text{ m/s}$$

$$f_{\text{n}} = \gamma_{\text{n}} \langle |\vec{B}| \rangle_{\text{V}}$$

$$f_{\text{Hg}} = \frac{\gamma_{\text{Hg}} B}{2\pi} \approx 8 \text{ Hz @ } 1 \mu\text{T} \quad \tilde{v}_{\text{Hg}} \approx 170 \text{ m/s}$$

$$f_{\text{Hg}} = \gamma_{\text{Hg}} |\langle \vec{B} \rangle_{\text{V}}|.$$

$$R = \frac{f_{\text{n}}}{f_{\text{Hg}}} = \frac{\gamma_{\text{n}}}{\gamma_{\text{Hg}}} \left( 1 \mp \frac{h}{B_0} \frac{\partial B}{\partial z} + \frac{\langle B_T^2 \rangle}{2B_z^2} \pm \left( \frac{f_{\text{Earth}}}{f_{\text{n}}} + \frac{f_{\text{Earth}}}{f_{\text{Hg}}} \right) \sin(\lambda) \right)$$

**GPE:**

$$\delta f_{\text{L}} = \frac{\gamma^2 D^2}{32\pi c^2} \frac{\partial B_0}{\partial z} E \quad (\text{non adiabatic})$$

$$\delta f_{\text{L}} = \frac{v_{xy}^2}{4\pi B_0^2 c^2} \frac{\partial B_0}{\partial z} E \quad (\text{adiabatic}),$$

# GPE for higher orders



General expression valid for any field distribution and volume geometry:

*Pignol, G. ; Roccia, S. Phys. Rev. A 85 (2012)*

$$d_{\text{false}} = \frac{\hbar\pi}{E} \Delta f(E) = \frac{\gamma^2 \hbar\pi}{2c^2} \langle xB_x + yB_y \rangle$$

Magnetic field parametrization:  $\vec{B}(\vec{r}) = \sum_{l,m} G_{l,m} \begin{pmatrix} \Pi_{x,l,m}(\vec{r}) \\ \Pi_{y,l,m}(\vec{r}) \\ \Pi_{z,l,m}(\vec{r}) \end{pmatrix}$  ↙ Harmonic polynomials in x,y,z of degree l

$l$	$m$	$\langle xB_x + yB_y \rangle$	$G_{\text{max}} (5 \cdot 10^{-27} \text{ e}\cdot\text{cm})$
1	0	$-\frac{1}{4}r^2 G$	0.57 pT/cm
3	0	$\frac{1}{16}r^2(2r^2 - H^2)G$	$2.4 \cdot 10^{-3} \text{ pT/cm}^3$
5	0	$-\frac{1}{10^9}r^2(15r^4 + 3H^4 - 20H^2r^2)G$	$8.92 \cdot 10^{-6} \text{ pT/cm}^5$

nEDM geometry: H=12cm , r=23.5cm