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SwissFEL RF BPMs: Status & Plans

SwissFEL Performance Workshop, 27.1.2021

- Hardware & Quantities
- Performance & Beam Measurements
- Summary

BPM Pickup Quantities Today

Pickups installed,
BPM electronics in
production, to be
installed 2-3/2021

BPM Type	Aper- ture [mm]	Quality Factor Q_L	Freq. [GHz]	ADCs per BPM	# Gun - Aramis	# Athos Branch Used	Athos Branch Unused
BPM-C38	38	28	3.3	6	6	0	0
BPM-C16	16				89	27	0
BPM-C8	8	1000	4.9	3	24	6	4
BPM-C5	5				0	22	0
Overall	-	-	-	-	119	55	4

BPM-C5/-C8 (high-Q, 4.9 GHz) in/near undulators

- Higher resolution, but can only measure **1 bunch**
- Electronics: "MBU" (similar to E-XFEL) or "DBPM3" (=SLS2 platform)

93% of Athos Branch BPMs
available & commissioned

BPM-C16/-C38 (low-Q 3.3 GHz) in transfer line, collimators & dump

- **28ns dual-bunch** operation
- Electronics: "MBU" (similar to E-XFEL)

DBPM3 maybe for PORTHOS? Would
need new RFFE/ADC design

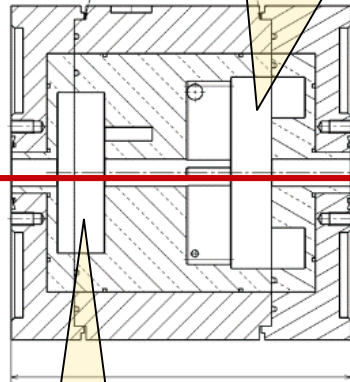
DBPM5 Pickup: Hybrid Copper/Steel Body

DBPM5: 1 reference resonator port (signal ~ charge)

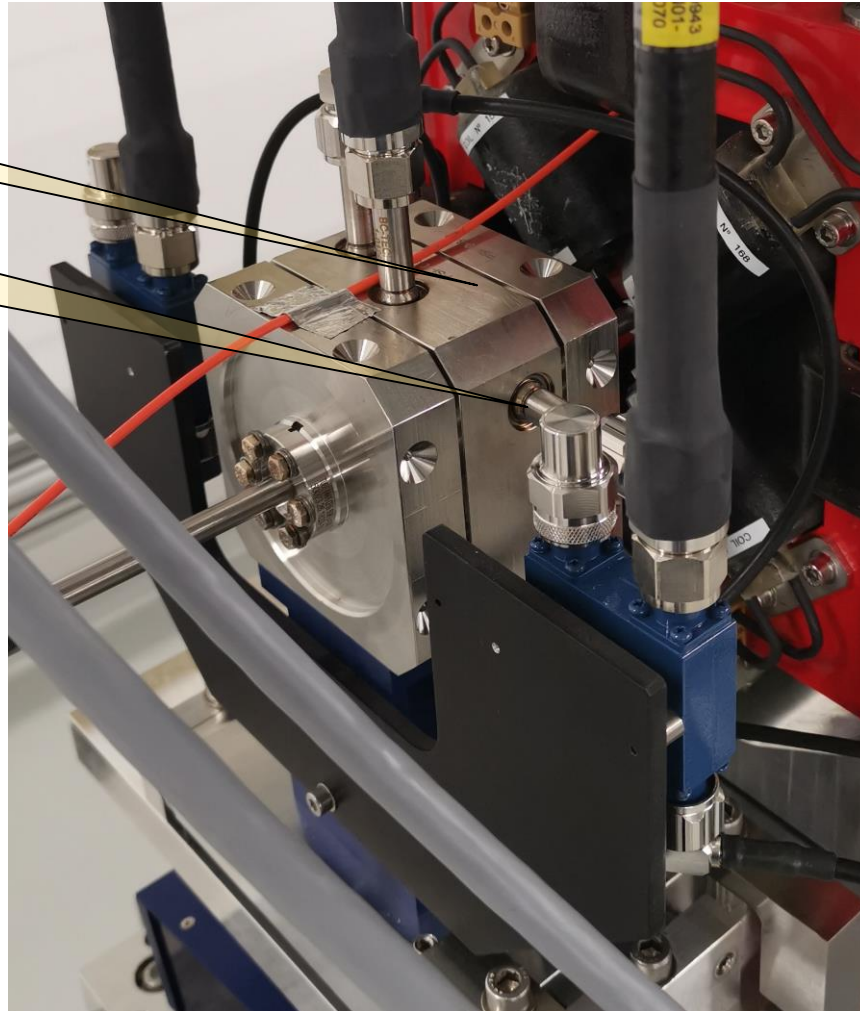
1 of 4 position resonator ports (signal ~ beam position * charge)

DBPM8: position resonator (similar to CBPM5 ...)

beam



reference resonator



SwissFEL BPM Electronics Types

GFA/AEK in-house designs

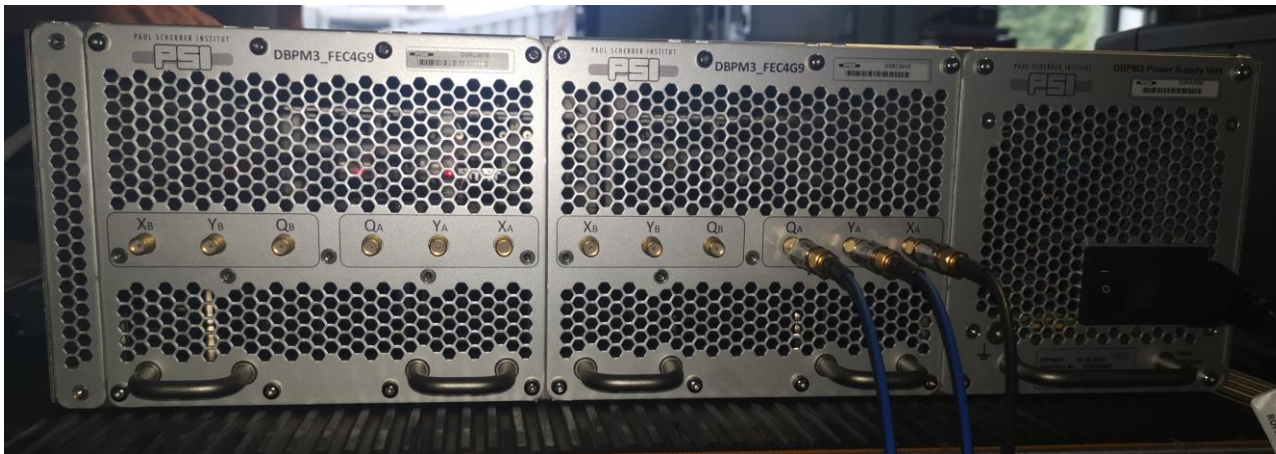
"MBU": Old BPM electronics platform developed for E-XFEL/SwissFEL ~10 years ago (VME-based, complex HW production)

"DBPM3": New PSI BPM electronics platform (SLS2, HIPA BPM upgrade, ...)

- **Athos undulator BPMs**: ~2.5x cheaper than MBU (by using newer technologies)
- Much easier production & testing
- Similar analog but much better digital performance
- **EPICS IOC & timing interface integrated** into BPM electronics (FPGA, 2-core & 4-core CPU on same chip: **Xilinx Zynq UltraScale+**)

New SwissFEL 4.9 GHz DBPM₃ Electronics

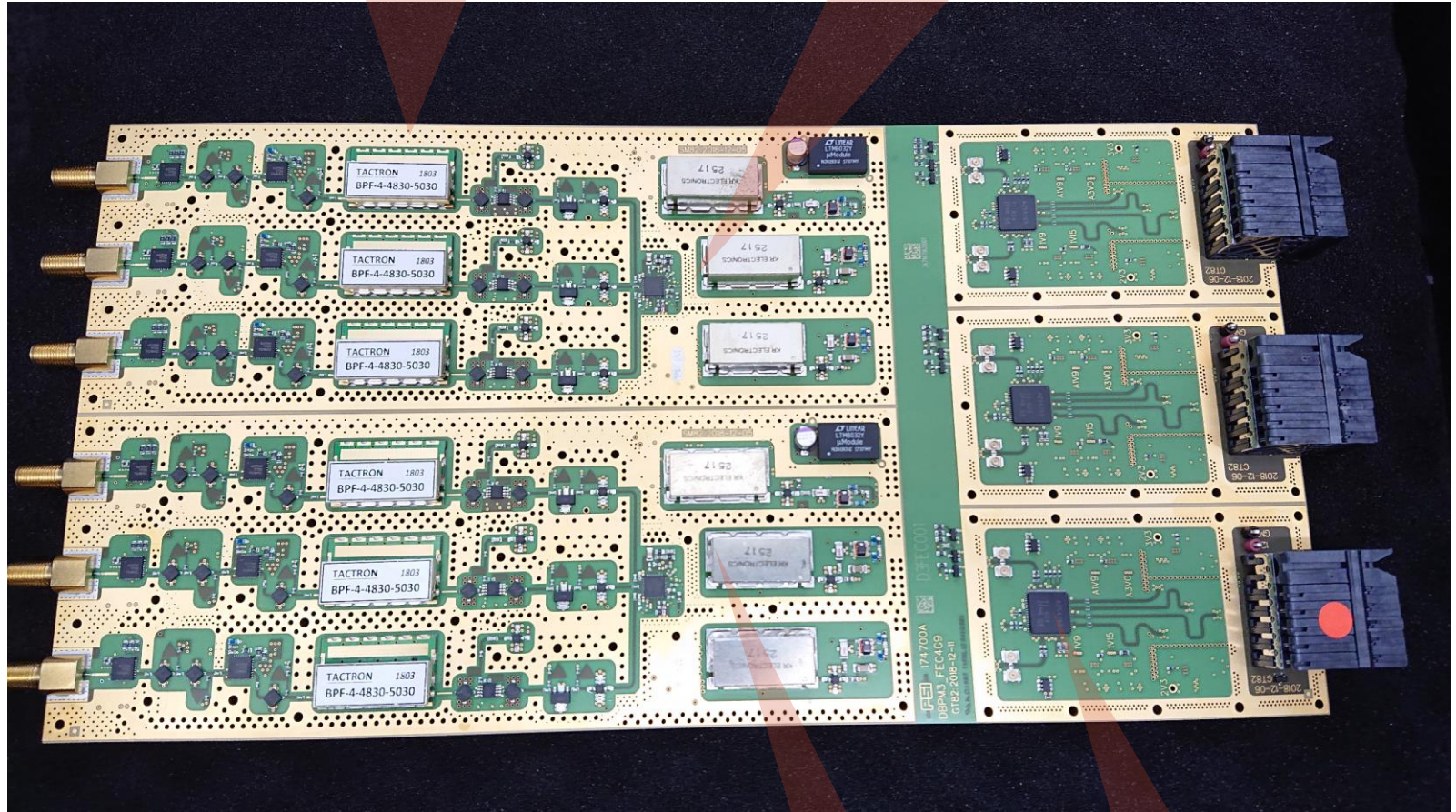
- Four 4.9 GHz High-Q Cavity BPMs per 3 HE Unit
- 500 MSample/s 16-Bit ADCs, 10Gbps serial data (old BPMs: 160 MSample/s, parallel data)
- Back-end same as SLS2 BPMs



New SwissFEL 4.9 GHz DBPM₃ Electronics

Top side: RF shields not yet mounted

3-Channel RF front-end, 1st cavity BPM



3-Channel RF
front-end, 2nd
cavity BPM

2-channel 16-bit
500MSPS ADC
(JESD204B)

Today:

- Aramis:
 - MBUs
- Athos:
 - High-Q BPMs: 13 DBPM3, 15 MBU (= Aramis spares)
 - Low-Q BPMs: MBU

4-5/2021:

- Athos High-Q BPMs use only DBPM3

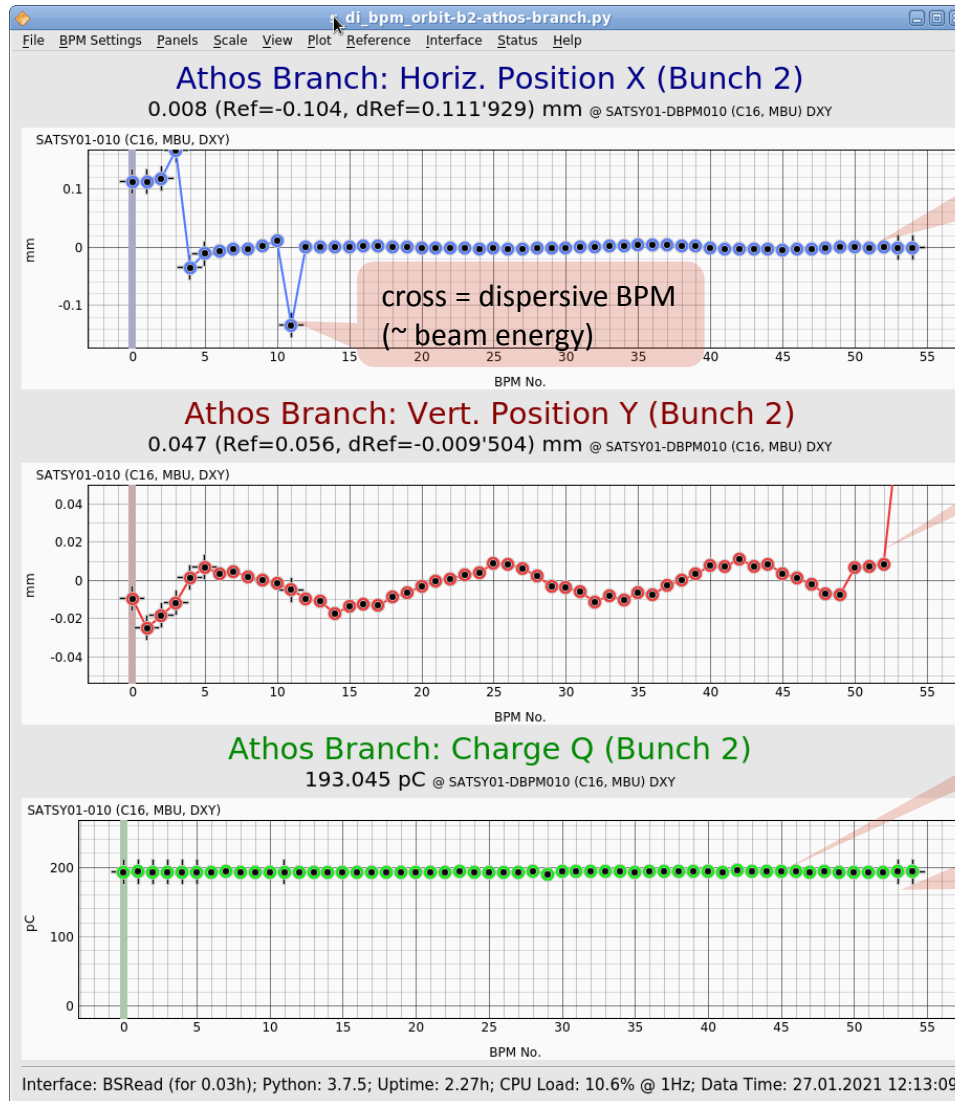
End 2021:

- Aramis high-Q BPMs also upgraded to DBPM3 (-> old high-Q BPM electronics used/needed as long-term spares for low-Q BPMs, except RFFEs)
- **Replace VME-based BPM IOCs (IFC1210) with** more performant integrated IOCs for all BPMs (**Zynq Ultrascale+**) -> enable **100 Hz plus easier maintenance & necessary future upgrades** of EPICS database (2-bunch calibration, automatic alarms, PORTHOS, ...)

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BPM Noise and Crosstalk



DBPM3 electronics position noise
~0.4 μ m RMS @ 100-200 μ m beam
offset (value may include real beam
motion -> may be even better) @
170pC.

Real beam motion
typically (much) larger
than BPM noise

DBPM3 charge
noise <0.04%
(<70fC) @ 170pC

Low-Q BPMs: Bunch-to-bunch
crosstalk (measurement error of
2nd bunch due to
presence/absence of 1st bunch)
of charge measurement typ. <
1% @ 170pC (measured at
SINEG01-DBPM340)

(Some) BPM Activities & Improvements 2020

EPICS IFC1210 IOCs for BPMs now work at 100 Hz (incl. BSRead):

- Temporary solution: Standard EPICS controls software replaced by BPM specific optimized software, more performant but hard(er) to maintain.
- Final solution (WIP): IFC1210 VME IOCs will be replaced with ZynqU+ IOCs (new SLS2 standard) -> ~10x more IOC performance per BPM.

X/Y position scaling factors calibrated with beam (conversion of ADC units to mm):

Calibration script should only be used by BPM experts (or in agreement with them ...)

- Calibrated for all Aramis & Athos BPMs on motorized movers (for Athos fully automated, including check if results are reasonable)
- Reproducibility over several weeks/months typ. ~1% (resolution of calibration limited by beam motion/noise, using 100x averaging & several measurement steps per BPM)

```
sf-lc7a ~/git/sf_diagnostics_scripts > s_di_bpm_cmd.py "cal_xy_scaling_satun auto SATUN01-DBPM070 SATUN02-DBPM070 SATUN03-DBPM070"
# Executing command cal_xy_scaling_satun_auto SATUN01-DBPM070 SATUN02-DBPM070 SATUN03-DBPM070 for accelerator all ...
Calibration X/Y position scaling factors for BPMs ['SATUN01-DBPM070', 'SATUN02-DBPM070', 'SATUN03-DBPM070']
# SATUN01-DBPM070:X-SCALE-CORR 0.811
# SATUN01-DBPM070:X-SCALE-CORR 0.816
# SATUN01-DBPM070:X-SCALE-CORR 0.808
# SATUN01-DBPM070:X-SCALE-CORR 0.822
# SATUN01-DBPM070:X-SCALE-CORR [0.8106, 0.8158, 0.8081, 0.8215]
# Average = 0.814
# Peak-Peak = 0.0134
# Median = 0.8132
# RMS = 0.0059
# -> Scaling factor is **NOT** O.K. (outside 2 sigma of this measurement).
Changed SATUN01-DBPM070:X-SCALE from 6.300 to 5.128 (factor = 0.814 +- 0.003406, values = [0.8106, 0.8158, 0.8081, 0.8215])

# SATUN01-DBPM070:Y-SCALE-CORR 0.954
# SATUN01-DBPM070:Y-SCALE-CORR 0.934
# SATUN01-DBPM070:Y-SCALE-CORR 0.946
Warning: Permanently added 'sf-lca,172.26.120.57' (RSA) to the list of known hosts.
# SATUN01-DBPM070:Y-SCALE-CORR 0.931
# SATUN01-DBPM070:Y-SCALE-CORR [0.9536, 0.9337, 0.9457, 0.931]
# Average = 0.941
# Peak-Peak = 0.0226
# Median = 0.9397
# RMS = 0.0106
# -> Scaling factor is **NOT** O.K. (outside 2 sigma of this measurement).
Changed SATUN01-DBPM070:Y-SCALE from 6.300 to 5.928 (factor = 0.941 +- 0.006120, values = [0.9536, 0.9337, 0.9457, 0.931])
```

0.34% error

0.61% error

X/Y Scaling Factor Calibration

December 2020, SATUN08-DBPM070: X position scaling factor changed by ~5% because beam offset was 0.8mm -> RFFE attenuator had non-standard value.

5% scaling factor change means:

- 50µm orbit offset change for 1mm beam offset (!)
- 5µm for 0.1mm beam offset

```
# SATUN08-DBPM070:X-SCALE-CORR 1.008
# SATUN08-DBPM070:X-SCALE-CORR 1.093
# SATUN08-DBPM070:X-SCALE-CORR 1.061
# SATUN08-DBPM070:X-SCALE-CORR 1.049
# SATUN08-DBPM070:X-SCALE-CORR [1.0078, 1.0927, 1.0614, 1.0486]
#   Average   = 1.0526
#   Peak-Peak = 0.0849
#   Median    = 1.055
#   RMS       = 0.0352
# -> Scaling factor is **NOT** O.K. (outside 2 sigma of this measurement).
Changed SATUN08-DBPM070:X-SCALE from 7.100 to 7.473 (factor = 1.053 +- 0.020323, values = [1.0078, 1.0927, 1.0614, 1.0486])

# SATUN08-DBPM070:Y-SCALE-CORR 0.983
# SATUN08-DBPM070:Y-SCALE-CORR 0.992
# SATUN08-DBPM070:Y-SCALE-CORR 0.989
# SATUN08-DBPM070:Y-SCALE-CORR 1.003
# SATUN08-DBPM070:Y-SCALE-CORR [0.9834, 0.992, 0.9894, 1.0032]
#   Average   = 0.992
#   Peak-Peak = 0.0198
#   Median    = 0.9907
#   RMS       = 0.0083
# -> Scaling factor is O.K. (within 2 sigma of this measurement).
Not changing SATUN08-DBPM070:Y-SCALE from 6.967 to 6.911 (factor = 0.992 +- 0.004792, values = [0.9834, 0.992, 0.9894, 1.0032])

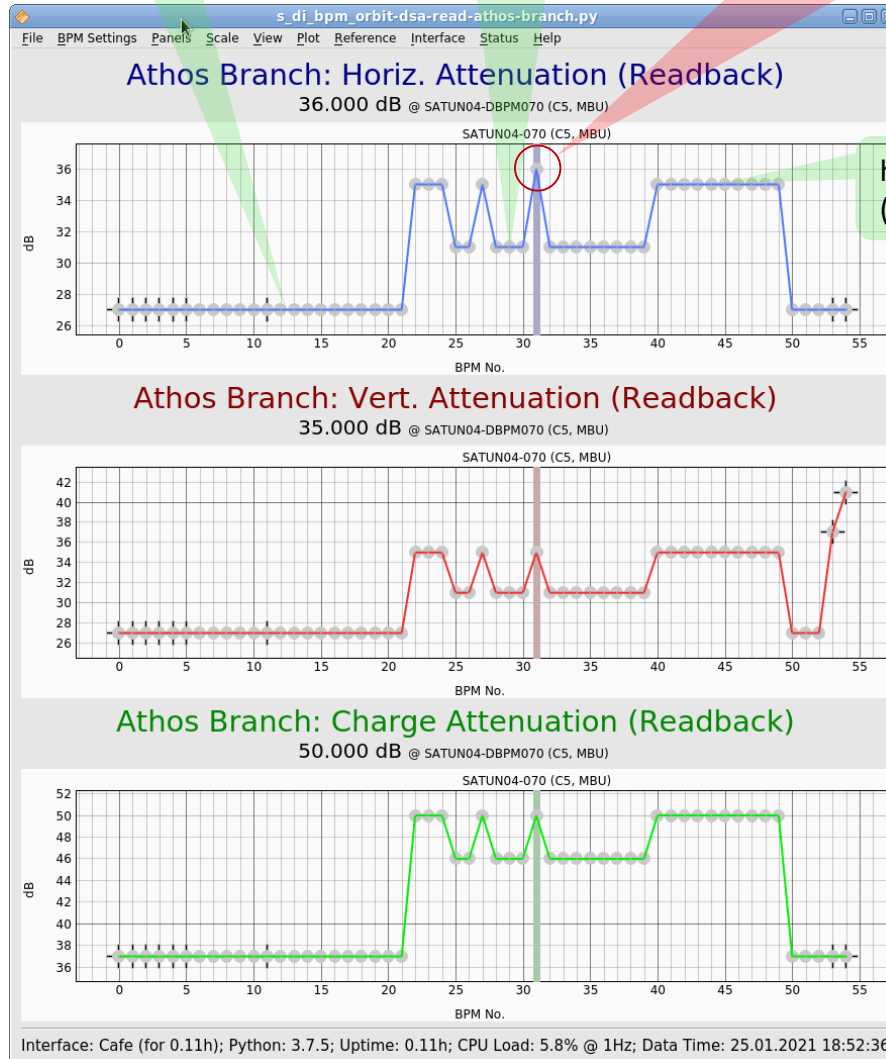
# SATUN09-DBPM070:X-SCALE-CORR 1.004
# SATUN09-DBPM070:X-SCALE-CORR 1.012
# SATUN09-DBPM070:X-SCALE-CORR 1.015
```


BPM Attenuator Settings

low-Q
BPMs: 27dB

high-Q BPMs
(DBPM3): 31dB

One high-Q BPM (MBU): 36dB
= non-standard (X beam
position "too large")



high-Q BPMs
(MBU): 35dB

At ~ 170 pC, each BPM type has a **reproducible standard RFFE attenuator** setting (and thus position and charge scaling factor) **as long as beam offset is < 0.4 mm.**

If beam offsets gets much larger, **automatic gain control of BPM FPGAs increases attenuation to avoid ADC saturation.**

BPM Performance Depends on Orbit

- BPMs have digital step attenuators, 63dB range, 1dB steps. Reality: Steps not exactly 1 dB, vary from BPM to BPM & from step to step.
- **Lab: All 63 attenuator settings per channel (X,Y,Q) (pre-)calibrated**, but calibration not perfect (cannot reproduce beam conditions in lab perfectly).
- **Beam: So far only one "standard" attenuator setting calibrated with beam** (Athos: ~15 min/BPM @ 10 Hz, automated)
- Automatic attenuation control on FPGA level: Non-standard attenuation when beam offset gets $\gg 0.4\text{mm}$ to avoid ADC saturation.
 - **Short term solution: Keep undulator beam positions $< 0.4\text{mm}$. Center the orbit symmetrically around 0mm ($\pm 0.4\text{mm}$ is better than $0 \dots +0.8\text{mm}$)**
 - **Medium/long-term solution: Calibrate more attenuator settings with beam**, speed up calibration procedure (and Athos rep rate ...), improve lab-based calibration.
- Noise and drift of BPMs also increase (\sim linearly) with beam offsets $\rightarrow \pm 0.4\text{mm}$ standard measurement range in undulators seems reasonable, could be increased at expense of more noise.

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Summary & Outlook

Special thanks to AEK for making this possible (despite loss of key personnel), and for delivering first SLS2 DBPM3 prototype (based on Athos DBPM3).

Status:

- New DBPM3 electronics: Performance O.K. (analog + digital). Number of software/firmware errors found and fixed so far comparably low, considering the system is complex & many components/technologies are very new.
- In a few weeks, all Athos BPMs will have BPM electronics (presently only four *least critical* BPMs still have no electronics - installation order agreed on with R. Ganter et al.)

Plans 2021+

- Finish DBPM3 series production (last HW expected 3/2021)
- Replace all high-Q BPM electronics with DBPM3 until end 2021 (incl. Aramis)
- Replace IFC1210 BPM IOCs with Zynq UltraScale+ IOCs (prototype 2021, series 2022)
- Calibration of position scaling factors for BPMs without movers & for non-standard attenuation (AEK-BD collaboration)
- Digital suppression of:
 - Bunch-bunch crosstalk (so far ~1%, except few pre-series RFFEes, to be replaced with series)
 - Nonlinearities of cavity resonators etc. (causing systematic measurement errors at large beam offsets)
- Long-term drift studies, better/automated lab & beam calibration & fault detection software

**Thank you for your
attention!**

**Thanks to all PSI
groups contributing to
the BPM system!**

Questions?

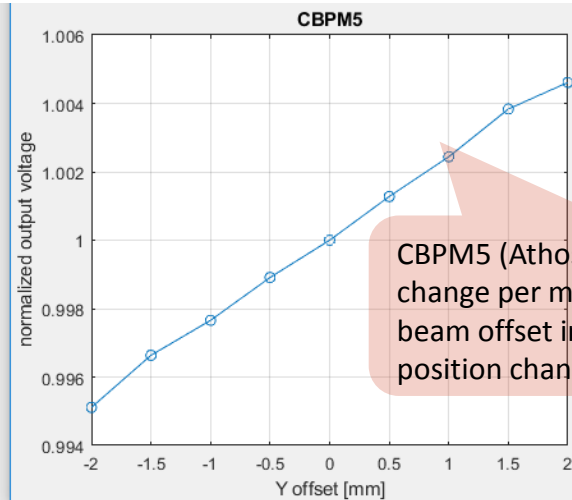
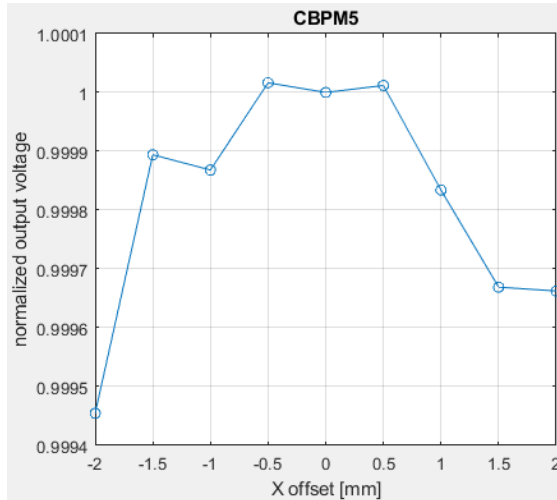


Backup Slides

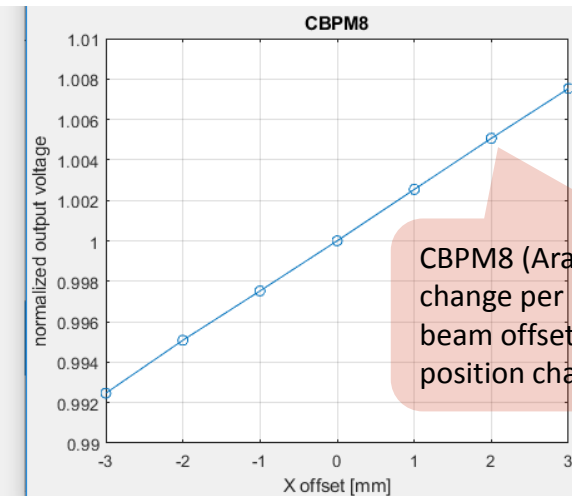
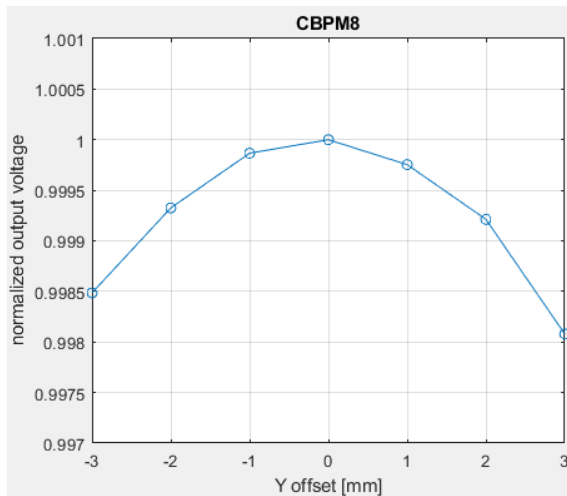


Position Dependence of Charge Reading

Reason: Cavity resonator that measures charge has only one RF coupler (CBPM5: at top, CBPM8: at side) -> asymmetric RF field.



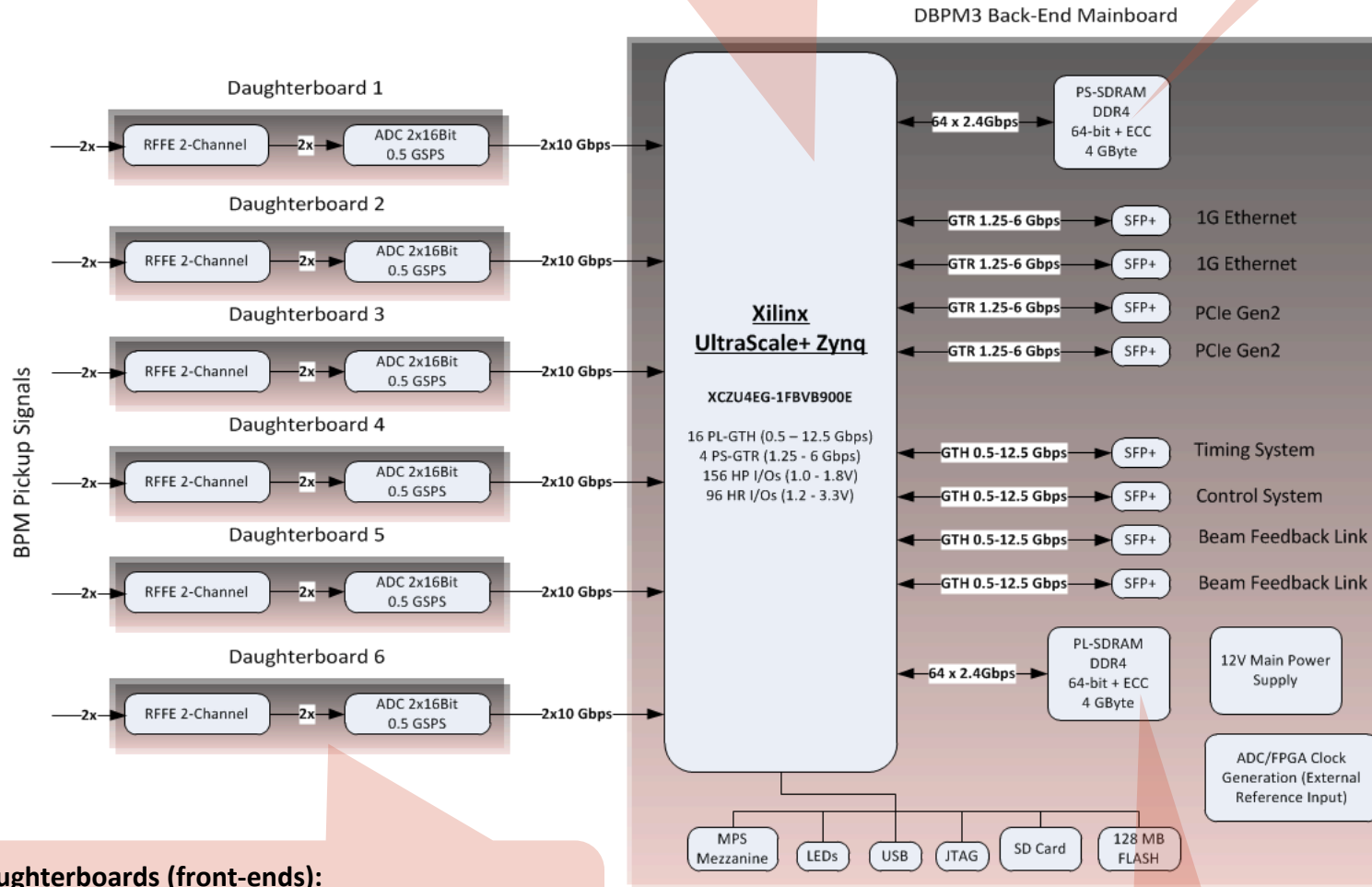
CBPM5 (Athos): 0.24% charge signal change per mm (only in Y) -> +1mm beam offset in Y+X causes +2.4 μ m position change in X



CBPM8 (Aramis): 0.25% charge signal change per mm (only in X) -> +1mm beam offset in Y+X causes +2.5 μ m position change in Y

System-on-Chip (SoC): BPM/feedback data processing (FPGA + real-time CPU), EPICS/Linux (2nd CPU), timing system interface.

RAM for Linux/EPICS



Daughterboards (front-ends):

- 6x single-width (feedback network switch)
- or 3x double width (SLS button BPM)
- or **2x triple-width (SwissFEL cavity BPM)**

RAM for measurement /
ADC raw data

DBPM₃: Xilinx Zynq UltraScale+ SoC

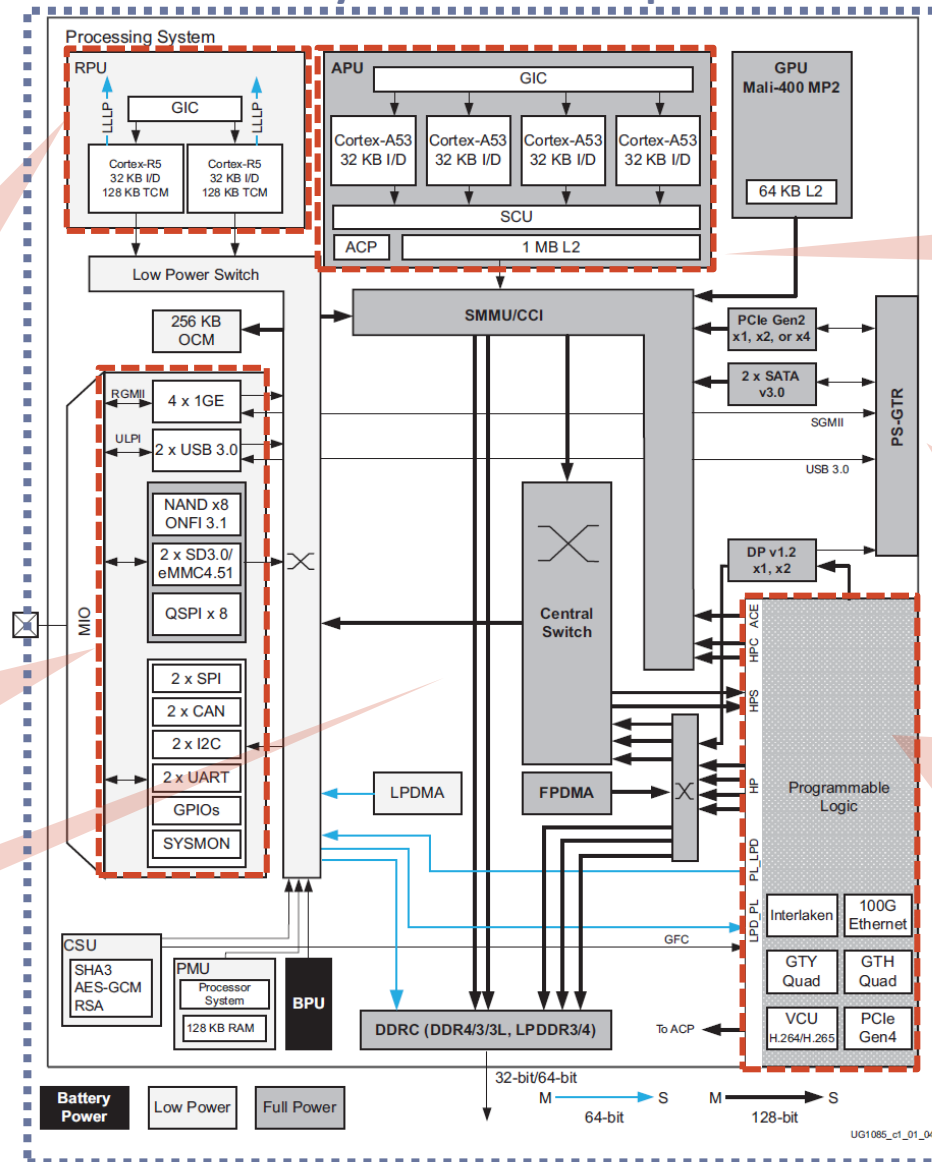
System-on-a-Chip



RPU: Realtime processor
for FOFB algorithm, BPM
control & data
processing, ...

Standard Interfaces
(USB, EEPROM,
FLASH memory, ...)

Flexible on-chip
data/address "bus"
(switch) system

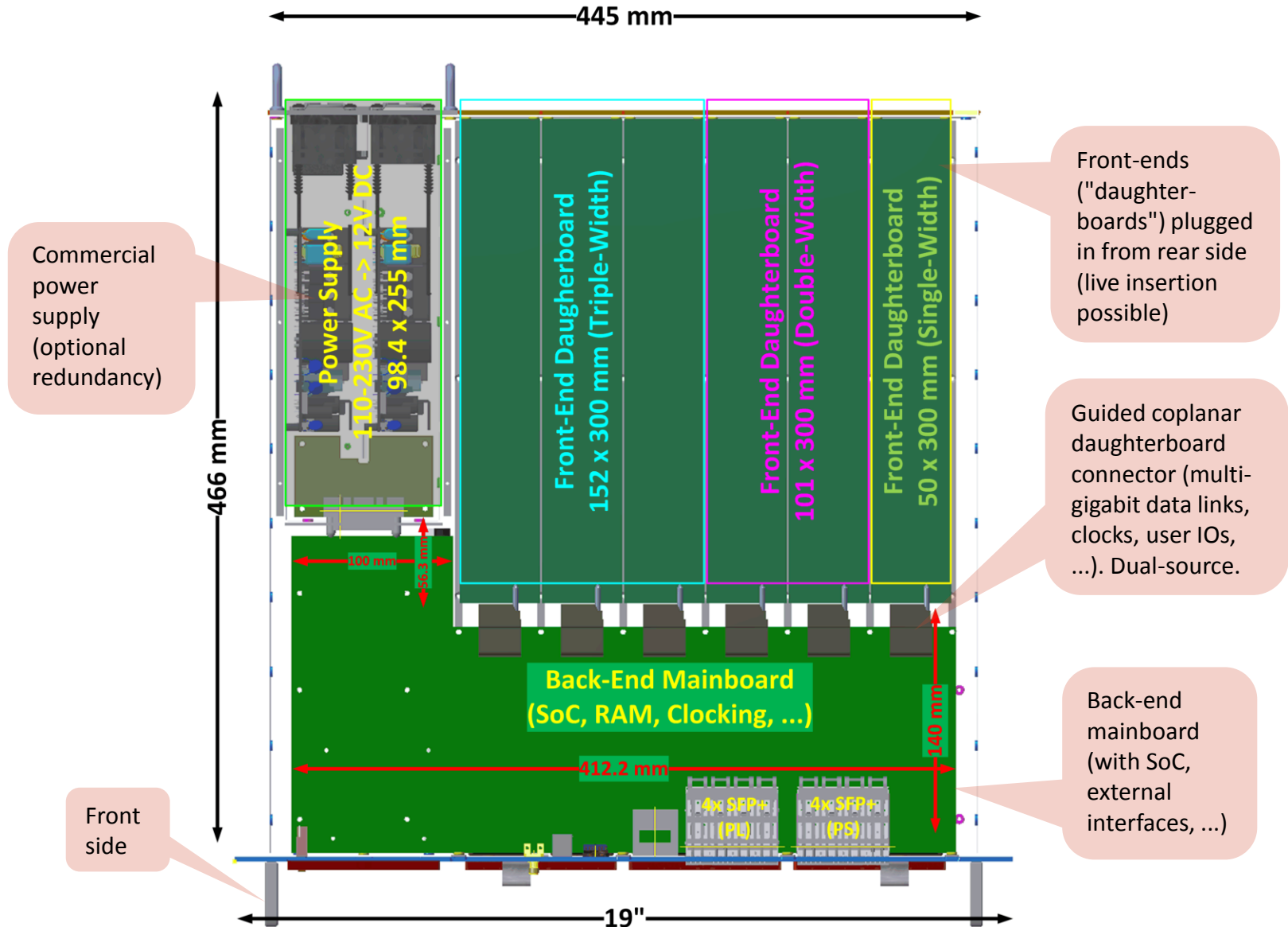


**APU: Processor for
Linux with EPICS IOC**

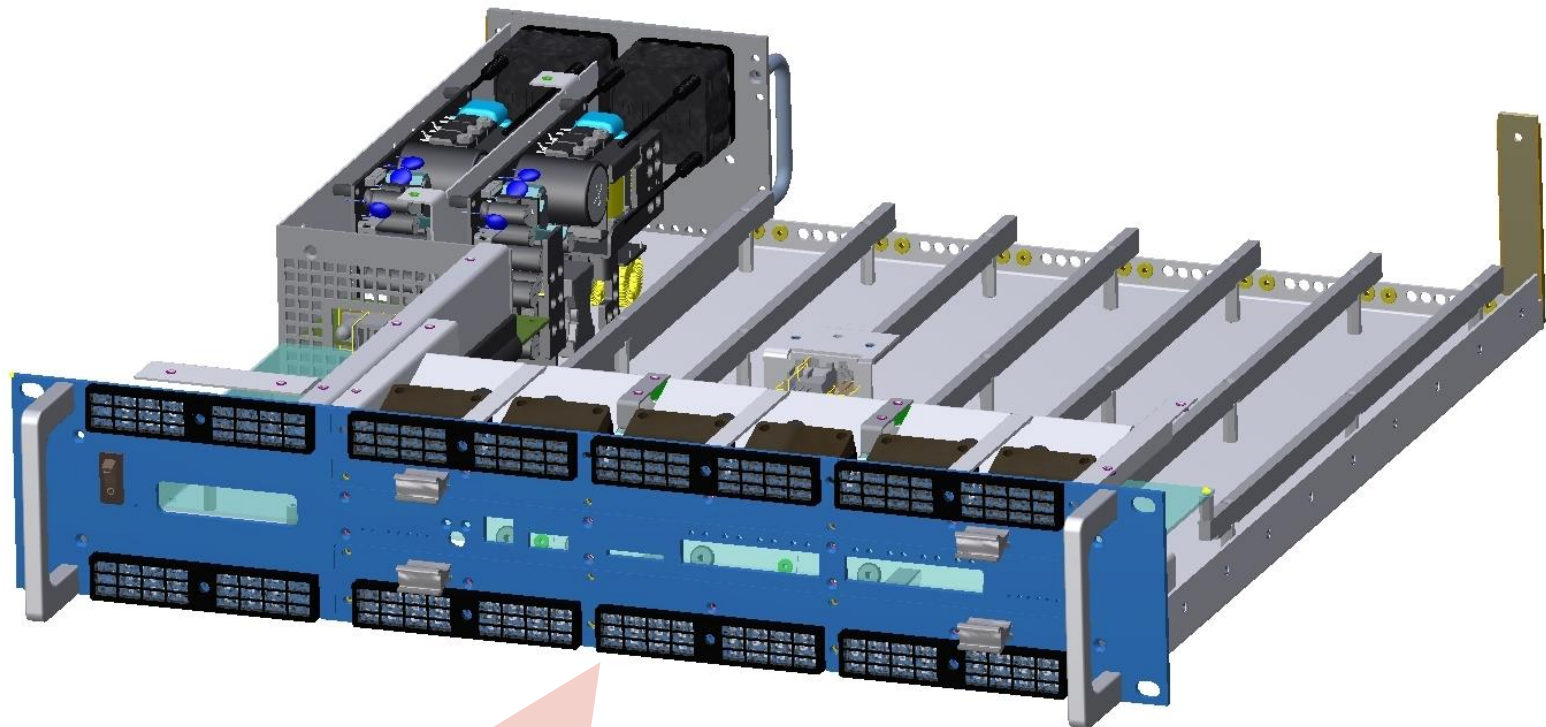
Multi-gigabit
interfaces (PCIe,
Ethernet, ...)

FPGA (logic elements
with programmable
interconnect, ...) for
digital downconversion
of ADC raw data,
timing system
interface, feedback
interface, ...

DBPM₃ System: 19" Unit



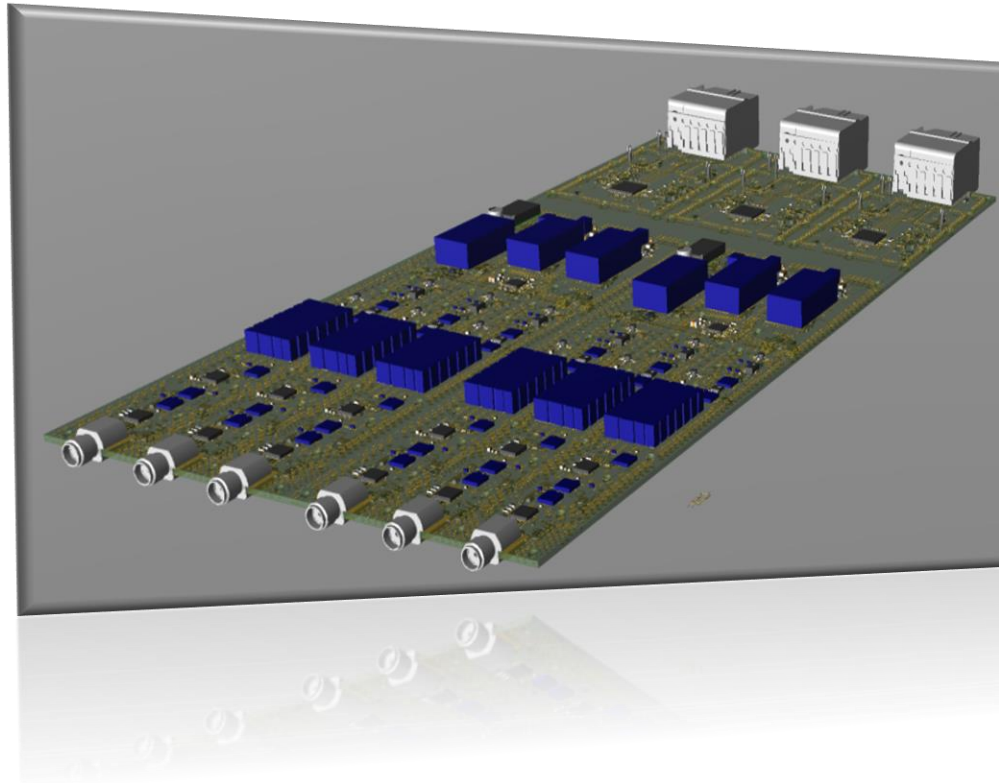
DBPM₃ System



Air flow/ventilation optimized for high temperature stability & low BPM drift (suboptimal in VME-based solutions).

DBPM₃: Athos High-Q RFFE/ADC

- One DBPM3 unit handles 4 SwissFEL high-Q cavity BPMs (2 RFFEs per unit, 2 BPMs / 6 channels per RFFE).
- 500 MSPS 16-Bit ADCs (JESD204B, 10Gsps per link)
- Multi-gigabit connectors to DBPM3 FPGA board
- Design (M. Stadler / M. Gloor)



DBPM₃ Quantities & Applications

Application	#DBPM3 Units*	BPMs or SFPs per Unit**	Needed in Year	Development Status
SwissFEL High-Q BPMs	24	4	2019	Advanced
SLS1 RF BPM	76	3	2020+	WIP
SLS1 Fast Orbit Feedb.	18	16	2020+	WIP
SLS2 RF BPM	31	3	2024	WIP
SLS2 Fast Orbit Feedb.	27	16	2024	Concept
HIP A RF BPM	20	3	2025+	Concept
SLS2 Beam Loss Mon	2024	Idea
SLS2 Photon BPM	2024	Idea
HIP A Diagnostics	Idea
<u>Overall</u> ****	<u>196</u>			

* Incl. spares & prototypes

** Fast Orbit Feedback (FOFB) uses fiber optic tree network with SFP+ transceiver daughterboards.

*** Price incl. front-end electronics. Back-end price 4.45 kCHF / unit incl. VAT

**** Excluding applications with status "Idea"

Proposed DBPM₃ platform saves overall costs (personnel + material), reduces hardware complexity, improves performance and maintainability by using newer/different technology (compared to previous generations):

- Xilinx Zynq UltraScale+ System-on-Chip (SoC)
 - First SoC generation that combines BPM/feedback data processing (FPGA + real-time CPU) and *performant* EPICS/Linux CPU on a single chip.
 - Same SoC also proposed for other SLS2 systems -> high synergies.
 - Pin-compatible SoCs available with same CPU but different FPGA sizes -> minimize effort for control system integration & firmware/software tools
- Single 12V power supply (optional redundancy)
- Only gigabit serial data transfer (for ADCs, communication/interfaces, ...)
- Housing/fans optimized for low temperature drift (needed for extremely challenging SLS BPMs)
- Design driven by most challenging application (SLS BPM), but also took other possible applications into account (as far as possible without unreasonable increase of cost, effort, project delays, ...).

DBPM₃ Complexity

DBPM₃: Reduced hardware complexity

- Lower costs
- Lower design & maintenance effort (hardware, firmware, software/controls)
- Higher MTBF
- Production & test can be fully outsourced (not possible for previous BPM electronics), attractive for licensing/industrialization.

<u>BPM System</u>	<u>Extra Timing System VME Card Needed</u>	<u>Extra VME CPU card & crate for EPICS IOC Needed</u>	<u># Printed Circuit Boards per Button BPM</u>	<u># FPGAs per Button BPM</u>
Old SLS 1.0	yes	yes (1 per 6 BPMs)	10	2 + ASICs
SwissFEL Platform	no	yes (1 per 16 BPMs)	3.25	1.75
DBPM ₃ Platform	no	no	1.33	0.33